**Relevant Book Sections** 

• Book chapters: 3.4

## **Precept Outline**

- Review of Lectures 13 and 14:
  - Hash Tables
  - K-d Trees

# A. Review: Hash Tables + K-d Trees

Your preceptor will briefly review key points of this week's lectures.

## B. Hash Tables

Solve exercises 1 through 6 in the Hash Tables Ed lesson.

### C. K-d Trees

Draw the Kd-tree that results from inserting the following points:

Α	В	С	D	E	F	G
(2, 3)	(4, 2)	(4,5)	(3,3)	(1, 5)	(4, 4)	(1, 1)

Additionally, draw each point on the grid, as well as the vertical or horizontal line that runs through the point and partitions the plane or a subregion thereof.

**Recall**: While inserting, go left if the coordinate of the inserted point is less than the coordinate of the current node. Go right if it is greater than **or equal**.

Use the images below to draw your grid/tree.





Determine each point's bounding box and fill them in the table below.

Α	$[-\infty,\infty]  imes [-\infty,\infty]$
В	
С	
D	
E	
F	
G	

Number the (non-null) nodes in the sequence they are visited by a *range query* with the rectangle shown below. Which subtrees are pruned? (Some null subtrees may be pruned, and some may not be.)

**Remember.** The range search algorithm recursively searches in both the left and right subtrees unless the bounding box of the *current* node does not intersect the query rectangle. If both do, our convention is to visit the left one first.



# D. Assignment Overview: K-d Tree

Your preceptor will introduce and give an overview of your fourth assignment. Please don't hesitate to ask questions!

Summary of the assignment.

- Implement a PointST class, a symbol table whose keys are two-dimensional points. Don't overthink this part of the assignment. It's worth 25% of the grade but should take much less than that proportion of time pay attention to the lax performance requirements. It has nothing to do with k-d trees!
- Implement a KdTreeST class, a 2d-tree to implement a symbol table with two-dimensional point keys.
- There is also a readme.txt where you have to perform a simple timing experiment and answer one theoretical question about pruning.

Here are a few implementation tips:

- **Avoid duplicating code**. Use private helper methods to achieve that. For example, a compare helper method can be used to encapsulate the logic of checking the orientation and doing the comparison using the correct coordinate. This makes the code cleaner and more concise.
- Avoid reinventing the wheel. Do not re-implement the RectHV and Point2D methods!
- Use the visualizer classes. They are there to help, and are extremely useful debugging tools!
- **Duplicate points**. The KdTreeST is a symbol table, so duplicates are not allowed. Make sure to handle that in the put method! The expected behavior when inserting a a key that has been inserted before is to replace the old value with the new value.
- **Timing**. To count the number of calls per second:
  - Use put() to build the tree but don't time this part.
  - Time so that the method is repeatedly called for at least 2 seconds.
  - Example: If the method is called N times in 4.62 seconds, then report  $\frac{N}{4.62}$  as the number of calls per second.
  - Expect a faster method to have a higher number of calls per second.
- Recursion.
  - If your recursive method returns a value, make sure to catch the return value and use it whenever you make a recursive call.
  - If your recursive method receives an argument that needs to be updated, note that the following works:

```
void myMethod(Type1 arg1, Type2 result) {
    result.setX(someValue);
    ...
}
But the following does not work:
```

```
void myMethod(Type1 arg1, Type2 result) {
    result = new Type2(someValue);
    ...
}
```

In the first example, result is a reference, and the method is changing X in the object referenced by result.
 In the second example, result is a reference to the object passed as an argument. By setting result = ..., we make the reference result point to a new object but don't change the original object.