Consistency Models



COS 418/518: Distributed Systems Lecture 14

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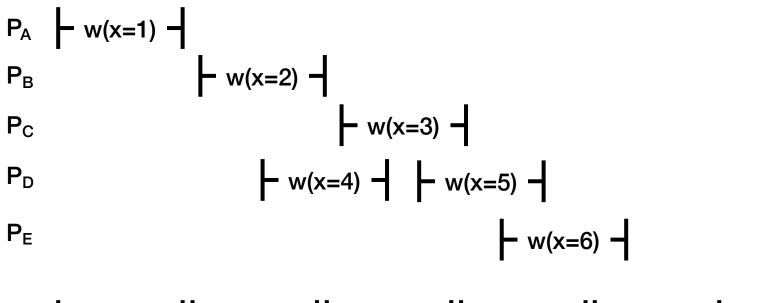
Consistency Models

- Contract between a distributed system and the applications that run on it
- A consistency model is a set of guarantees made by the distributed system

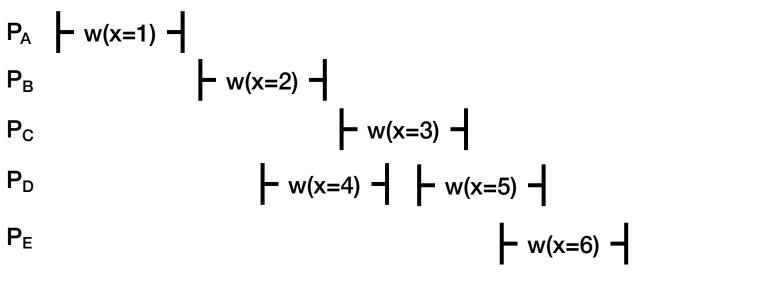
Linearizability

- All replicas execute operations in some total order
- That total order preserves the real-time ordering between operations
 - If operation A completes before operation B begins, then A is ordered before B in real-time
 - If neither A nor B completes before the other begins, then there is no real-time order
 - (But there must be *some* total order)

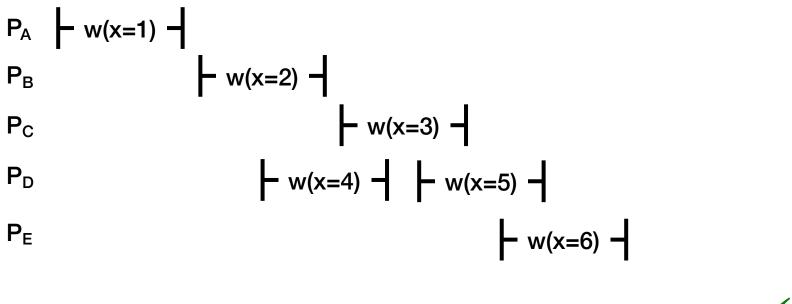
Real-Time Ordering Examples



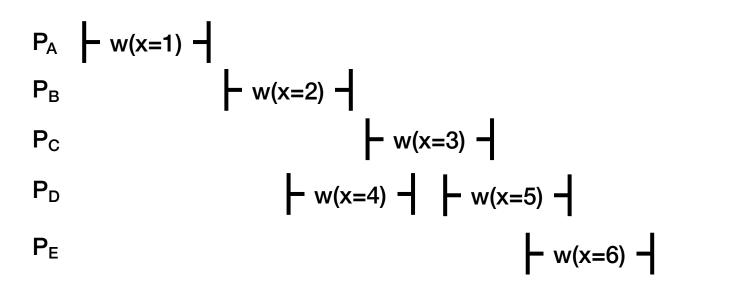
$$\mathsf{P}_{\mathsf{F}} \models \mathsf{r}(\mathsf{x})=1 \longrightarrow \mathsf{r}(\mathsf{x})=2 \longrightarrow \mathsf{r}(\mathsf{x})=3 \longrightarrow \mathsf{r}(\mathsf{x})=6 \longrightarrow \mathsf{r}(\mathsf{x})=5 \longrightarrow \mathsf{r}(\mathsf{x})=5 \longrightarrow \mathsf{r}(\mathsf{x})=1$$



$$P_{G} \models r(x)=1 \implies r(x)=2 \implies r(x)=5 \implies r(x)=6 \implies r(x)=5 \implies X$$



$$P_{H} \models r(x)=1 \implies r(x)=4 \implies r(x)=2 \implies r(x)=3 \implies r(x)=6 \implies \checkmark$$



$$P_{1} \models r(x)=1 \implies r(x)=4 \implies r(x)=5 \implies r(x)=6 \implies r(x)=3 \implies X$$

Linearizability == "Appears to be a Single Machine"

- Single machine processes requests one by one in the order it receives them
 - Will receive requests ordered by real-time in that order
 - Will receive all requests in some order
- Atomic Multicast, Viewstamped Replication, Paxos, and RAFT provide Linearizability
- Single machine processing incoming requests one at a time also provide Linearizability [©]

Linearizability is Ideal?

- Hides the complexity of the underlying distributed system from applications!
 - Easier to write applications
 - Easier to write correct applications
- But, performance trade-offs

Stronger vs Weaker Consistency

- Stronger consistency models
 - + Easier to write applications
 - More guarantees for the system to ensure Results in performance tradeoffs
- Weaker consistency models
 - Harder to write applications
 - + Fewer guarantees for the system to ensure

Strictly Stronger Consistency

- A consistency model A is strictly stronger than B if it allows a strict subset of the behaviors of B
 - Guarantees are strictly stronger

Sequential Consistency

- All replicas execute operations in some total order
- That total order preserves the process ordering between operations
 - If process P issues operation A before operation B, then A is order before B by the process order
 - If operations A and B and done by different processes then there is no process order between them
 - (But there must be *some* total order)

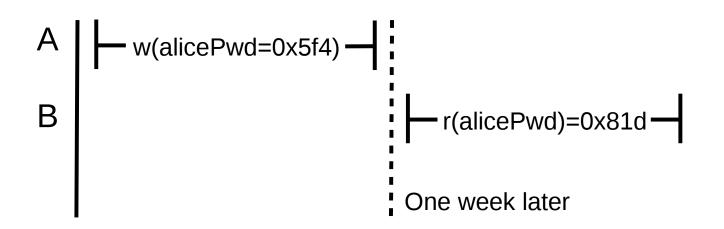
Sequential Consistency ≈ "Appears to be a Single Machine"

- Single machine processes requests one by one in the order it receives them
 - Will receive requests ordered by process order in that order
 - Will receive all requests in some order

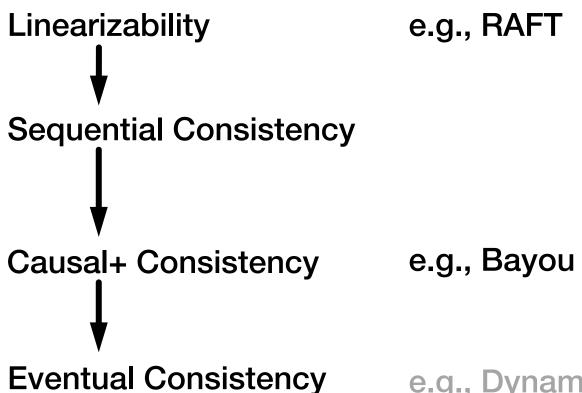
Linearizability is strictly stronger than Sequential Consistency

- Linearizability: 3total order + real-time ordering
- Sequential: ∃total order + process ordering
 - Process ordering \subseteq Real-time ordering

Sequential But Not Linearizable



Consistency Hierarchy

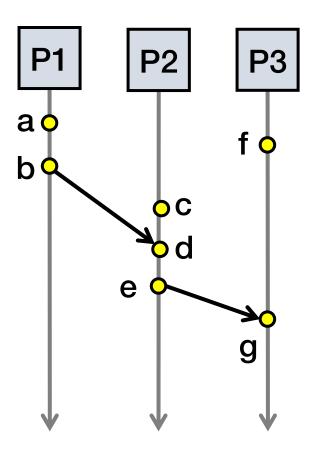


e.g., Dynamo

- Partially orders all operations, does not totally order them
 - Does not look like a single machine
- Guarantees
 - For each process, ∃ an order of all writes + that process's reads
 - Order respects the happens-before (\rightarrow) ordering of operations
 - + replicas converge to the same state
 - Skip details, makes it stronger than eventual consistency

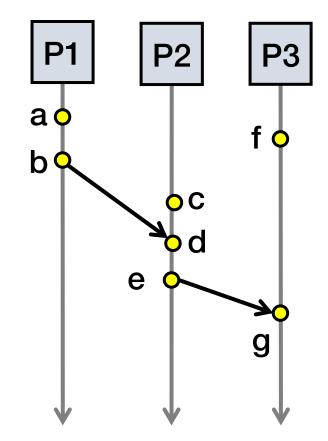
- 1. Writes that are potentially causally related must be seen by all processes in same order.
- 2. Concurrent writes may be seen in a different order on different processes.
- Concurrent: Ops not causally related

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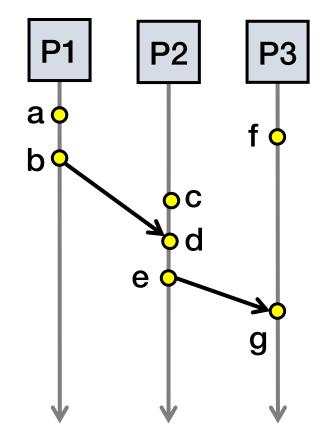
Physical time \downarrow

| Operations | Concurrent? |
|------------|-------------|
| a, b | |
| b, f | |
| c, f | |
| e, f | |
| e, g | |
| a, c | |
| a, e | |



Physical time \downarrow

| Operations | Concurrent? |
|------------|-------------|
| a, b | Ν |
| b, f | Y |
| c, f | Y |
| e, f | Υ |
| e, g | Ν |
| a, c | Y |
| a, e | Ν |



Physical time \downarrow

Causal+ But Not Sequential

$$P_{A} \models w(x=1) \dashv \models r(y)=0 \dashv$$
$$P_{B} \models w(y=1) \dashv \models r(x)=0 \dashv$$

✓ Casual+

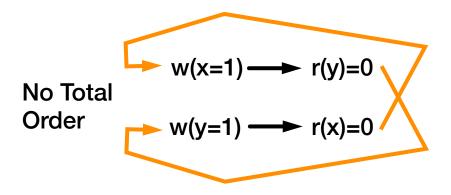
Happens $w(x=1) \longrightarrow r(y)=0$ BeforeOrder $w(y=1) \longrightarrow r(x)=0$

P_A Order: w(x=1), r(y=0), w(y=1)

P_B Order: w(y=1), r(x=0), w(x=1)

X Sequential

Process Ordering $w(x=1) \longrightarrow r(y)=0$ $w(y=1) \longrightarrow r(x)=0$



Eventual But Not Causal+

$$P_A \models w(x=1) \dashv \models w(y)=1 \dashv$$

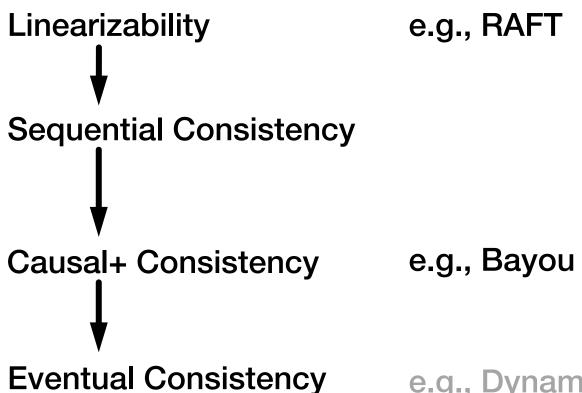
 \mathbf{P}_{B}

Eventual

As long as P_B eventually would see r(x)=1 this is fine

$$\begin{array}{c} \downarrow r(y)=1 & \downarrow r(x)=0 & \downarrow \\ \textbf{X Causal+} \\ \text{Happens Before Ordering } & w(x=1) & w(y)=1 \\ \downarrow r(y)=1 & \downarrow r(x)=0 \end{array}$$

Consistency Hierarchy



e.g., Dynamo