

Linear Regression

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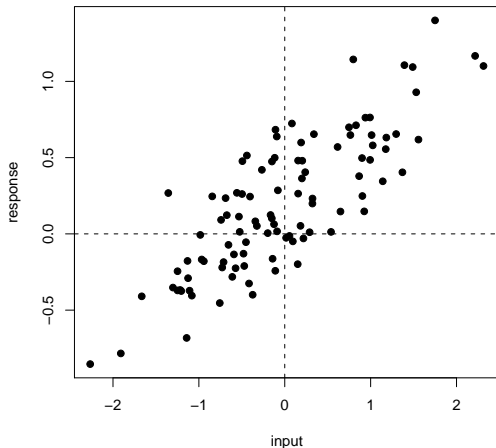
COS424
Princeton University

April 10, 2008

Regression

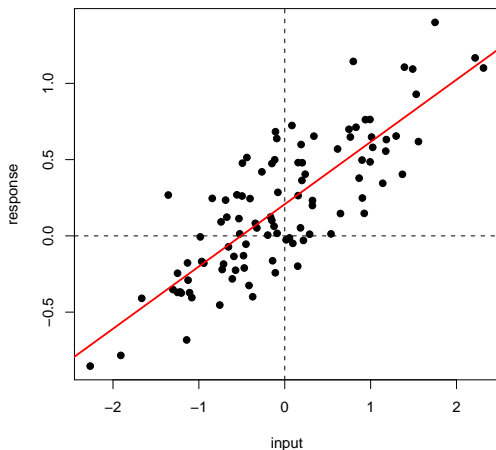
- We have studied classification, the problem of automatically categorizing data into a set of discrete classes.
- E.g., based on its words, is an email spam or ham?
- **Regression** is the problem of predicting a real-valued variable from data input.

Linear regression



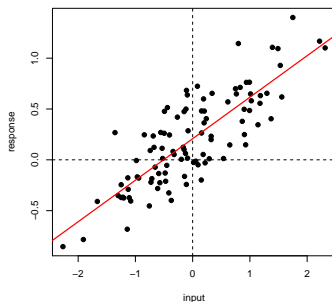
Data are a set of inputs and outputs $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$

Linear regression



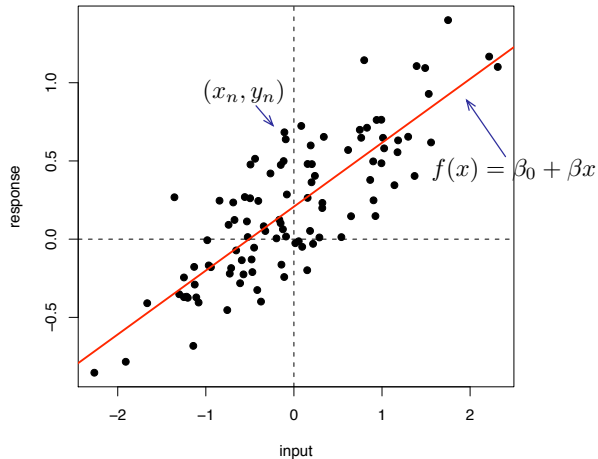
The goal is to predict y from x using a linear function.

Examples



- Given today's weather, how much will it rain tomorrow?
- Given today's market, what will be the price of a stock tomorrow?
- Given her emails, how long will a user stay on a page?
- Others?

Linear regression



Multiple inputs

- Usually, we have a vector of inputs, each representing a different **feature** of the data that might be predictive of the response.

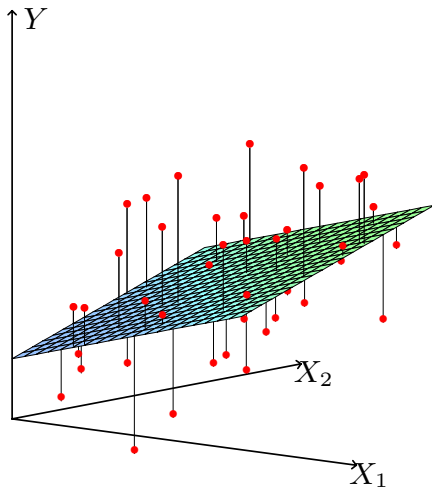
$$\mathbf{x} = \langle x_1, x_2, \dots, x_p \rangle$$

- The response is assumed to be a linear function of the input

$$f(\mathbf{x}) = \beta_0 + \sum_{i=1}^p x_i \beta_i$$

- Here, $\beta^\top \mathbf{x} = 0$ is a **hyperplane**.

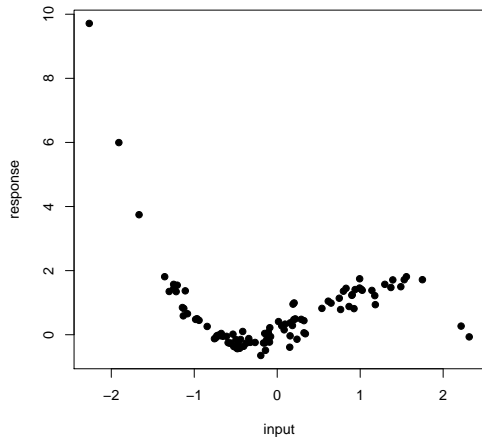
Multiple inputs



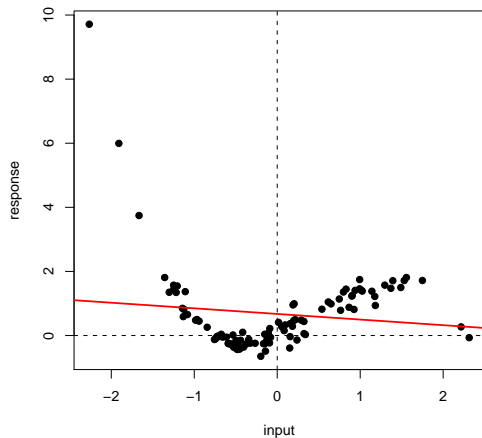
Flexibility of linear regression

- This set-up is less limiting than you might imagine.
- Inputs can be:
 - Any features of the data
 - Transformations of the original features, e.g., $x_2 = \log x_1$ or $x_2 = \sqrt{x_1}$.
 - A basis expansion, e.g., $x_2 = x_1^2$ and $x_3 = x_1^3$
 - Indicators of qualitative inputs, e.g., category
 - Interactions between inputs, e.g., $x_1 = x_2x_3$
- Its simplicity and flexibility make linear regression one of the most important and widely used statistical prediction techniques.

Polynomial regression example

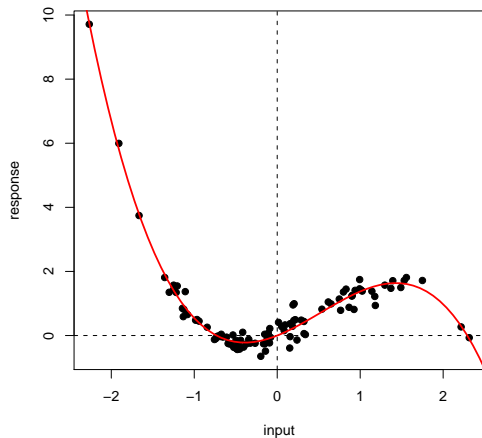


Linear regression



$$f(x) = \beta_0 + \beta x$$

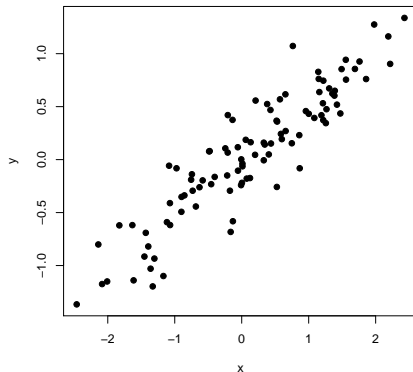
Polynomial regression



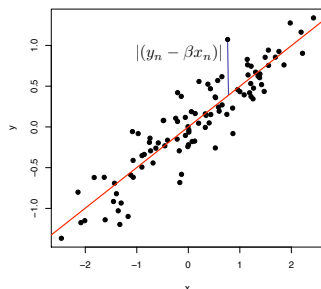
$$f(x) = \beta_0 + \beta_1x + \beta_2x^2 + \beta_3x^3$$

Fitting a regression

- Given data $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$, find the coefficient β that can predict y_{new} from x_{new} .
- Simplifications:
 - 0-intercept, i.e., $\beta_0 = 0$
 - One input, i.e., $p = 1$
- How should we proceed?



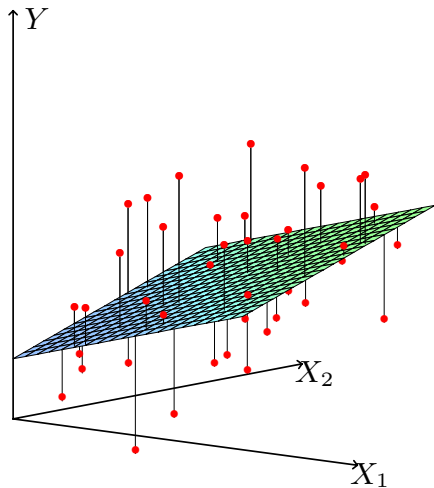
Residual sum of squares



A reasonable approach is to minimize sum of the squared Euclidean distance between each prediction βx_n and the truth y_n

$$\text{RSS}(\beta) = \frac{1}{2} \sum_{n=1}^N (y_n - \beta x_n)^2$$

RSS for two inputs



Optimizing β

The objective function is

$$\text{RSS}(\beta) = \frac{1}{2} \sum_{n=1}^N (y_n - \beta x_n)^2$$

The derivative is

$$\frac{d}{d\beta} \text{RSS}(\beta) = - \sum_{n=1}^N (y_n - \beta x_n) x_n$$

The optimal value is

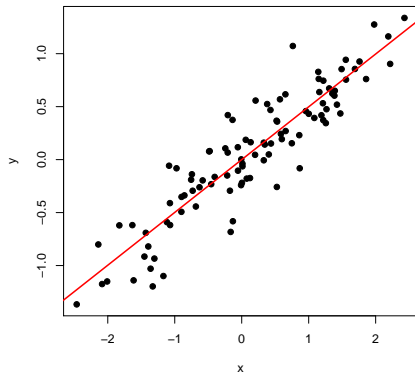
$$\hat{\beta} = \frac{\sum_{n=1}^N y_n x_n}{\sum_n x_n^2}$$

The optimal β

- The optimal value is

$$\hat{\beta} = \frac{\sum_{n=1}^N y_n x_n}{\sum_n x_n^2}$$

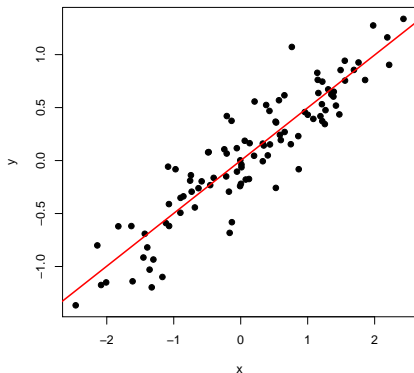
- + values pull the slope up.
- - values pull the slope down



Prediction

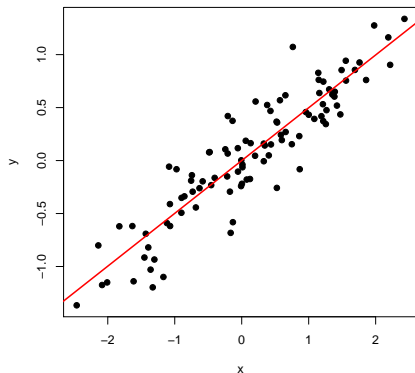
- After finding the optimal β , we would like to **predict** a new output from a new input.
- We use the point on the line at the input,

$$\hat{y}_{\text{new}} = \hat{\beta}x_{\text{new}}$$



Prediction

- Note the difference between classification and prediction.
- Note that linear regression assumes the input is always observed.



Multiple inputs

In general,

$$y = \beta_0 + \sum_{i=1}^p \beta_i x_i$$

To simplify, let β be a $p + 1$ vector and set $x_{p+1} = 1$. Now the RSS is

$$\text{RSS}(\beta) = \frac{1}{2} \sum_{n=1}^N (y_n - \beta^\top x_n)^2$$

(Note that β_{p+1} is β_0 in the old notation.)

Multiple inputs

The objective is:

$$\text{RSS}(\beta) = \frac{1}{2} \sum_{n=1}^N (y_n - \beta^\top x_n)^2$$

The derivative with respect to β_i is:

$$\frac{d}{d\beta_i} = - \sum_{n=1}^N (y_n - \beta_i x_{n,i}) x_{n,i}$$

As a vector, the gradient is:

$$\nabla_{\beta} \text{RSS} = - \sum_{n=1}^N (y_n - \beta^\top x_n) x_n$$

One option : optimize with some kind of gradient-based algorithm.

The normal equations

The **design matrix** is an $N \times (p + 1)$ matrix:

$$X = \begin{bmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,p} & 1 \\ x_{2,1} & x_{2,2} & \dots & x_{2,p} & 1 \\ & & \vdots & & \\ x_{N,1} & x_{N,2} & \dots & x_{N,p} & 1 \end{bmatrix}$$

The **response vector** is an N -vector:

$$y = \langle y_1, y_2, \dots, y_N \rangle$$

Recall that the **parameter vector** is a $(p + 1)$ -vector

$$\beta = \langle \beta_1, \beta_2, \dots, \beta_{p+1} \rangle$$

The normal equations

With these definitions, the gradient of the RSS is

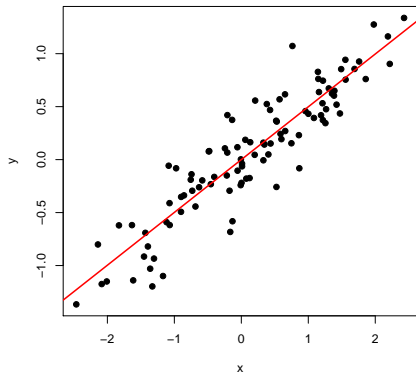
$$\nabla_{\beta} \text{RSS} = -\mathbf{X}^{\top}(\mathbf{y} - \mathbf{X}\beta)$$

Setting to the 0-vector and solving for β :

$$\begin{aligned}\mathbf{X}^{\top}\mathbf{y} - \mathbf{X}^{\top}\mathbf{X}\hat{\beta} &= 0 \\ \mathbf{X}^{\top}\mathbf{X}\hat{\beta} &= \mathbf{X}^{\top}\mathbf{y} \\ \hat{\beta} &= (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}\end{aligned}$$

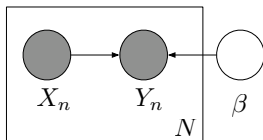
This works as long as $\mathbf{X}^{\top}\mathbf{X}$ is invertible, i.e., \mathbf{X} is full rank.

Probabilistic interpretation



- Our reasoning so far has not included any probabilities
- It is no surprise that linear regression has a probabilistic interpretation
- What do you think that it is?

Probabilistic interpretation



- Linear regression assumes that the output are drawn from a Normal distribution whose mean is a linear function of the coefficients and the input,

$$Y_n | x_n, \beta \sim \mathcal{N}(\beta \cdot x_n, \sigma^2)$$

- This is like putting a Gaussian “bump” around the mean, which is a linear function of the input.
- Note that this is a **conditional model**. The inputs are not modeled.

Conditional maximum likelihood

We find the parameter vector β that maximizes the **conditional likelihood**. The conditional log likelihood of data $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$ is

$$\begin{aligned}\mathcal{L}(\beta) &= \log \prod_{n=1}^N p(y_n | x_n, \beta) \\ &= \log \prod_{n=1}^N \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left\{ \frac{-(y_n - \beta^\top x_n)^2}{2\sigma^2} \right\} \\ &= \sum_{n=1}^N -\frac{1}{2} \log 2\pi\sigma^2 - \frac{1}{2} (y_n - \beta^\top x_n)^2 / \sigma^2\end{aligned}$$

Question: What happens when we optimize with respect to β ?

Conditional maximum likelihood

Maximizing the conditional log likelihood with respect to β ,

$$\mathcal{L}(\beta) = \sum_{n=1}^N -\frac{1}{2} \log 2\pi\sigma^2 - \frac{1}{2}(y_n - \beta^\top x_n)^2/\sigma^2$$

is the same as *minimizing* the residual sum of squares

$$\text{RSS}(\beta) = \frac{1}{2}(y_n - \beta^\top x_n)^2$$

The maximum likelihood estimates are identical to the estimates we obtained earlier.

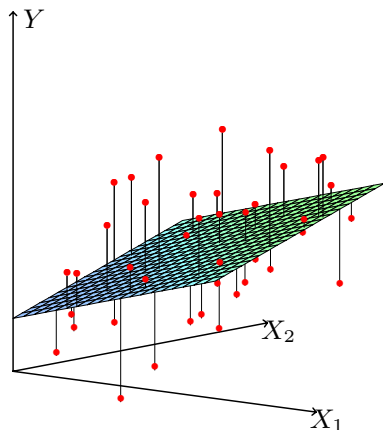
Question: What is the probabilistic interpretation of prediction?

Probabilistic prediction

- In prediction, we estimate the *conditional expectation*:

$$E[y_{\text{new}} | x_{\text{new}}] = \beta^T x_{\text{new}}$$

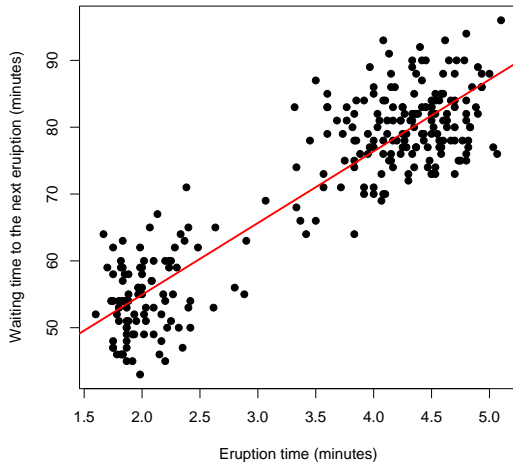
- This is identical to the geometric treatment.
- Note: the variance term σ^2 does not play a role in estimation or prediction.



“Real-world” example



“Real-world” example



Important aside

- A pervasive concept in machine learning and statistics is the **bias variance trade-off**.
- Consider a random data set that is drawn from a linear regression model,

$$Y_n | x_n, \beta \sim \mathcal{N}(\beta x_n, \sigma^2).$$

- We can contemplate the maximum likelihood estimate $\hat{\beta}$ as a *random variable* whose distribution is governed by the distribution of the data set $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$.

Bias variance decomposition

Suppose we observe a new data input x , we can consider the **mean squared error** of our estimate of $E[y | x] = \hat{\beta}x$.

$$\text{MSE}(\hat{\beta}x) = E_{\mathcal{D}}[(\hat{\beta}x - \beta x)^2]$$

Note that β is *not* random and $\hat{\beta}$ is random.

$$\begin{aligned} \text{MSE} &= E[(\hat{\beta}x)^2] - 2E[\hat{\beta}x]\beta x + (\beta x)^2 \\ &= E[(\hat{\beta}x)^2] - 2E[(\hat{\beta}x)](\beta x) + (\beta x)^2 + E[(\hat{\beta}x)]^2 - E[(\hat{\beta}x)]^2 \\ &= \left(E[(\hat{\beta}x)^2] - E[\hat{\beta}x]^2\right) + \left(E[\hat{\beta}x] - \beta x\right)^2 \end{aligned}$$

Bias variance decomposition

$$\text{MSE} = \left(\text{E}[(\hat{\beta}_x)^2] - \text{E}[\hat{\beta}_x]^2 \right) + \left(\text{E}[\hat{\beta}_x] - \beta_x \right)^2$$

- The second term is the squared **bias**,

$$\text{bias} = \text{E}[\hat{\beta}_x] - \beta_x$$

An estimate for which this term is zero is an **unbiased estimate**.

- The first term is the **variance**,

$$\text{variance} = \text{E}[(\hat{\beta}_x)^2] - \text{E}[\hat{\beta}_x]^2$$

This reflects how sensitive the estimate is to the randomness inherent in the data.

Bias variance and prediction error

What about **prediction error**, which is what we ultimately care about? Suppose we see a new input x . The expected squared prediction error is

$$E_{\mathcal{D}}[E_Y[(\hat{\beta}x - Y)^2]]$$

The first expectation is taken for the randomness of $\hat{\beta}$. The second is taken for the randomness of Y given x .

$$\begin{aligned} E_{\mathcal{D}}[E_Y[(\hat{\beta}x - Y)^2]] &= \text{Var}(Y) + \text{MSE}(\hat{\beta}x) \\ &= \sigma^2 + \text{Bias}^2(\hat{\beta}x) + \text{Var}(\hat{\beta}x) \end{aligned}$$

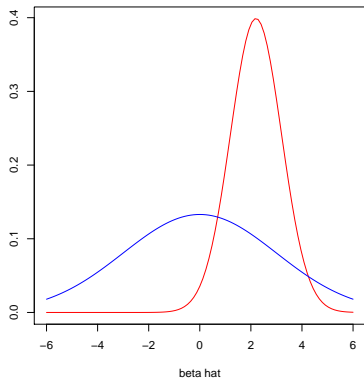
The first term is the inherent uncertainty around the true mean; the second two terms are the bias variance decomposition of the estimator.

Gauss-Markov theorem

$$\text{MSE} = \left(\text{E}[(\hat{\beta}_x)^2] - \text{E}[\hat{\beta}_x]^2 \right) + \left(\text{E}[\hat{\beta}_x] - \beta_x \right)^2$$

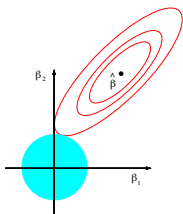
The *Gauss-Markov* theorem states that the MLE/least squares estimate of β is the unbiased estimate with smallest variance.

Bias variance trade-off



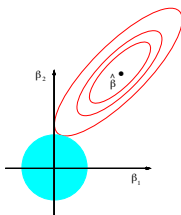
- Classical statistics focuses on unbiased estimates.
- Modern statistics has explored the *trade-off*.
- We might sacrifice a little bias for a larger reduction in variance.

Regularization



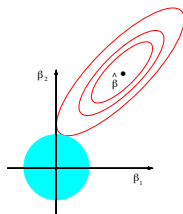
- In regression, we can make this trade-off with **regularization**, which means placing constraints on the coefficients β .
- Intuitively, this reduces the variance because it limits the space that the parameter vector β can live in.
- If the true MLE of β lives outside that space, then the resulting estimate *must* be biased because of the Gauss-Markov theorem.

Regularization



- Regularization encourages smaller and simpler models.
- Intuitively, simpler models are more robust to **overfitting**, generalizing poorly because of a close match to the training data.
- Simpler models can also be more **interpretable**, which is another goal of regression.

Ridge regression



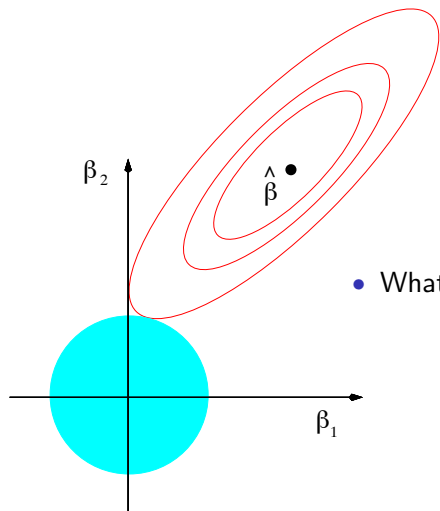
- In **ridge regression**, we optimize the RSS subject to a constraint on the sum of squares of the coefficients,

$$\text{minimize} \quad \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2$$

$$\text{subject to} \quad \sum_{i=1}^p \beta_i^2 \leq s$$

- This constrains the coefficients to live within a sphere of radius s .

Ridge regression



- What happens as s increases?

Ridge regression

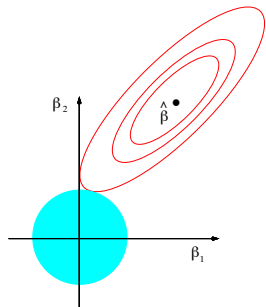
- The ridge regression estimate can also be expressed as

$$\hat{\beta}^{\text{ridge}} = \arg \min_{\beta} \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2 + \lambda \sum_{i=1}^p \beta_i^2$$

- This problem is convex.
- If the covariates are uncorrelated, it has an analytic solution. (You'll see this on your homework.)

Ridge regression

$$\hat{\beta}^{\text{ridge}} = \arg \min_{\beta} \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2 + \lambda \sum_{i=1}^p \beta_i^2$$

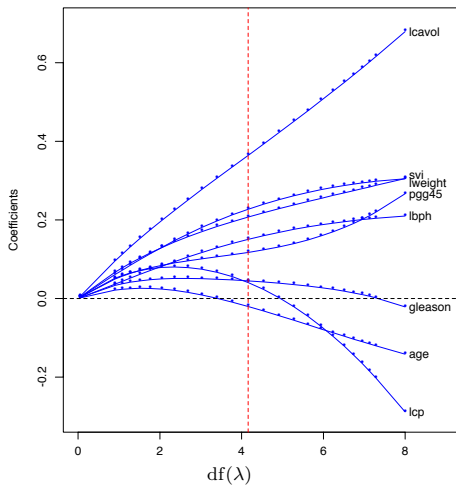


- There is a 1-1 mapping between s and λ .
- λ is the **complexity parameter**
- It determines the radius of the sphere
- Trades off an increase in bias for a decrease in variance

Prostate cancer data

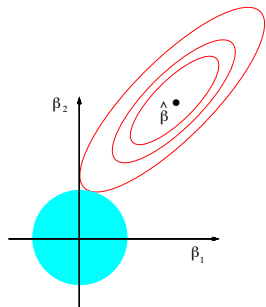
- Study from Stamey et al. (1989)
- Examined the correlation between the level of prostate-specific antigen and a number of clinical measures in mean about to receive a procedure
- Variables are
 - log cancer volume
 - log prostate weight
 - age
 - log of the amount of benign prostatic hyperplasia
 - seminal vesicle invasion
 - log of capsular penetration
 - Gleason score
 - percent of Gleason scores 4 or 5

Coefficients as a function of λ



How can we choose λ ?

Choosing λ



- The choice of complexity parameter greatly affects our estimate
- What would happen if we used training error as the criterion?
- In practice, λ is chosen by **cross validation**.
- This is an attempt to minimize *test error*.

Cross-validation to choose the complexity parameter

- Divide the data into 10 folds
- Decide on candidate values of λ (e.g., a grid between 0 and 1)
- For each fold and value of λ ,
 - Estimate $\hat{\beta}^{\text{ridge}}$ on the **out-of-fold** samples.
 - For each **within-fold** sample x_n , compute its squared error

$$\epsilon_n = (\hat{y}_n - y_n)^2$$

- The score for that value of λ is

$$\text{MSE}(\lambda) = \frac{1}{N} \sum_{n=1}^N \epsilon_n$$

- Choose the value of λ that minimizes this score.

Cross-validation to choose the complexity parameter

- The score for that value of λ is

$$\text{MSE}(\lambda) = \frac{1}{N} \sum_{n=1}^N \epsilon_n$$

- Choose the value of λ that minimizes this value.
- Notice that each ϵ_n was computed from a model that did not include the n th data point in its fit.
- Thus, $\text{MSE}(\lambda)$ is an estimate of **test error**.
- Dave, draw a picture on the board.

Aside: Bayesian statistics

- In **Bayesian** statistics, we treat the *parameter* as a *random variable*.
- In the model, it is endowed with a **prior distribution**.
- Rather than estimate the parameter, we perform **posterior inference**.
- In general,

$$\begin{aligned}\theta &\sim G_0(\alpha) \\ y_n &\sim F(\theta)\end{aligned}$$

and posterior inference is concerned with

$$p(\theta | y_1, \dots, y_N, \alpha)$$

- The parameter to the prior α is called a **hyperparameter**.

Aside: Bayesian statistics

There are two usual ways of using the posterior to obtain an estimate

- Maximum a posteriori estimates

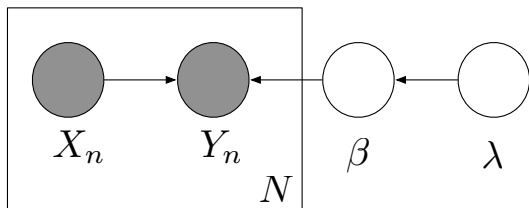
$$\theta^{\text{MAP}} = \arg \max_{\theta} p(\theta | y_1, \dots, y_N, \alpha)$$

- Posterior mean estimate

$$\theta^{\text{mean}} = \text{E}[\theta | y_1, \dots, y_N, \alpha]$$

- *Why are these different from the MLE?*

Ridge regression



Ridge regression corresponds to MAP estimation in the following model:

$$\begin{aligned}\beta_i &\sim \mathcal{N}(0, 1/\lambda) \\ Y_n | x_n, \beta &\sim \mathcal{N}(\beta^\top x_n, \sigma^2)\end{aligned}$$

Bayesian interpretation of ridge regression

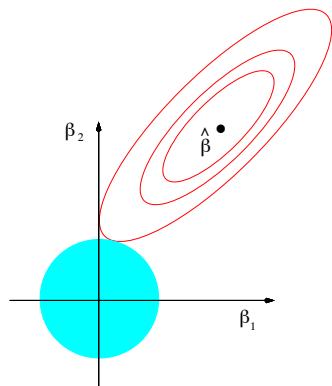
Note that

$$p(\beta_i | \lambda) = \frac{1}{\sqrt{2\pi(1/\lambda)}} \exp\{-\lambda\beta_i^2\}$$

Let's compute the MAP estimate of β :

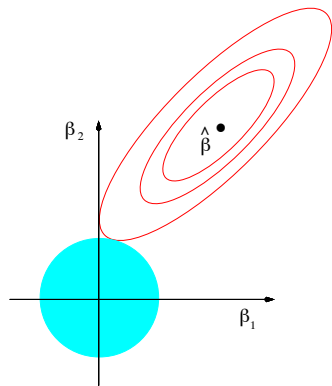
$$\begin{aligned} \max_{\beta} p(\beta | y_{1:N}, x_{1:N}, \lambda) &= \max_{\beta} \log p(\beta | y_{1:N}, x_{1:N}, \lambda) \\ &= \max_{\beta} \log p(\beta, y_{1:N} | x_{1:N}, \lambda) \\ &= \max_{\beta} \log \left(p(y_{1:N} | x_{1:N}, \beta) \prod_{i=1}^p p(\beta_i | \lambda) \right) \\ &= \max_{\beta} -\text{RSS}(\beta; y_{1:N}, x_{1:N}) - \sum_{i=1}^p \lambda\beta_i^2 \end{aligned}$$

Bayesian intuitions



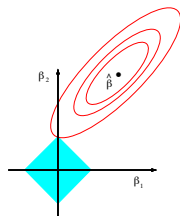
- The hyperparameter controls how far away the estimate will be from the MLE
- A small hyperparameter (large variance) will choose the MLE, i.e., the data totally determine the estimate
- As the hyperparameter gets larger, the estimate moves further from the MLE. The prior ($E[\beta] = 0$) becomes more influential.
- A theme in Bayesian estimation: Both the data and the prior influence the answer.

Summary of ridge regression



- We constrain β to be in a hypersphere around 0.
- This is equivalent to minimizing the RSS plus a regularization term.
- We no longer find the $\hat{\beta}$ that minimizes the RSS. (Contours illustrate constant RSS.)
- Also called *shrinkage*, because we are reducing the components to be close to 0 and close to each other
- Ridge estimates trade off bias for variance.

The lasso

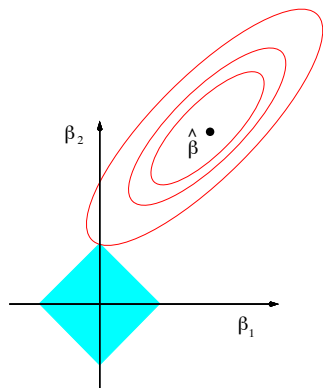


- A related regularization method is called **the lasso**.
- We optimize the RSS subject to a different constraint.

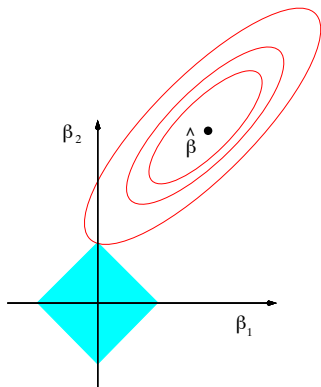
$$\text{minimize} \quad \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2$$

$$\text{subject to} \quad \sum_{i=1}^p |\beta_i| \leq s$$

- This small change yields very different estimates.



- What happens as s increases?
- Where is the solution going to lie?



- It's a fact: unless it chooses $\hat{\beta}$, the lasso will set some of the coefficients to exactly zero.
- This is a form of **feature selection**, identifying a relevant subset of our inputs to perform prediction.
- Trades off an increase in bias with a decrease in variance
- And, provides interpretable (sparse) models

- The lasso is equivalent to

$$\hat{\beta}^{lasso} = \arg \min_{\beta} \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2 + \lambda \sum_{i=1}^p |\beta_i|$$

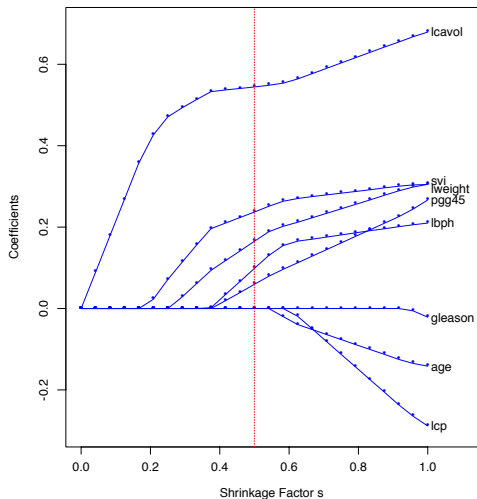
- Again, there is a 1-1 mapping between λ and s
- This objective is still convex!

Why the lasso is exciting

$$\hat{\beta}^{\text{lasso}} = \arg \min_{\beta} \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2 + \lambda \sum_{i=1}^p |\beta_i|$$

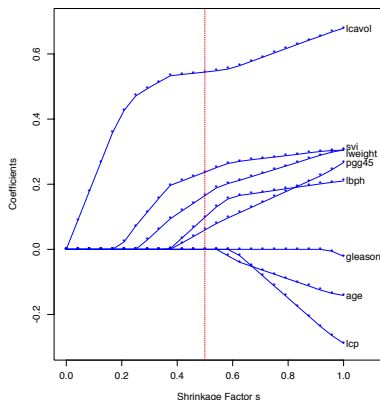
- Prior to the lasso, the only “sparse” method was **subset selection**, finding the best subset of features with which to model the data
- But, searching over all subsets is very computationally expensive
- The lasso efficiently finds a sparse solution with convex optimization.
- This is akin to a “smooth version” of subset selection.
- Note: the lasso won't consider all possible subsets.

Optimizing λ



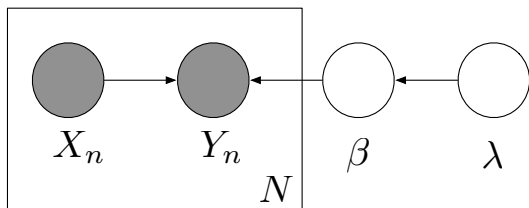
As we increase s (decrease λ), coefficients become non-zero.

Choosing λ with LARS



- Again, we choose the complexity parameter λ with cross-validation.
- The LARS algorithm (Efron et al., 2004) lets us efficiently explore the entire **regularization path** of λ .

Bayesian interpretation of the lasso



Lasso regression corresponds to MAP estimation in the following model:

$$\begin{aligned}\beta_i &\sim \text{Laplace}(\lambda) \\ Y_n | x_n, \beta &\sim \mathcal{N}(\beta^\top x_n, \sigma^2)\end{aligned}$$

Where the coefficients come from a **Laplace distribution**

$$p(\beta_i | \lambda) = \frac{1}{2} \exp\{-\lambda|\beta_i|\}$$

Generalized regularization

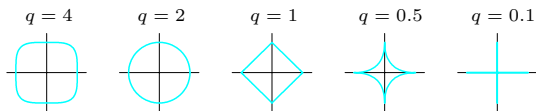
- In general, regularization can be seen as minimizing the RSS with a constraint on a q -norm,

$$\text{minimize} \quad \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2$$

$$\text{subject to} \quad \|\beta\|_q \leq s$$

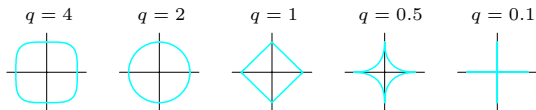
- The methods we discussed so far:
 - $q = 2$: ridge regression
 - $q = 1$: lasso
 - $q = 0$: subset selection

Generalized regularization



- This brings us away from the minimum RSS solution, but might provide better test prediction via the bias/variance trade-off.
- Complex models have less bias; simpler models have less variance. Regularization encourages simpler models.

Generalized regularization



- Each of these methods correspond to a Bayesian solution with a different choice of prior.

$$\hat{\beta}^{\text{ridge}} = \arg \min_{\beta} \sum_{n=1}^N \frac{1}{2} (y_n - \beta x_n)^2 + \lambda \|\beta\|_q$$

- The complexity parameter λ can be chosen with cross validation.
- Lasso ($q = 1$) is the only norm that provides sparsity and convexity.

Regularization comparison

TABLE 3.3. *Estimated coefficients and test error results, for different subset and shrinkage methods applied to the prostate data. The blank entries correspond to variables omitted.*

Term	LS	Best Subset	Ridge	Lasso	PCR	PLS
Intercept	2.480	2.495	2.467	2.477	2.513	2.452
lcavol	0.680	0.740	0.389	0.545	0.544	0.440
lweight	0.305	0.367	0.238	0.237	0.337	0.351
age	-0.141		-0.029		-0.152	-0.017
lbph	0.210		0.159	0.098	0.213	0.248
svi	0.305		0.217	0.165	0.315	0.252
lcp	-0.288		0.026		-0.053	0.078
gleason	-0.021		0.042		0.230	0.003
pgg45	0.267		0.123	0.059	-0.053	0.080
Test Error	0.586	0.574	0.540	0.491	0.527	0.636
Std. Error	0.184	0.156	0.168	0.152	0.122	0.172