## **CONCURRENCY**

Introduction: What is a thread?

- on board

multiple "programs" executing within the SAME address space!
usually cooperating to achieve some task, or independent related tasks

- e.g., parallel program, web/db server

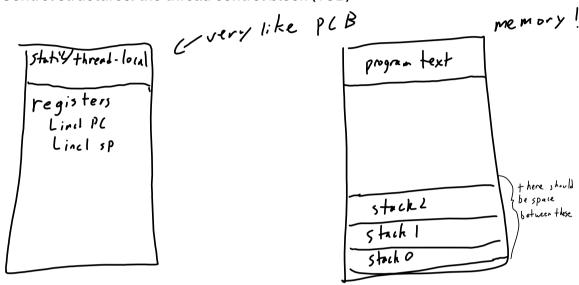
thus, each thread has:

- its own private set of registers
- its own program counter
- its own stack (and stack-pointer/base-pointer)

but shares

- rest of address space (heap, static global, code section too)

Control structures: the thread control block (TCB)



What makes thread programming hard?

main-thread-0 (no locks)

Examine in detail: imagine a trace of main-thread-0; how is "++" implemented? assembly on the board: | oad (allr); ald 1; store (addr)

Why programs get tricky: SHARED DATA

REAL PROBLEM: uncontrolled scheduling (interrupts at any time)

- remember our timer-based scheduler?? This is where it hurts!
- note: this is NOT a problem if we're in cooperative scheduling with predictable yields.

lots of definitions:

- program is not deterministic (indeterminate)
- critical section (where the bug can be)
- race condition (what the bug is)
- need mutual exclusion (one-at-a-time)

(turn non-deterministic code into quasi-deterministic code)

main-thread-1 (fine-grained locks)
need synch primitives

main-thread-2 (coarse-grained locks) need synch primitives but be careful

main-thread-3 (implement locks try #1: test-and-set)

just run it

(what is the problem?)

main-thread-4 (implement locks try #2: x86 xchg)

how to build a lock using special hardware?

(how to use xchg?)

main-thread-5 (implement locks try #2: x86 xchg + spinlock implementation)

this is how

objdump -d to look at it

Conclusions:

Why in OS class?

threads are basic OS primitive

OS itself is a concurrent program!

## code fixed (1)

```
we just init a lock and lock the exact increment
```

```
#include <stdio.h>
#include "mythreads.h"
#include <stdlib.h>
#include <pthread.h>
int max;
volatile int balance = 0;
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
void *
mythread(void *arg)
  char *letter = arg;
  //cpubind();
  printf("%s: begin\n", letter);
  int i;
  for (i = 0; i < max; i++) {
    Pthread_mutex_lock(&lock);
    balance++;
    Pthread_mutex_unlock(&lock);
  }
  printf("%s: done\n", letter);
  return NULL;
}
int
main(int argc, char *argv[])
{
  if (argc != 2) {
    fprintf(stderr, "usage: main-first <loopcount>\n");
    exit(1);
  }
  max = atoi(argv[1]);
  pthread_t p1, p2;
  printf("main: begin [balance = %d]\n", balance);
  Pthread_create(&p1, NULL, mythread, "A");
  Pthread_create(&p2, NULL, mythread, "B");
  // join waits for the threads to finish
  Pthread_join(p1, NULL);
  Pthread_join(p2, NULL);
  printf("main: done\n [balance: %d]\n [should: %d]\n",
      balance, max*2);
  return 0;
}
```

## code fix (2)

we move the lock to outside the loop, and cpubind()

```
#include <stdio.h>
#include "mythreads.h"
#include "mythreads-2.h"
#include <stdlib.h>
#include <pthread.h>
int max;
volatile int balance = 0;
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
void *
mythread(void *arg)
  char *letter = arg;
  cpubind();
  printf("%s: begin\n", letter);
  int i;
  Pthread_mutex_lock(&lock);
  for (i = 0; i < max; i++) {
    balance++;
  }
  Pthread_mutex_unlock(&lock);
  printf("%s: done\n", letter);
  return NULL;
}
int
main(int argc, char *argv[])
  if (argc != 2) {
    fprintf(stderr, "usage: main-first <loopcount>\n");
    exit(1);
  }
  max = atoi(argv[1]);
  pthread_t p1, p2;
  printf("main: begin [balance = %d]\n", balance);
  Pthread_create(&p1, NULL, mythread, "A");
  Pthread_create(&p2, NULL, mythread, "B");
  // join waits for the threads to finish
  Pthread_join(p1, NULL);
  Pthread_join(p2, NULL);
  printf("main: done\n [balance: %d]\n [should: %d]\n",
      balance, max*2);
  return 0;
```

}

## in the exchange-based one

```
SpinLock(volatile unsigned int *lock) {
  while (xchg(lock, 1) == 1)
  // spin!
}
SpinUnlock(volatile unsigned int *lock) {
  xchg(lock, 0);
}
```