

Global Illumination

COS 426, Spring 2016 Princeton University

Overview



- Direct Illumination
 - Emission at light sources
 - Scattering at surfaces
- Global illumination
 - Shadows
 - Inter-object reflections
 - Rendering equation
 - Recursive ray tracing
 - More advanced ray tracing
 - Radiosity

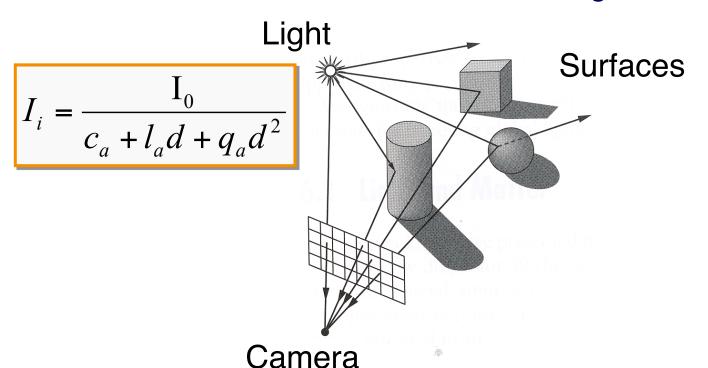


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Direct Illumination (last lecture)



- For each ray traced from camera
 - Sum radiance reflected from each light



$$I = I_E + K_A I_{AL} + \sum_i \left(K_D (N \cdot L_i) + K_S (V \cdot R_i)^n \right) I_i$$

Example





Red's Dream (Pixar Animation Studios)

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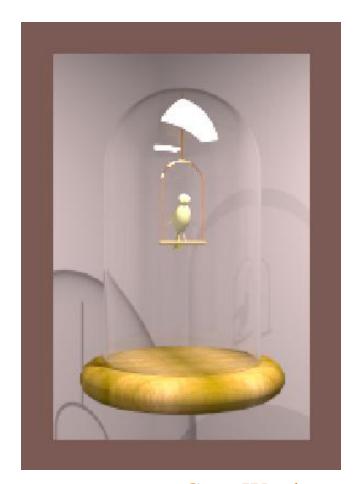


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Overview



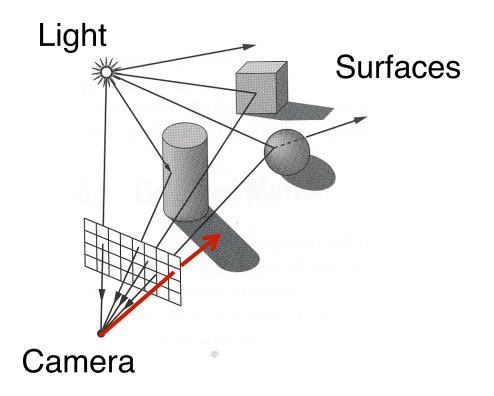
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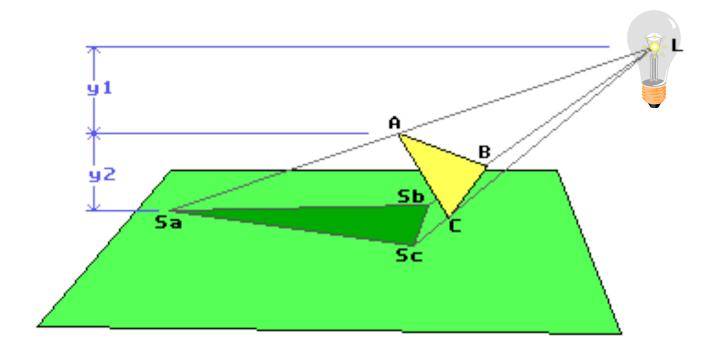


Hard shadows from point light sources



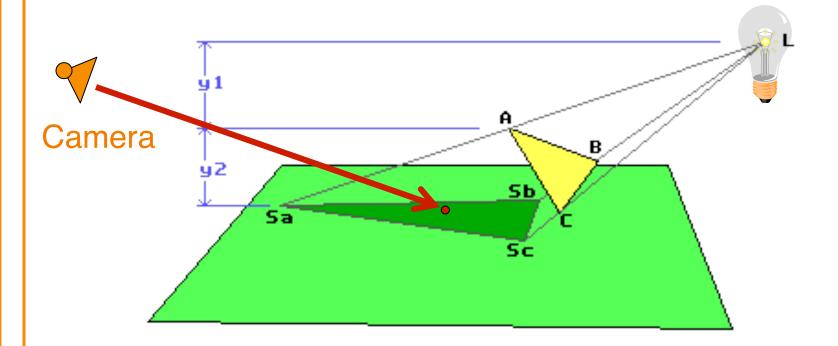


Hard shadows from point light sources



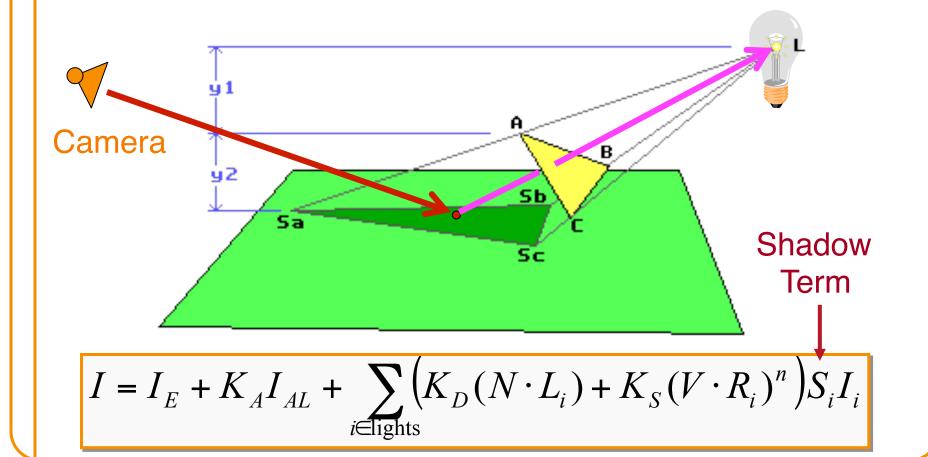


Hard shadows from point light sources



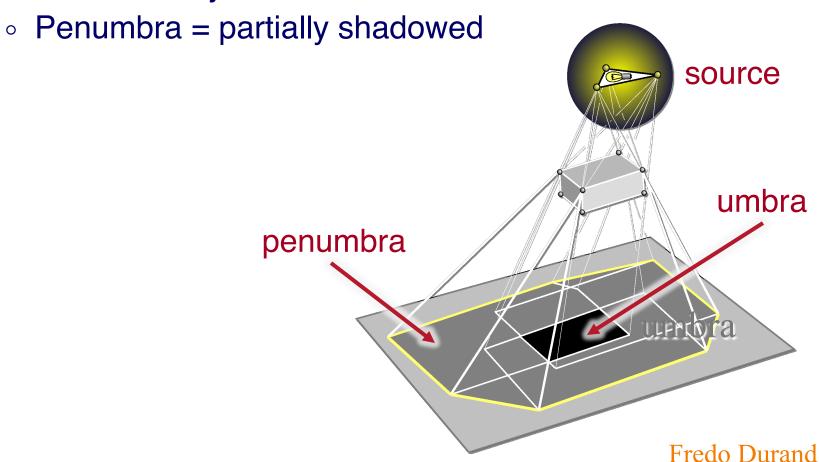


- Hard shadows from point light sources
 - Cast ray towards light; S_L=0 if blocked, S_L=1 otherwise





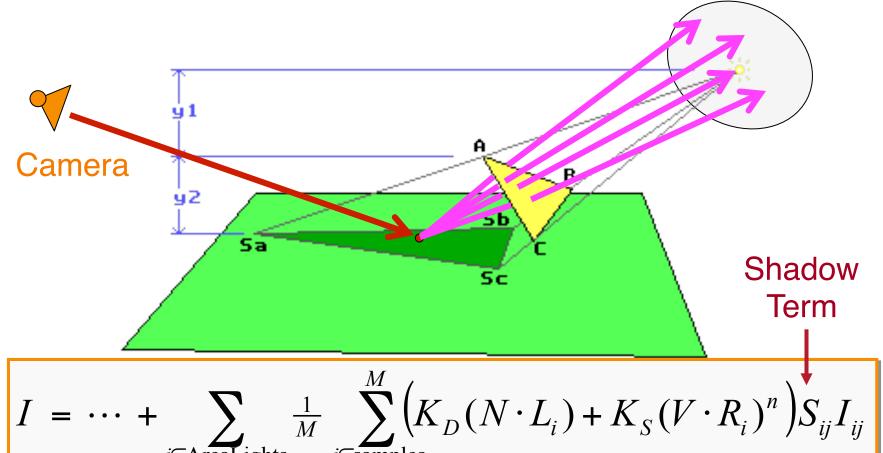
- Soft shadows from area light sources
 - Umbra = fully shadowed





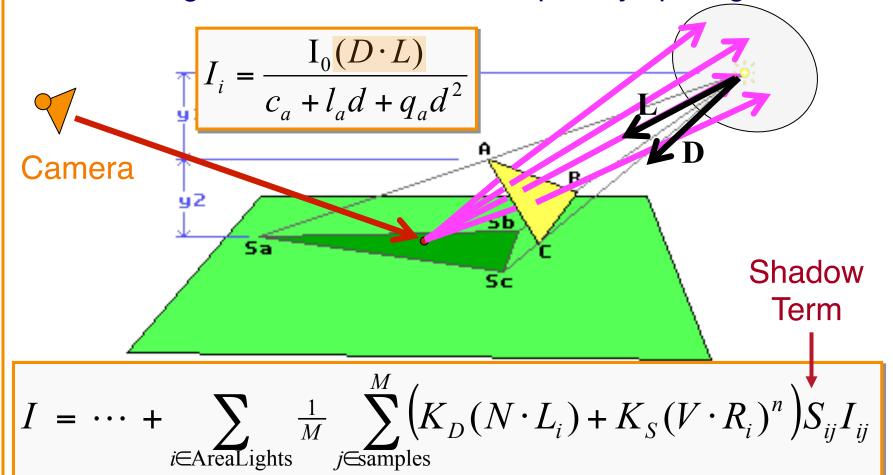
Soft shadows from area light sources





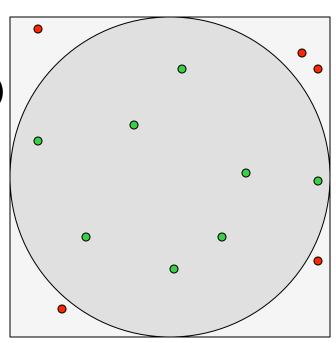


- Soft shadows from circular area light sources
 - Average illumination for M sample rays per light





- Soft shadows from circular area light sources
 - Average illumination for M sample rays per light
 - Generate M random sample points on area light (e.g., with rejection sampling)
 - Compute illumination for every sample
 - Average

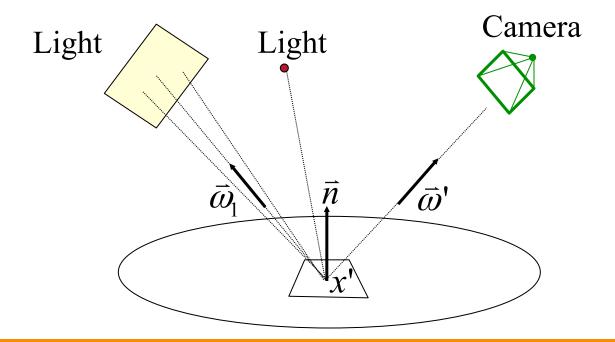


$$I = \cdots + \sum_{i \in Area Lights} \frac{1}{M} \sum_{j \in samples}^{M} \left(K_D(N \cdot L_i) + K_S(V \cdot R_i)^n \right) S_{ij} I_{ij}$$

Direct Illumination



- Illumination from polygonal area light sources
 - Average illumination for M sample rays per light

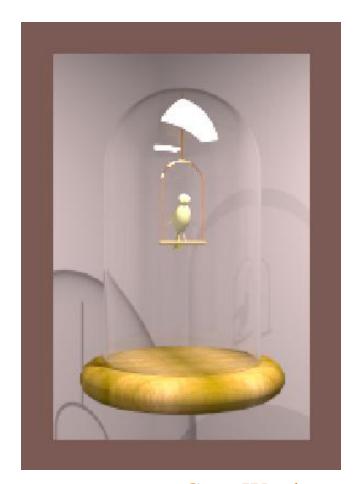


$$I = \dots + \sum_{i \in Area Lights} \frac{1}{M} \sum_{j \in samples}^{M} \left(K_D(N \cdot L_i) + K_S(V \cdot R_i)^n \right) S_{ij} I_{ij}$$

Overview



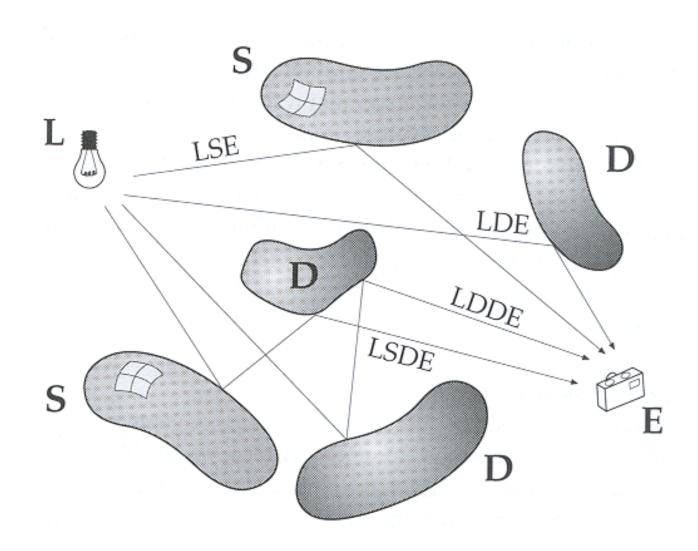
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Inter-Object Reflection

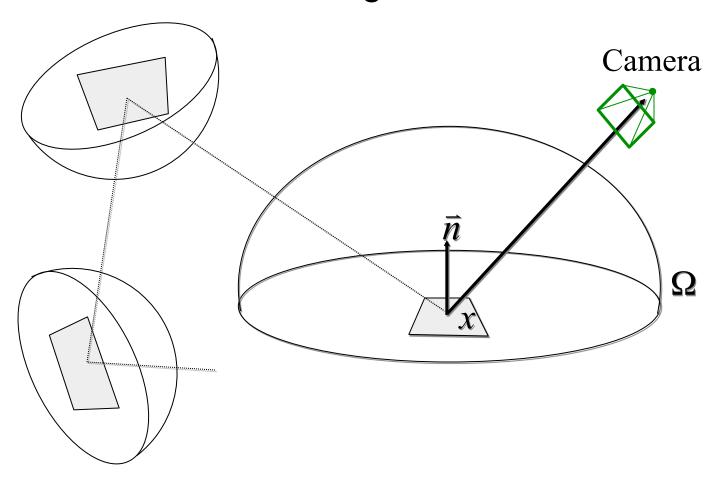




Inter-Object Reflection



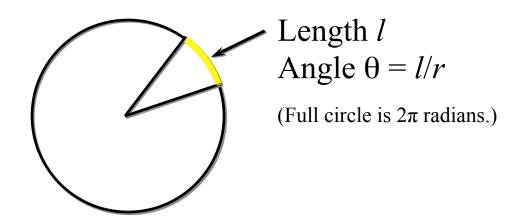
 Radiance leaving point x on surface is sum of reflected irradiance arriving from other surfaces



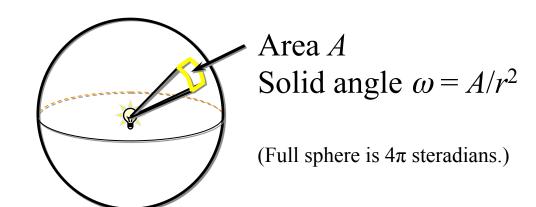
Solid Angle



Angle in radians



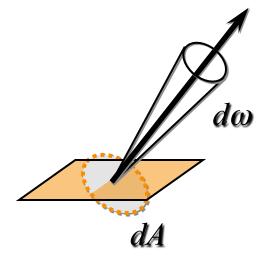
Solid angle in steradians



Light Emitted from a Surface



- Power per unit area per unit solid angle Radiance (L)
 - Measured in W/m²/sr

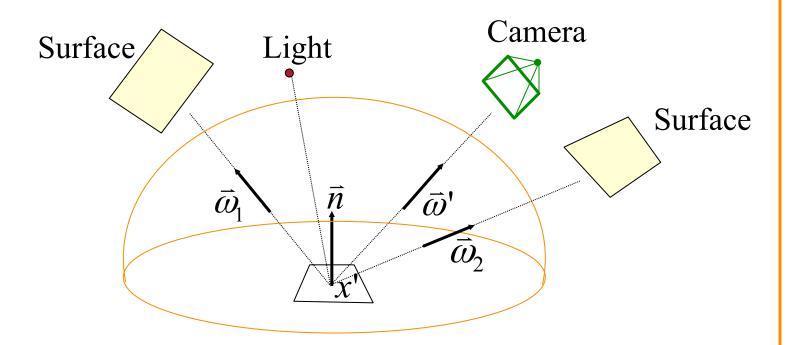


$$L = \frac{d\Phi}{dA \, d\omega}$$

Rendering Equation [Kajiya 86]



 Compute radiance in outgoing direction by integrating reflections over all incoming directions

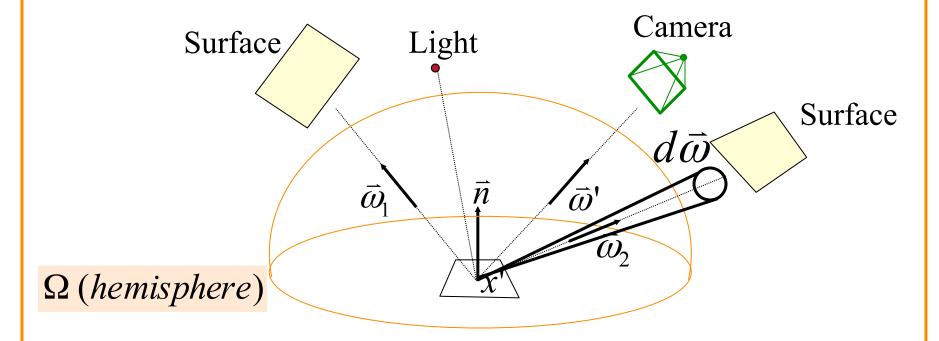


$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \int_{\Omega} f_r(x', \vec{\omega}, \vec{\omega}') (\vec{\omega} \cdot \vec{n}) L_i(x', \vec{\omega}) d\vec{\omega}$$

Rendering Equation [Kajiya 86]



 Compute radiance in outgoing direction by integrating reflections over all incoming directions



$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \int_{\Omega} f_r(x', \vec{\omega}, \vec{\omega}') (\vec{\omega} \cdot \vec{n}) L_i(x', \vec{\omega}) d\vec{\omega}$$

Overview



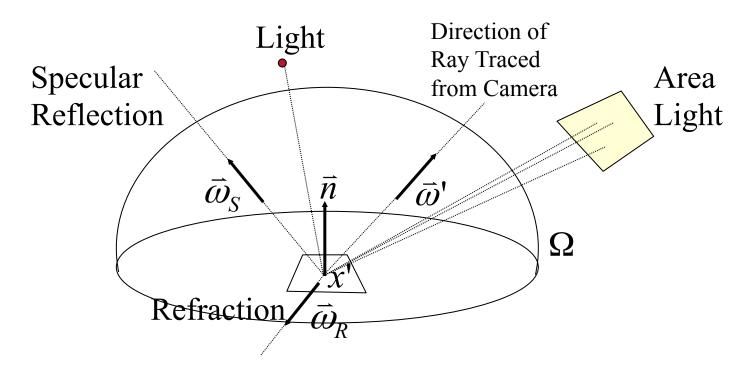
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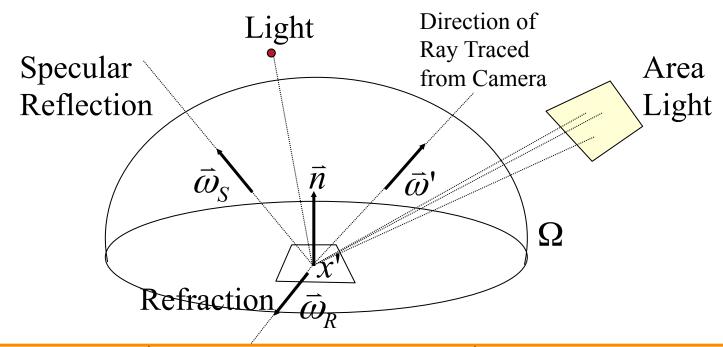
 Assume only significant irradiance is in directions of light sources, specular reflection, and refraction



$$L_o(x', \bar{\omega}') = L_e(x', \bar{\omega}') + \int_{\Omega} f_r(x', \bar{\omega}, \bar{\omega}') (\bar{\omega} \cdot \bar{n}) L_i(x', \bar{\omega}) d\bar{\omega}$$



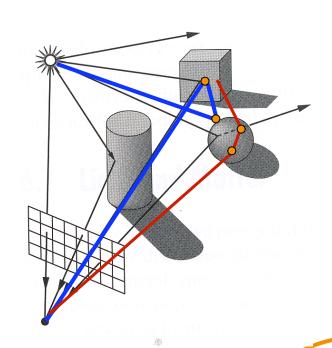
 Compute radiance in outgoing direction by summing reflections from directions of lights specular reflections, and refractions



$$I = I_E + K_A I_{AL} + \sum_{L} (K_D (N \cdot L_i) + K_S (V \cdot R_i)^n) S_L I_L + K_S I_R + K_T I_T$$



 Same as ray casting, but trace secondary rays for specular (mirror) reflection and refraction



$$I = I_E + K_A I_{AL} + \sum_{L} \left(K_D (N \cdot L_i) + K_S (V \cdot R_i)^n \right) S_L I_L + \left(K_S I_R + K_T I_T \right)^n$$

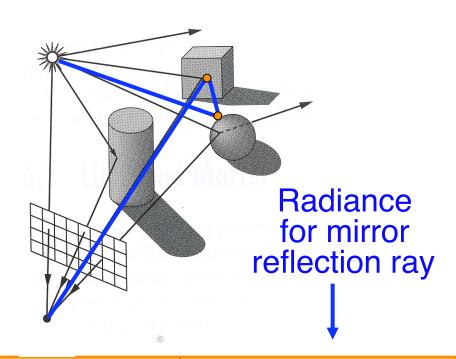
Specular Reflection



- Trace secondary ray in direction of mirror reflection
 - Evaluate radiance along secondary ray and include it into illumination model



wikimedia.org/wikipedia/en/c/c1/Cloud_Gate_(The_Bean)_from_east'.jpg



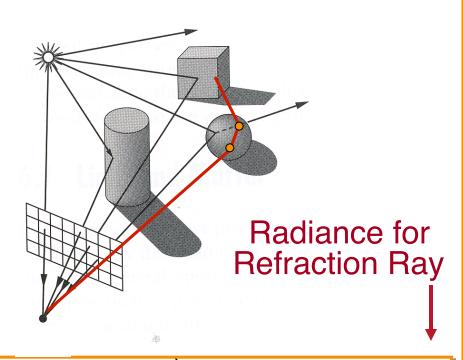
$$I = I_E + K_A I_{AL} + \sum_{L} (K_D (N \cdot L_i) + K_S (V \cdot R_i)^n) S_L I_L + K_S I_R + K_T I_T$$

Refraction



- Trace secondary ray in direction of refraction
 - Evaluate radiance along secondary ray and include it into illumination model





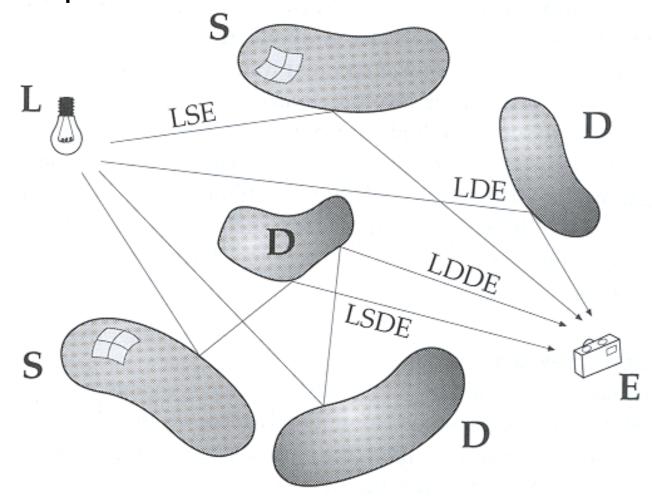
$$I = I_E + K_A I_{AL} + \sum_{I} (K_D (N \cdot L_i) + K_S (V \cdot R_i)^n) S_L I_L + K_S I_R + K_T I_T$$



ComputeRadiance is called recursively

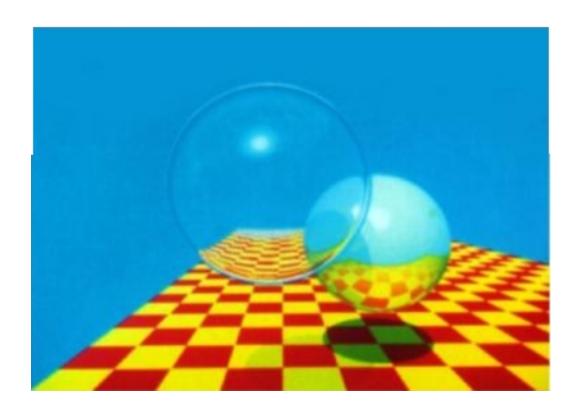


Which paths?





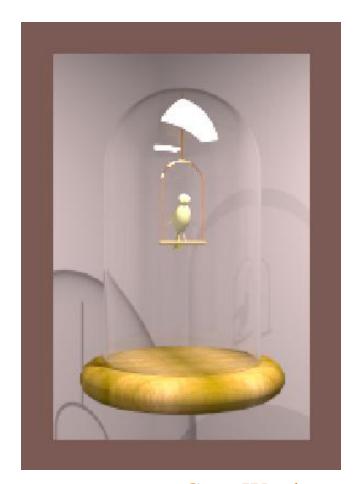
Specular reflection and refraction -- LD(SIR)*E



Overview



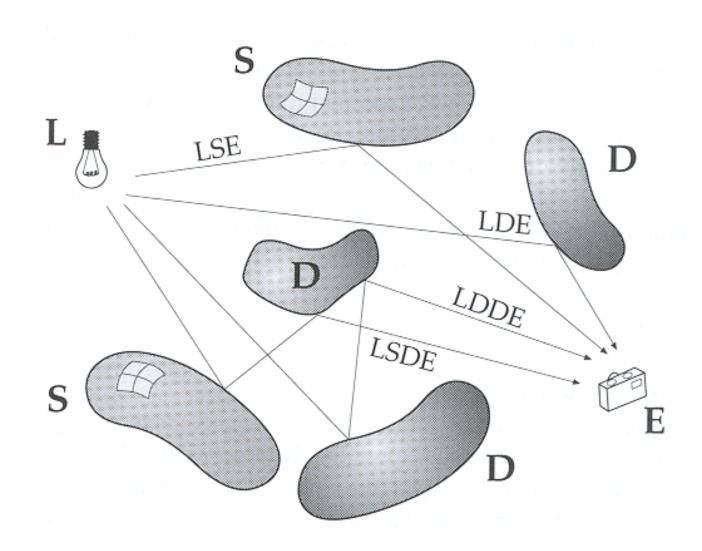
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Beyond Recursive Ray Tracing

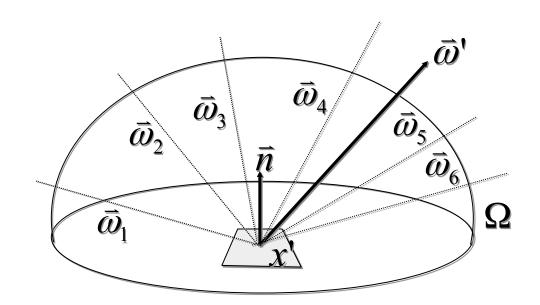




Distributed Ray Tracing



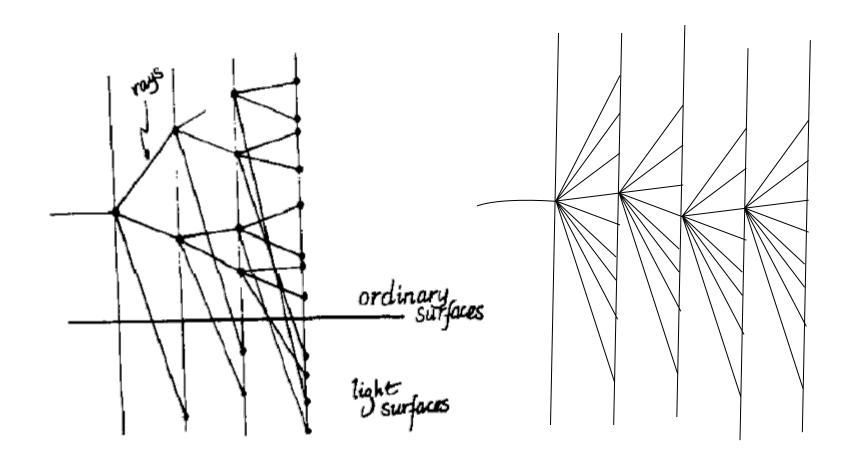
Estimate integral for each reflection by sampling incoming directions



$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \sum_{\text{samples}} f_r(x', \vec{\omega}, \vec{\omega}') (\vec{\omega} \cdot \vec{n}) L_i(x', \vec{\omega}) d\vec{\omega}$$

Ordinary Ray Tracing vs. Distribution Ray Tracing





Ray tracing

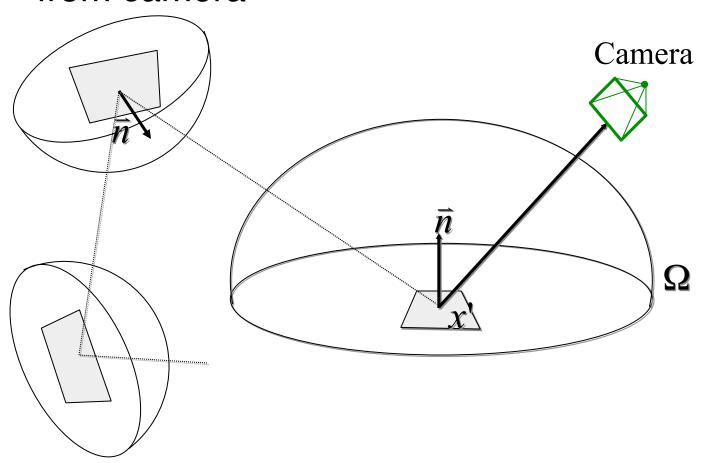
Distributed ray tracing

Kajiya

Monte Carlo Path Tracing

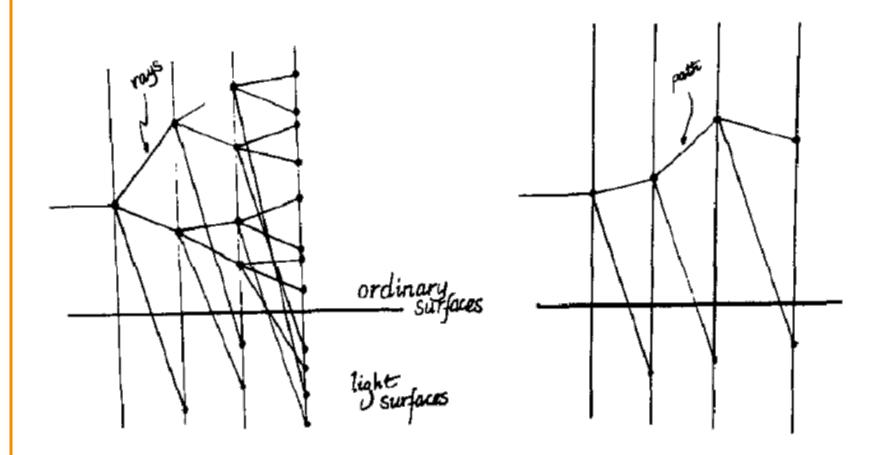


Estimate integral for each pixel by sampling paths from camera



Ray Tracing vs. Path Tracing





Ray tracing

Path tracing

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Radiosity

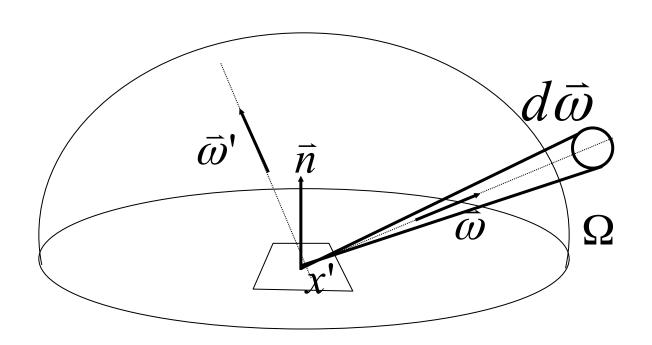


Indirect diffuse illumination – LD*E



Rendering Equation (1)

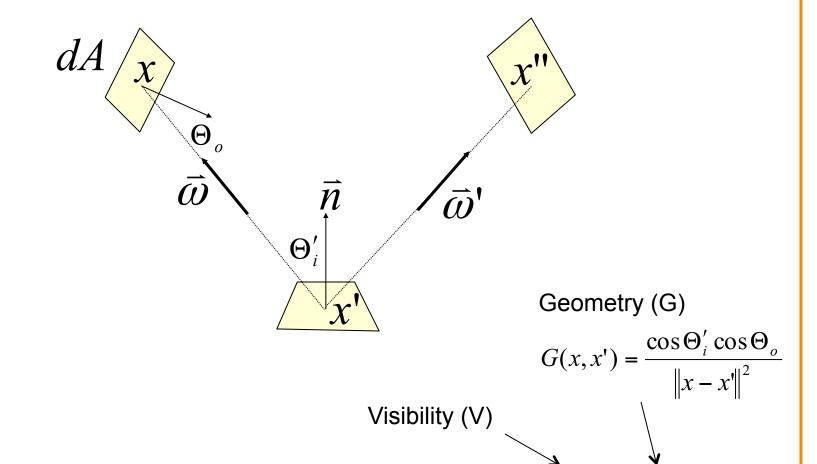




$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \int_{\Omega} f_r(x', \vec{\omega}, \vec{\omega}') (\vec{\omega} \cdot \vec{n}) L_i(x', \vec{\omega}) d\vec{\omega}$$

Rendering Equation (2)





 $L(x' \to x'') = L_e(x' \to x'') + \int f_r(x \to x' \to x'') L(x \to x') V(x, x') G(x, x') dA$

Kajiya 1986

Radiosity Equation



$$L(x' \to x'') = L_e(x' \to x'') + \int_S f_r(x \to x' \to x'') L(x \to x') V(x, x') G(x, x') dA$$

Assume everything is Lambertian

$$\rho(x') = f_r(x \to x' \to x'')\pi$$

$$L(x') = L_e(x') + \frac{\rho(x')}{\pi} \int_{S} L(x)V(x,x') G(x,x') dA$$

Convert to Radiosities

$$B = \int_{\Omega} L_o \cos \theta \, d\omega \qquad L = \frac{B}{\pi}$$

$$L = \frac{B}{\pi}$$

$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_{S} B(x) V(x, x') G(x, x') dA$$

Radiosity Approximation



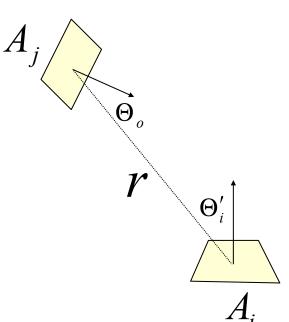
$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_S B(x) V(x, x') G(x, x') dA$$

Discretize the surfaces into "elements"

$$B_i = E_i + \rho_i \sum_{j=1}^{N} B_j F_{ij}$$

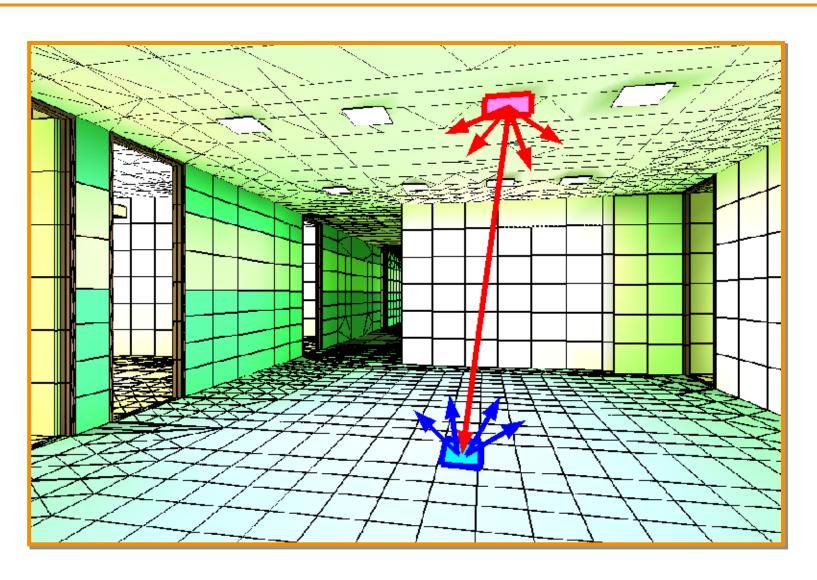
where "form factor" F is:

$$F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_i} \frac{V_{ij} \cos \Theta_i' \cos \Theta_o}{\pi r^2} dA_j dA_i$$



Radiosity Approximation





Form Factor



On the Form Factor between Two Polygons

Peter Schröder

Pat Hanrahan

Department of Computer Science Princeton University



1993

Abstract

Form factors are used in radiosity to describe the fraction of diffusely reflected light leaving one surface and arriving at another. They are a fundamental geometric property used for computation. Many special configurations admit closed form solutions. However, the important case of the form factor between two polygons in three space has had no known closed form solution. We give such a solution for the case of general (planar, convex or concave, possibly containing holes) polygons.

CR Categories and Subject Descriptors: I.3.7 [Computer Graphics]: *Three-Dimensional Graphics and Realism – Radiosity*; J.2 [Physical Sciences and Engineering]: *Engineering*.

Additional Key Words and Phrases: Closed form solution; form factor; polygons.

1 Introduction

When using the radiosity technifactor plays a central role. It

In this paper we present a formula for the form factor integral between two general polygons. The derivation of this formula is quite involved, and the interested reader is referred to [9] for a detailed derivation. The purpose of this paper is to bring this result to the attention of the graphics community.

2 Closed form solution

The form factor integral can be reduced to a double contour integral by two applications of Stokes' theorem [6]

$$\pi A_1 F_{12} = \int_{A_1} \int_{A_2} \frac{\cos \theta_1 \cos \theta_2}{\|\vec{r}\|^2} dA_2 dA_1
= \frac{1}{4} \int_{\partial A_1} \int_{\partial A_2} \ln(\vec{r} \cdot \vec{r}) d\vec{x}_2 \cdot d\vec{x}_1$$

where θ_1 , θ_2 are the angles between the normal vector of the respective surface and a radius vector \vec{r} , which connects two points on the surfaces. The above equation holds for all surfaces such

ne same contour of the

contour integral reduces

- [5] HANRAHAN, P., SALZMAN, D., AND AUPPERLE, L. A Rapid Hierarchical Radiosity Algorithm. Computer Graphics 25, 4 (July 1991), 197–206.
- [6] HERMAN, R. A. A Treatise on Geometrical Optics. Cambridge University Press, 1900.
- [7] LAMBERT. Photometria sive de mensura et gradibus luminis, colorum et umbrae. 1760. German translation by E. Anding in Ostwald's Klassiker der Exakten Wissenschaften, Vol. 31-33, Leipzig, 1892.

System of Equations



$$B_i = E_i + \rho_i \sum_{j=1}^{N} B_j F_{ij}$$

$$E_i = B_i - \rho_i \sum_{j=1}^{N} B_j F_{ij}$$

$$B_i - \rho_i \sum_{i=1}^N B_j F_{ij} = E_i$$

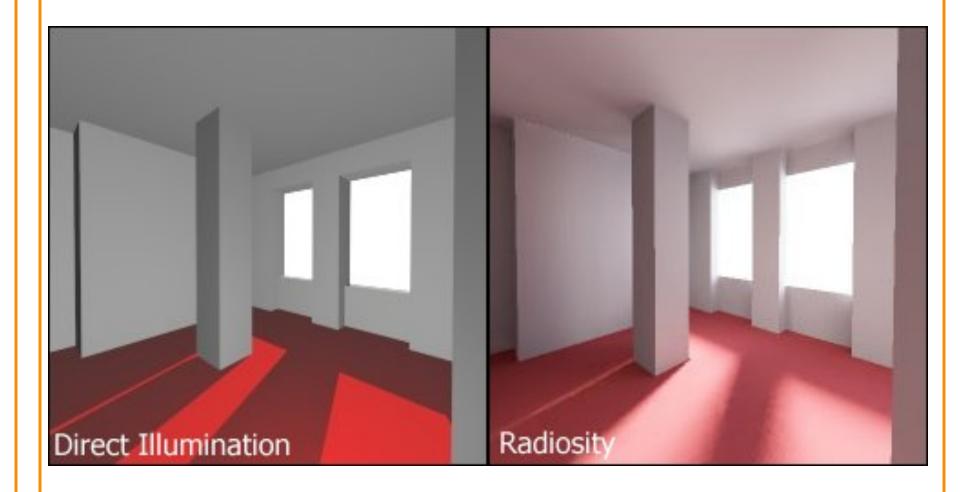
$$\begin{bmatrix} 1 - \rho_{1}F_{1,1} & . & . & . & -\rho_{1}F_{1,n} \\ -\rho_{2}F_{2,1} & 1 - \rho_{2}F_{2,2} & . & . & -\rho_{2}F_{2,n} \\ . & . & . & . & . \\ -\rho_{n-1}F_{n-1,1} & . & . & . & -\rho_{n-1}F_{n-1,n} \\ -\rho_{n}F_{n,1} & . & . & . & 1 - \rho_{n}F_{n,n} \end{bmatrix} \begin{bmatrix} B_{1} \\ B_{2} \\ . \\ . \\ B_{n} \end{bmatrix} = \begin{bmatrix} E_{1} \\ E_{2} \\ . \\ . \\ E_{n} \end{bmatrix}$$

$$\left(1 - \rho_{i} \sum_{j=1}^{N} F_{ii}\right) B_{i} - \rho_{i} \sum_{j=1}^{N} F_{ij} B_{j} = E_{i}$$

$$B_i A_i = E_i A_i + \rho_i \sum_{j=1}^{N} F_{ji} B_j A_j$$
 This is an energy balance equation

Compare with Direct Illumination





Radiosity



- Application
 - Interior lighting design
 - LD*E
- Issues
 - Computing form factors
 - Selecting basis functions for radiosities
 - Solving large linear system of equations
 - Meshing surfaces into elements
 - Rendering images



Summary



- Global illumination
 - Rendering equation
- Solution methods
 - Sampling
 - Ray tracing
 - Distributed ray tracing
 - Monte Carlo path tracing
 - Discretization
 - Radiosity

Photorealistic rendering with global illumination is an integration problem