Distributed Snapshots

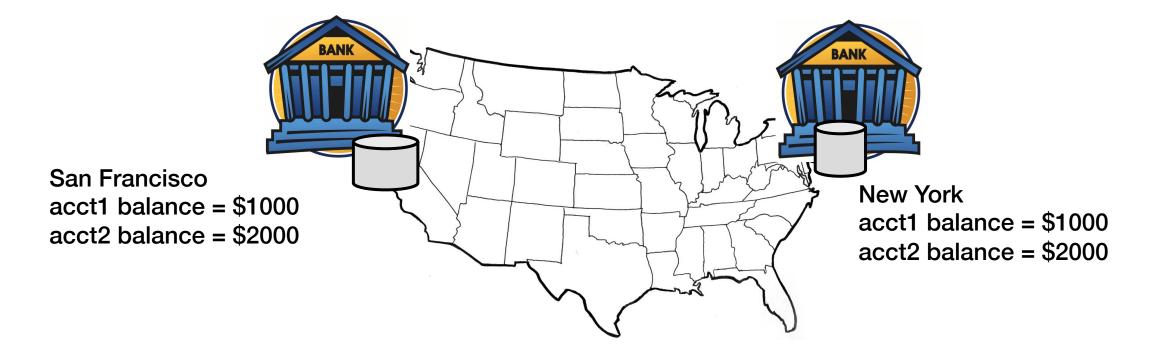


COS 418/518: Distributed Systems Lecture 7

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Distributed Snapshots

• What is the state of a distributed system?



System model

- N processes in the system with no process failures
 - Each process has some state it keeps track of

- There are two first-in, first-out, unidirectional channels between every process pair P and Q
 - Call them channel(P, Q) and channel(Q, P)
 - The channel has state, too: the set of messages inside
 - All messages sent on channels arrive intact, unduplicated, in order

Aside: FIFO communication channel

- "All messages sent on channels arrive intact, unduplicated, in order"
- Q: Arrive?
- Q: Intact?
- Q: Unduplicated?
- Q: In order?
- TCP provides all of these when processes don't fail

Global snapshot is global state

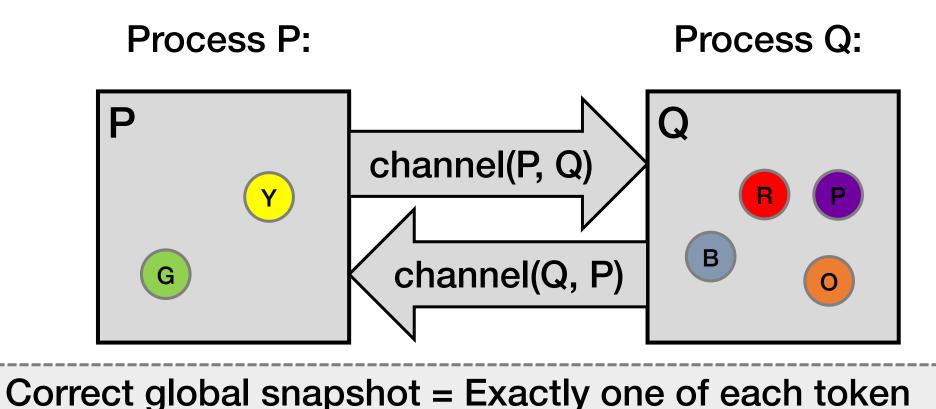
- Each distributed application has a number of processes running on a number of physical servers
- These processes communicate with each other via channels
- A global snapshot captures
 - I. The local states of each process (e.g., program variables), and
 - 2. The state of each communication channel

Why do we need snapshots?

- Checkpointing: Restart if the application fails
- Collecting garbage: Remove objects that aren't referenced
- Detecting deadlocks: The snapshot can examine the current application state
 - Process A grabs Lock 1, B grabs 2, A waits for 2, B waits for 1....

System model: Graphical example

- Let's represent process state as a set of colored tokens
- Suppose there are two processes, P and Q:



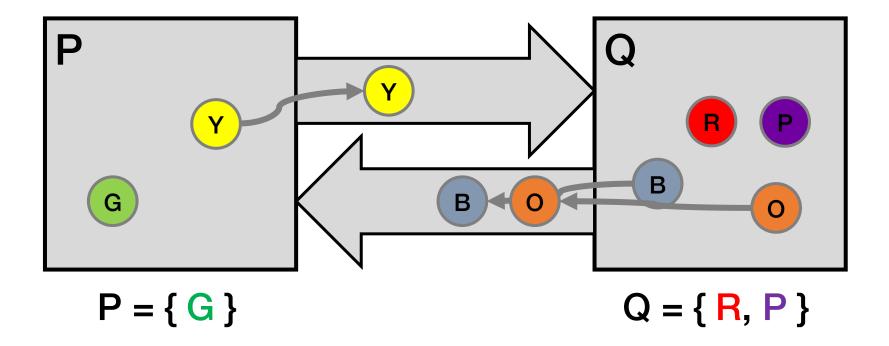
When is inconsistency possible?

- Suppose we take snapshots only from a process perspective
- Suppose snapshots happen independently at each process
- Let's look at the implications...

Problem: Disappearing tokens

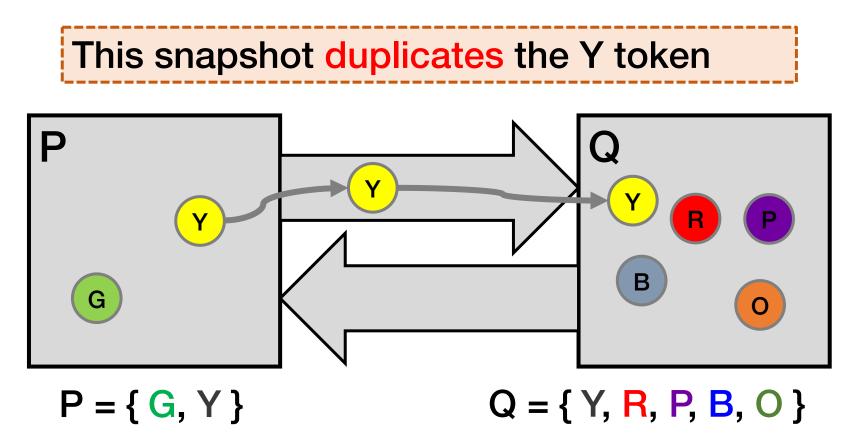
• P, Q put tokens into channels, then snapshot

This snapshot misses Y, B, and O tokens



Problem: Duplicated tokens

- P snapshots, then sends Y
- Q receives Y, then snapshots



Idea: "Marker" messages

- What went wrong?
 - We should have captured the state of the channels as well
 - Avoids missing tokens
 - We should have coordinated snapshots at different processes
 - Avoids duplicate tokens
- Let's send a marker message ▲
 - Used to capture channel state and coordinate different processes
 - Distinct from other messages
 - Channels deliver marker and other messages FIFO

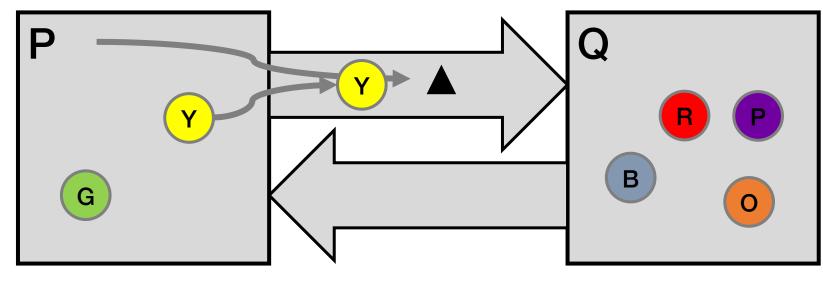
Chandy-Lamport Algorithm: Overview

- We'll designate one node (say P) to start the snapshot
 - Without any steps in between, P:
 - 1. Records its local state ("snapshots")
 - 2. Sends a marker on each outbound channel

- Nodes remember whether they have snapshotted
- On receiving a marker, a non-snapshotted node performs steps (1) and (2) above

Chandy-Lamport: Sending process

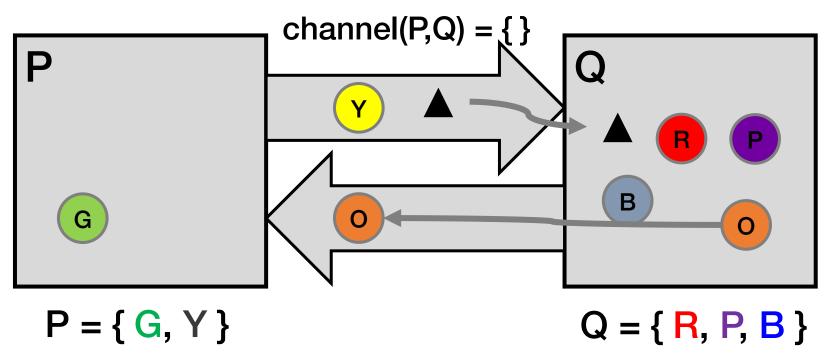
- P snapshots and sends marker, then sends Y
- Send Rule: Send marker on all outgoing channels
 - Immediately after snapshot
 - Before sending any further messages



snap: $P = \{ G, Y \}$

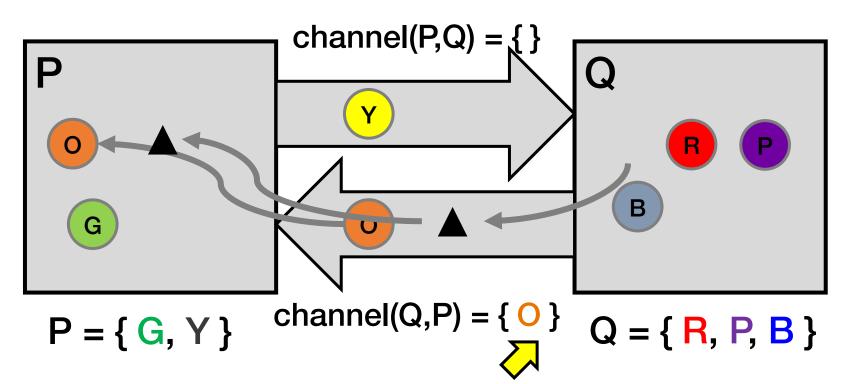
Chandy-Lamport: Receiving process (1/2)

- At the same time, Q sends orange token O
- Then, Q receives marker \blacktriangle
- Receive Rule (if not yet snapshotted)
 - On receiving marker on channel c record c's state as empty



Chandy-Lamport: Receiving process (2/2)

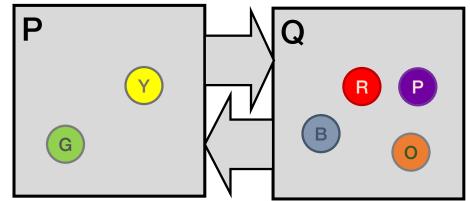
- Q sends marker to P
- P receives orange token O, then marker \blacktriangle
- Receive Rule (if already snapshotted):
 - On receiving marker on c record c's state: all msgs from c since snapshot



Chandy-Lamport Algorithm: Details

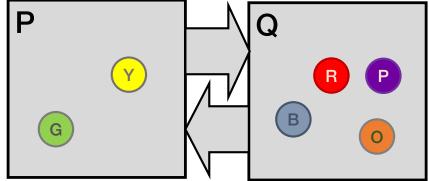
- We'll designate one node (say P) to start the snapshot
 - Without any steps in between, P:
 - 1. Records its local state ("snapshots")
 - 2. Sends a marker on each outbound channel
 - 3. Starts recording messages on each inbound channel
- Nodes remember whether they have snapshotted
- On receiving a marker on channel c
 - If (\neg snapshotted) then performs steps 1-3
 - 4. Stop recording messages on channel c

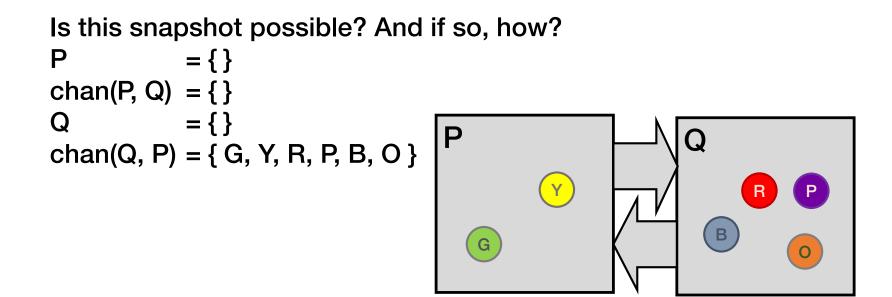
Is this snapshot possible? And if so, how? $P = \{G\},$ $chan(P, Q) = \{Y\},$ $Q = \{R, P\},$ $chan(Q, P) = \{B, O\},$ P



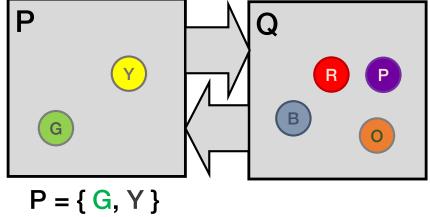
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Is this snapshot possible? And if so, how?

P = \{G, Y, R, P, B, O\}
chan(P, Q) = \{\}
Q = \{\}
chan(Q, P) = \{\}
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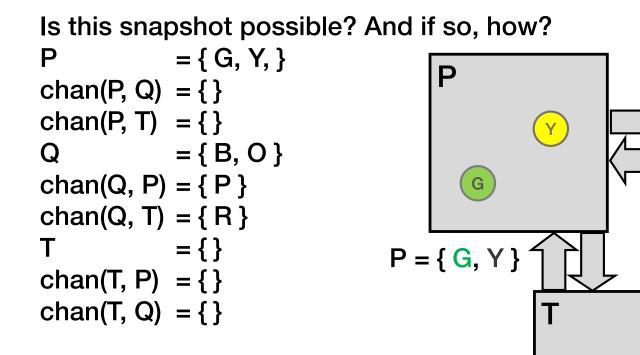




Is this snapshot possible? And if so, how? $P = \{G, Y, \}$ $chan(P, Q) = \{R\}$ $Q = \{B, O\}$ $chan(Q, P) = \{P\}$



- Is it possible (and how) if we add:
 - A process T and just a chan(T,P)?
 - T, chan(T,P) and chan (T,Q)?



(

(в)

R P

0

Is this snapshot possible? And if so, how? Ρ $= \{ G, Y, \}$ Ρ \mathbf{O} $chan(P, Q) = \{\}$ chan(P, T) = $\{\}$ (Y) R P $Q = \{B\}$ (в) $chan(Q, P) = \{P\}$ G 0 $chan(Q, T) = \{R\}$ $\mathsf{T} = \{\mathsf{O}\}$ $\mathsf{P} = \{ \mathsf{G}, \mathsf{Y} \}$ chan(T, P) = $\{\}$ chan(T, Q) = $\{\}$ $\mathsf{T} = \{ \mathsf{O} \}$

Terminating a Snapshot

- Distributed algorithm: No one process decides when it terminates
- Eventually, all processes have received a marker (and recorded their own state)
- All processes have received a marker on all the N–1 incoming channels (and recorded their states)
- Later, a central server can gather the local states to build a global snapshot

Take-away points

- Distributed Global Snapshots
 - FIFO Channels: we can do that!
 - Chandy-Lamport algorithm: use marker messages to coordinate
- Reasoning about concurrency
 - You're doing it!
 - Use trickier and trickier puzzle methodology to understand how (and if) systems really work