

Lecture 14 & 15: Edge Degree Constrained Subgraph

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1 Preliminary

Definition 1 (EDCS). For unweighted graph $G = (V, E)$, parameter $\beta \geq \beta^- \geq 0$, subgraph $H = (V, E_H)$ is an (β, β^-) -EDCS of G if:

- for $e \in H$, $w(e) \leq \beta$;
- for $e \notin H$, $w(e) \geq \beta^-$.

where $w(e) = \deg_H(u) + \deg_H(v)$ for $e = (u, v)$.

Lemma 1. For every graph G , an EDCS exists for $\beta \geq \beta^- + 1$.

Proof. Consider the following algorithm: We start with an arbitrary subgraph H , and iteratively fix a violated edge until no such edges.

Define the potential function

$$\Phi(H) = \left(\beta - \frac{1}{2}\right) \cdot \sum_{v \in V} \deg_H(v) - \sum_{e \in H} w(e).$$

Suppose edge $e \in E$ violates EDCS conditions:

- If $w(e) \geq \beta + 1$: $\Delta\Phi \geq \left(\beta - \frac{1}{2}\right) \cdot (-2) + (\beta - 1 + \beta + 1) \geq 1$;
- If $w(e) \leq \beta^- - 1 \leq \beta - 2$: $\Delta\Phi \geq \left(\beta - \frac{1}{2}\right) \cdot 2 - (\beta - 2 + \beta) \geq 1$.

Therefore, every fix would increase Φ by at least 1, the algorithm terminates in polynomial iterations since $|\Phi(H)| \leq \text{poly}(n, \beta)$ for every subgraph H . \square

2 Approximate Maximum Matching via EDCS [AB19]

For graph $G = (V, E)$, let $N_G(A)$ be the set of neighbors of vertices $A \subseteq V$ in G , and let $\mu(G)$ be the maximum matching size of G .

Theorem 2. For any (β, β^-) -EDCS H of G , with $\beta^- \geq (1 - O(\epsilon)) \cdot \beta$ and $\beta \geq O(\epsilon^{-3})$, we have $\mu(G) \leq (3/2 + \epsilon) \cdot \mu(H)$.

We first show the theorem for the case when G is a bipartite graph, and then extend it to general graphs.

2.1 Approximate Matching on Bipartite Graphs

Lemma 3 (Hall's Theorem). *Let $G = (L, R, E)$ be any bipartite graph with $|L| = |R| = n$. Then,*

$$\max_{A \subseteq L} (|A| - |N(A)|) = n - \mu(G).$$

We refer to such set A as a witness set.

Lemma 4. *For any (β, β^-) -EDCS H of bipartite graph $G = (L, R, E)$, we have $\mu(G) \leq (1/2 + \beta/\beta^-) \cdot \mu(H)$.*

Proof. Suppose $|L| = |R| = n$. Let $H = (L, R, E_H)$ be a (β, β^-) -EDCS of G with β and β^- satisfying the conditions in the theorem 2, and our goal is to show that

$$\mu(G) \leq (3/2 + \epsilon) \cdot \mu(H).$$

We apply Hall's theorem (Theorem 3) to H , and consider the witness set $S \subseteq L$ and $T = N_H(S) \subseteq R$, we have $\mu(H) = |\bar{S}| + |T| = n - |S| + |T|$.

Let $M_G \subseteq L \times R$ be the maximum matching of G , and let $M' = M_G \cap (S \times \bar{T})$. We must have

$$|M'| \geq \mu(G) - \mu(H)$$

because otherwise it raises the contradiction that

$$\begin{aligned} \mu(G) - n &\leq |N_G(S)| - |S| \leq |N_H(S)| + |M'| - |S| \\ &< (|S| - n + \mu(H)) + (\mu(G) + \mu(H)) - |S| \\ &= \mu(G) - n \end{aligned}$$

Let $V' = V(M') \subseteq (S \cup \bar{T})$ be the endpoints of the matching M' , and $E' = E_H \cap (V' \times N_H(V'))$. By the fact that H is a (β, β^-) -EDCS and $M' \cap H = \emptyset$, we have

$$|E'| = \sum_{v \in V'} \deg_H(v) = \sum_{(u,v) \in M'} (\deg_H(u) + \deg_H(v)) \geq \beta^- \cdot |M'| = \frac{\beta^-}{2} \cdot |V'|$$

On the other hand,

$$\begin{aligned} \beta \cdot |E'| &\geq \sum_{(u,v) \in E'} (\deg_{E'}(u) + \deg_{E'}(v)) \\ &= \sum_{v \in V'} (\deg_{E'}(v))^2 + \sum_{v \in N_H(V')} (\deg_{E'}(v))^2 \\ &\geq |V'| \cdot \left(\frac{1}{|V'|} \sum_{v \in V'} \deg_{E'}(v) \right)^2 + |N_H(V')| \cdot \left(\frac{1}{|N_H(V')|} \sum_{v \in N_H(V')} \deg_{E'}(v) \right)^2 \quad (*) \\ &\geq \frac{|E'|^2}{|V'|} + \frac{|E'|^2}{|N_H(V')|} \\ &\geq \left(\frac{\beta^-}{2} + \frac{|E'|}{|N_H(V')|} \right) \cdot |E'| \end{aligned}$$

Inequality (*) is due to the Cauchy-Schwarz inequality due to the fact that $\sum_{v \in V'} \deg_{E'}(v) = \sum_{v \in N_H(V')} \deg_{E'}(v) = |E'|$.

Therefore, $|E'| \leq (\beta - \frac{\beta^-}{2})|N_H(V')|$. Note that $|V'| \geq 2(\mu(G) - \mu(H))$ and $|N_H(V')| \leq \mu(H)$, we have

$$\beta^- \cdot (\mu(G) - \mu(H)) \leq |E'| \leq (\beta - \frac{\beta^-}{2}) \cdot \mu(H)$$

As a result,

$$\mu(G) \leq (1/2 + \beta/\beta^-) \cdot \mu(H)$$

□

2.2 Approximate Matching on General Graphs

In this section, we will show that we can generalize the result to general graph $G = (V, E)$ with a maximum matching M_G , and a (β, β^-) -EDCS $H = (V, E_H)$.

Construction To utilize results in the bipartite case, we apply the following randomized construction:

- Bipartition $V = L \cup R$ uniformly at random such that for all $(u, v) \in M_G$, u and v belong to different sides.
- Let $G' = (L, R, E \cap (L \times R))$ and $H' = (L, R, E_H \cap (L \times R))$.

It immediately follows from the construction that $\mu(G) = \mu(G')$ and $\mu(H') \leq \mu(H)$.

We want to show that a good partition exists, i.e., we can sample that partition with strictly positive probability using the following Lovasz Local Lemma.

Lemma 5 (Lovasz Local Lemma). *For events E_1, \dots, E_n , $\Pr \bigcap \bar{E}_i > 0$ if the following conditions hold:*

- $\Pr E_i \leq p$;
- E_i is independent of all but d events;
- $d \cdot p \leq 0.1$.

Lemma 6. H' is a $((1 + O(\epsilon))\beta/2, (1 - O(\epsilon))\beta^-/2)$ -EDCS of G' with probability > 0 .

Proof of Lemma 6. For any fixed $v \in V$, the number of its neighbors in subgraph H' can be modeled as: for every $u \in N_H(v)$, it is added to $N_{H'}(v)$ with probability $1/2$ independently. Moreover, we have $\mathbb{E}[\deg_{H'}(v)] = \deg_H(v)/2$ (+1 if v is in M_G). Therefore, by Chernoff Bound, we have

$$\Pr |\deg_{H'}(v) - \deg_H(v)/2| \geq \epsilon \cdot \beta + 1 \leq \exp(-\Omega(\epsilon^2 \beta)) \leq 1/\text{poly}(\beta)$$

By Lovasz Local Lemma with $d \leq \beta^4$

□

Finally, we are ready to prove the main theorem.

Theorem 2. *For any (β, β^-) -EDCS H of G , with $\beta^- \geq (1 - O(\epsilon)) \cdot \beta$ and $\beta \geq O(\epsilon^{-3})$, we have $\mu(G) \leq (3/2 + \epsilon) \cdot \mu(H)$.*

Proof of Theorem 2. By Lemma 6, there exists a partition $V = L \cup R$ such that $H' = (L, R, E_H \cap (L \times R))$ is a $((1 + O(\epsilon))\beta/2, (1 - O(\epsilon))\beta^-/2)$ -EDCS of the bipartite graph $G' = (L, R, E \cap (L \times R))$. Since G' is a bipartite graph, by Lemma 4, we have

$$\begin{aligned} \mu(G) = \mu(G') &\leq (1/2 + (1 + O(\epsilon))\beta/(1 - O(\epsilon))\beta^-)\mu(H') \\ &\leq (3/2 + \epsilon)\mu(H') \\ &\leq (3/2 + \epsilon)\mu(H) \end{aligned}$$

□

2.3 Application: One-Way Communication for Approximate Matching

In this section, we demonstrate an application of EDCS in the one-way communication model for approximate matching.

Setting Alice and Bob are given graphs $G_A = (V, E_A)$ and $G_B = (V, E_B)$, respectively. Alice is allowed to send a small message to Bob, and the goal is that Bob can find a large matching in the union graph $G = (V, E_A \cup E_B)$ given the message from Alice.

Protocol Alice computes an $(\beta, \beta - 1)$ -EDCS H_A of G_A and send it to Bob, the message size is only $O(n)$. Bob can then compute a maximum matching in $H_A \cup G_B$ and output it.

Claim $\mu(G) \leq (3/2 + \epsilon) \cdot \mu(H_A \cup G_B)$.

Proof. We fix a maximum matching M in G . Define $M_B = M \cap E_B$, $G' = (V, E_A \cup M_B)$, and $H' = (V, E_H \cup M')$, where $M' = \{e \in M_B \mid w_{H_A}(e) \leq \beta\}$. Now we show that H' is a $(\beta + 2, \beta - 1)$ -EDCS of G' . Note that $\deg_{H'}(v) - \deg_H(v) \in \{0, 1\}$.

- For any $(u, v) \in H'$: we have $\deg_{H'}(u) + \deg_{H'}(v) \leq \deg_H(u) + \deg_H(v) + 2$.
If $(u, v) \in H$, then $\deg_H(u) + \deg_H(v) \leq \beta$ by the properties of EDCS H .
Otherwise, by definition of M' , we have $\deg_H(u) + \deg_H(v) \leq \beta$ as well.
- For any $(u, v) \notin H'$: we have $\deg_{H'}(u) + \deg_{H'}(v) \geq \deg_H(u) + \deg_H(v)$.
If $(u, v) \in G \setminus H$, there is $\deg_H(u) + \deg_H(v) \geq \beta - 1$ by properties of EDCS H .
Otherwise, $\deg_H(u) + \deg_H(v) > \beta$ by the definition of M' .

Finally, since $\mu(G') = \mu(G)$, we have

$$\mu(G) = \mu(G') \leq (3/2 + \epsilon) \cdot \mu(H') \leq (3/2 + \epsilon) \cdot \mu(H_A \cup G_B).$$

□

3 Maintaining an EDCS in General Graphs [GSSU22]

In this section, we introduce a **deterministic** algorithm with **worst-case** update-time $O_\epsilon(m^{1/4})$ for maintaining an $(3/2 + \epsilon)$ -MCM in general graphs using EDCS.

Theorem 7. *For any dynamic graph G subject to edge updates and for any $\epsilon < 1/2$, one can maintain a $(3/2 + \epsilon)$ -MCM for G with a deterministic worst-case update time of $O(m^{1/4}\epsilon^{-5/2} + \epsilon^{-6})$.*

Related Works. In the following summarization of related works, we focus on the following key properties: the approximation factor, the update time, *whether the analysis is worst-case(W) or amortized(A)*, and *whether the algorithm is deterministic(D) or randomized(R)*.

	MCM	Update Time	W/A	D/R
[BGS11]	2	$O(\log n)$	A	R
[Sol16]	2	$O(1)$	A	R
[BFH19]	2	$O(\text{poly } \log n)$	W	R
[NS13]	$3/2$	$O(\sqrt{m})$	W	D
[BS16]	$3/2 + \epsilon$	$O_\epsilon(m^{1/4})$	A	D
[GSSU22]	$3/2 + \epsilon$	$O_\epsilon(m^{1/4})$	W	D

Table 1: Related works. Result of [GSSU22] is stated as Theorem 7.

High-level idea Approximate MCM \Leftrightarrow EDCS

In the following discussion, let $G = (V, E)$ be an undirected, unweighted dynamic graph with $n = |V|$ and $m = |E|$. We will dynamically maintain a subgraph $H = (V, E_H)$. Let Δ be an upper bound of the maximum degree in the dynamic graph. For simplicity, let $\beta^- = (1 - \epsilon)\beta$.

3.1 Part I: Update Time $O_\epsilon(\Delta)$

In this section, we show that an (β, β^-) -EDCS can be maintained with a worst-case update time $O_\epsilon(\Delta)$. We define the following two types of edges:

- “Full” edge $e = (u, v)$ if $e \in H$ and $w(u, v) = \beta$;
- “Deficient” edge $e = (u, v)$ if $e \notin H$ and $w(u, v) = \beta^-$.

Furthermore, a vertex v is said to be “increase-safe” (or respectively, “decrease-safe”) if it has no incident full (or respectively, deficient) edges.

Insertion. When inserting edge $e = (u, v)$ into G , there are two cases:

- If $w(u, v) \geq \beta^-$: then e will not be added to H . In this case, none of the weights will change, and the properties of EDCS will continue be satisfied.

- Otherwise, we add e to H . In this case, both $d_H(u)$ and $d_H(v)$ will increase by 1, which may lead incident edges to violate the EDCS properties. We focus on $v \in V$ first:

- If v is increase-safe, by definition, then we can safely increase $d_H(v)$ by 1. No further action is needed.
- If v is not increase-safe: Let $(v, p_1) \in H$ be the incident full edge, and we remove (v, p_1) from H . As a result, $d_H(v)$ will remain unchanged (compared to the time before insertion).

Such removal may also lead to violation of EDCS properties for p_1 since $d_H(p_1)$ will decrease by 1. Similarly, if p_1 is decrease-safe, no further action is needed. Otherwise, we find deficient edge (p_1, p_2) and add it to H . We repeat such process, updating full/deficient edges until we reach an increase-safe/decrease-safe vertex, like finding an alternative path.

Deletion. When deleting edge $e = (u, v)$ from G , the process is symmetric to insertion. We alternatively delete and add edges until no EDCS properties are violated.

Analysis. It remains to show that such process will terminate quickly, i.e., such alternative path will not be too long.

Lemma 8. *For any alternative path P of full and deficient edges, we have $|P| \leq 2/\epsilon$.*

Proof. Consider the path $(p_1, p_2, p_3, \dots, p_l)$ that begins with a full edge, with $d_H(p_1) + d_H(p_2) \geq \beta$. Then (p_2, p_3) is a deficient edge with $d_H(p_2) + d_H(p_3) \leq \beta^-$. Therefore, we have

$$d_H(p_3) \leq \beta^- - d_H(p_2) \leq d_H(p_1) + (\beta^- - \beta) \leq d_H(p_1) - \epsilon\beta.$$

By induction, we have $d_H(p_l) \leq d_H(p_1) - \frac{l\epsilon\beta}{2}$. However, $d_H(p_l) \geq 0$ and $d_H(p_1) \leq \beta$. Therefore, we must have $l \leq 2/\epsilon$. \square

Update Time. In the implementation, we maintain for every vertex its adjacent edges, full adjacent edges, and deficient adjacent edges. These lists should be updated in $O(\Delta)$ when the degree of the vertex changes. By the algorithm above, regardless of the length of the alternative path, at most 2 vertices will change in their degrees. Therefore, the list update time is $O(\Delta)$. Finally, we have showed that the worst-case update time is $O(\Delta + 1/\epsilon)$.

3.2 Part II: Improved Update Time $O_\epsilon(\sqrt{\Delta})$

In this section, we improve the above algorithm to allow a better update time – instead of updating all $O(\Delta)$ neighbors, we only update $\frac{10\Delta}{\epsilon\beta}$ out of its $O(\Delta)$ neighbors in a cyclic manner. It immediately follows that the new update time is $O(\frac{\Delta}{\epsilon\beta} + 1/\epsilon)$.

For $(v, w) \in E$, let $\tilde{d}_H^w(v)$ be the estimated degree of v by its neighbor w . The maximum error in estimation is the maximum number of batches a neighbor will wait until get notified,

i.e.,

$$Dis(H) = \max_{v,w} \{d_H(v) - \tilde{d}_H^w(v)\} \leq \Delta / \frac{10\Delta}{\epsilon\beta} = \frac{\epsilon\beta}{10}.$$

Since the update is incomplete, we need to analyze the consequences of not having accurate degree information in the following two aspects: change of length of alternative path, and the changed properties of EDCS.

Length of Alternative Path. We then show that the maximum length of an alternative path remains $O(1/\epsilon)$ using the estimated degree information. For path $(p_1, p_2, p_3, \dots, p_l)$, similarly to the proof of Lemma 8, we have

$$\begin{aligned} \tilde{d}_H^{p_2}(p_3) &\leq \beta^- - d_H(p_2) \leq \beta^- - \tilde{d}_H^{p_1}(p_2) + Dis(H) \\ &\leq \beta^- - \beta + d_H(p_1) + Dis(H) \\ &\leq d_H(p_1) - \epsilon\beta + \frac{\epsilon\beta}{10} = d_H(p_1) - \frac{9\epsilon\beta}{10}. \end{aligned}$$

Similarly, note that $d_H(p_1) \leq \beta$ and $d_H(p_l) \geq 0$, we have $l \leq \frac{5}{2\epsilon}$.

EDCS Properties. We than argue that H will still hold weaker EDCS properties with the estimated degree information.

Lemma 9. *The modified algorithm maintains a $(\gamma, (1 - 2\epsilon)\gamma)$ -EDCS with $\gamma = \beta(1 + \epsilon/10)$.*

Proof. For every edge $(u, v) \in H$, consider vertex u that knows its exact degree but only have estimation for its neighbors: the estimated weight

$$w(u, v) = d_H(u) + \tilde{d}_H^u(v) \leq d_H(u) + d_H(v) + Dis(H) \leq \beta + \frac{\beta\epsilon}{10} = \gamma.$$

On the other hand, for some edge $(u, v) \notin H$, we have

$$w(u, v) = d_H(u) + \tilde{d}_H^u(v) \geq d_H(u) + d_H(v) - Dis(H) \geq (1 - \epsilon)\beta - \frac{\beta\epsilon}{10} \geq \gamma(1 - 2\epsilon).$$

Therefore, the maintained H is a $(\gamma, (1 - 2\epsilon)\gamma)$ -EDCS. \square

Furthermore, we can verify that $(\gamma, (1 - 2\epsilon)\gamma)$ satisfies the conditions in Theorem 2 to maintain a $(3/2 + \epsilon)$ -approximate MCM.

Maintaining the MCM. By Gupta-Peng [GP13] algorithm, a $(1 + \epsilon)$ -MCM can be maintained on top of H within $O(\beta/\epsilon^2)$ time. Therefore, the combination yields a $(1 + \epsilon)(3/2 + \epsilon) \leq (3/2 + \frac{7}{2}\epsilon)$ approximation. Putting all together, we have a deterministic algorithm with worst-case update time

$$O\left(\frac{\Delta}{\epsilon\beta} + \frac{1}{\epsilon} \cdot \frac{\beta}{\epsilon^2}\right) = O\left(\frac{\Delta}{\epsilon\beta} + \frac{\beta}{\epsilon^3}\right) = O\left(\frac{\sqrt{\Delta}}{\epsilon^2} + \epsilon^{-6}\right).$$

The last equality is achieved by setting β to $\epsilon\sqrt{\Delta}$ if $\epsilon\sqrt{\Delta} \geq O(\epsilon^{-3})$ (by the requirement of Theorem 2), or to $O(\epsilon^{-3})$ otherwise.

3.3 Part III: Improved Update Time $O_\epsilon(\sqrt{\alpha})$

Definition 2 (Arboricity). *For graph G , the arboricity $\alpha(G)$ is the minimum number of forests into which the edges of G can be partitioned.*

Let α be the upper bound of the arboricity of the dynamic graph. In this section, we improve the update time to $O_\epsilon(\sqrt{\alpha})$.

One important property of arboricity is that $\alpha(G) \leq \sqrt{m}$ for an m -edge graph G . Therefore, an $O_\epsilon(\sqrt{\alpha})$ update time immediately implies an $O_\epsilon(m^{1/4})$ update time.

Sparsification. The matching sparsification algorithm by Solomon [Sol18] is as follows: For a parameter η , for every vertex $v \in V$, we mark up to η arbitrary incident edges. An edge will be added to the sparsified graph if it is marked twice. It is shown that by setting $\eta = 5(5/\epsilon + 1)2\alpha$, the resulting graph G' is a $(1 - \epsilon)$ -approximate matching sparsifier for G .

Maintaining Sparsifier. The idea is to maintain a sparsifier G' of the dynamic graph G , and feed G' to the algorithm in previous sections. In fact, the following lemma is proven.

Lemma 10. *One can dynamically maintain a $(1 + \epsilon)$ -approximate sparsifier G' for dynamic graph G with constant worst-case update time and recourse bound, where $\Delta(G') \leq O(\sqrt{m}/\epsilon)$.*

Finally, we are able to show the main Theorem 7. The overall approximation ratio is $(3/2 + \epsilon)$, and the worst-case update time is

$$O\left(\frac{\sqrt{\Delta}}{\epsilon^2} + \epsilon^{-6}\right) = O(m^{1/4} \cdot \epsilon^{-5/2} + \epsilon^{-6}).$$

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