COS 217, Fall 2023 Final Exam

This exam consists of 6 questions, and you have 120 minutes – budget your time wisely*. Do all of your work on these pages (using the back for scratch space), and give the answer in the space provided.* Note that the exams will be scanned and graded online, so *ONLY ANSWERS IN THE BOXES WILL BE GRADED.* Assume the ArmLab/Linux/C/gcc217 environment unless otherwise stated. This is a closed-book, closed-note exam, and only 1 two-sided page of notes is allowed. Please place items that you will not need out of view in your bag or under your working space at this time. Electronic devices such as cell phones, laptops, tablets, etc. may not be used during this exam.

This examination is administered under the Princeton University Honor Code. Students should sit one seat apart from each other, and refrain from talking to other students during the exam. All suspected violations of the Honor Code must be reported to honor@princeton.edu.

Write out and sign the Honor Code pledge before turning in the test:

"I pledge my honor that I have not violated the Honor Code during this examination."

Pledge, written out exactly as above:

Signature:

1. ADT vs. AO

An undirected graph is defined as a collection of nodes with edges. These edges do *not* have a direction: if node A and node B share an edge, A is a neighbor of B, and B is a neighbor of A. We want to design a module for such a graph. Assume that we can have *only one* graph in the entire program, and assume that the graph can contain *more than one* node.

(a) Would this undirected graph API be better represented as an abstract object (AO) or an abstract data type (ADT)? *Write only ADT or AO: (3 pts total for a and b)*

(b) Write a brief (a few words or a sentence) *justification* for your answer in part (a):

(c) Would a node in this undirected graph be better represented as an abstract object (AO) or an abstract data type (ADT)? *Write only ADT or AO: (3 pts total for c and d)*

(d) Write a brief (a few words or a sentence) *justification* for your answer in part (c):

(e) Assume that each node stores a unique string and can have *up to 5 neighbors*. Write the definition of a struct GraphNode to represent each node in the graph, assuming that *no storage outside of the struct* will be allocated to represent the neighbor pointers: *(3 pts)*

struct GraphNode {

};

(f) Now instead assume that each node can have an *arbitrary number of neighbors* (still together with a string label) and that storage for the neighbor pointers will be allocated on the heap. Also assume that it is a requirement of the API that the *number of neighbors* of a node be available as a *constant-time* operation. Write the definition of a struct GraphNode to represent each node in the graph, assuming these new requirements: *(3 pts)*

struct GraphNode {

2. DMM errors

Consider the following C program, with one piece of code missing:

```
#include <stdlib.h>
#include <stdio.h>
void square(int i, int **piResult)
{
   *piResult = (int *) malloc(sizeof(int));
   if (*piResult == NULL) {
       fprintf(stderr, "Insufficient memory available\n");
        return;
   }
   **piResult = i * i;
}
int main()
{
   int i = 5;
   int *piResult = NULL;int *piExtra = NULL;square(i, &piResult);
   /* INSERT CODE HERE */
   printf("%d is one plus the square of %d", *piResult, i);
    return 0;
}
```
Identify the memory management bugs (if any) that occur if the /* INSERT CODE HERE */ comment is replaced with each of the code snippets in parts a-e. *Write the letters for ALL relevant bugs in the boxes at right*, or write "None" if none of the issues are present. Consider bugs in the entire resulting program, not just the provided code snippets.

A: accesses unallocated memory **B**: accesses freed memory (dangling pointer) **C**: leaks memory (does not free allocated memory) **D**: frees unallocated memory **E**: double-frees allocated memory **None**: none of the memory management errors above are present

3. VM, Bitwhacking, and Hash Tables

The heart of a virtual memory implementation is the differentiation between virtual and physical addresses. In this question, you will write C code that translates from a virtual address to a physical address.

On AArch64, 64-bit addresses can be divided into a *48-bit page number* in the most-significant bits, and a *16-bit offset* that is identical between virtual and physical addresses. Assume that you are provided with a function virt_to_phys_page() that returns the physical page number corresponding to a given virtual page number:

size_t virt_to_phys_page(size_t virt_page);

(a) *Implement the following function*, which returns the physical address corresponding to a given virtual address, calling virt_to_phys_page() as appropriate. Assume that the virtual address passed in as virt_addr is valid and mapped-in to physical memory. *(8 pts)*

size_t virt_to_phys_addr(size_t virt_addr) {

}

Now assume that the virtual-to-physical page mappings (the "page tables") are implemented as a hash table, using the following data structure:

```
struct Binding {
  size_t virt_page, phys_page;
  struct Binding *next;
};
struct PageTable {
  struct Binding *buckets[BUCKET_COUNT];
};
struct PageTable page_table; /* Global variable */
extern size_t hash_page(size_t page); /* Hash function */
```
(b) *Implement* a version of virt_to_phys_page() that uses the page_table global variable, calling hash_page() as appropriate. *If the virtual page number is not found, return 0. (10 pts)*

size_t virt_to_phys_page(size_t virt_page) {

}

4. Memory Sections

The following questions ask you to identify the most relevant memory section, from the following list: TEXT, RODATA, DATA, BSS, STACK, HEAP. *Write the (single) section corresponding to the answer in the boxes at right.*

For some of the questions, you will need to refer to the following program:

```
#include <stdio.h>
int result;
int multiply(int left, int right)
{
     return left * right;
}
int main()
{
     const char *greetString = "Choose two numbers!\n";
     int firstNumber;
     static int secondNumber = 0;
     int (*mul)(int, int) = 8multiply;
     printf("%s", greetString);
     scanf("%d %d", &firstNumber, &secondNumber);
     result = (*mul)(firstNumber, secondNumber);
     printf("The result is: %d\n", result);
     return 0;
}
```


Memory section:

AArch64 Assembly Language Reference for Questions 5 and 6

5. Assembly Errors

A: Has no errors

For each of the following snippets of C code, analyze the corresponding AArch64 assembly and *choose the single most appropriate option* depending on whether the code: *(3 pts ea)*

B: Doesn't assemble **C**: Causes a segmentation fault or other run-time crash **D**: Doesn't segfault, but doesn't achieve the C code's intended purpose (a) C code: long volume = length $*$ width $*$ height; Assembly: // Assume that volume, length, width, and height are on the stack at // offsets 8, 16, 24, and 32, respectively. ldr x0, [sp, 16] ldr x1, [sp, 24] ldr x2, [sp, 32] mul x0, x1 $mul x0, x2$ str x0, [sp, 8] Answer (A-D): (b) C code: extern int addTwoNumbers(int, int); int sum = addTwoNumbers(200, 17); Assembly: // Assume that sum is at offset 8 on the stack. mov w1, 200 mov w2, 17 bl addTwoNumbers str w0, [sp, 8] Answer (A-D):

```
(c) C code:
      struct List {
          long value;
          struct List *next;
      };
      // linkedList is a pointer to the first node of a linked list
      // containing **at least two** nodes
      long secondNodeValue = linkedList—>next—>value
  Assembly:
      // Assume that secondNodeValue is at offset 8 on the stack.
      // Assume that linkedList is at offset 16 on the stack.
      ldr x0, [sp, 16]
      add x0, x0, 8
      ldr x0, [x0]
      ldr x0, [x0]
      str x0, [sp, 8]
  Answer (A-D):
(d) C code:
      long arr[20];
      long i = 0;
      while (i < 20) {
          arr[i] = 0;i++;
      }
  Assembly:
      // Assume that i is stored in callee-saved register x19.
      // Assume that a pointer to arr[0] is stored in register x20.
      mov x19, xzr
      loop1:
      str xzr, [x20, x19, lsl 3]
      add x19, x19, 1
      b loop1
      endloop1:
  Answer (A-D):
```
6. Bubble Sort Asm

Consider this correct C implementation of the naïve sorting algorithm BubbleSort:

```
void swap(int array[], size_t i, size_t j)
{
   int temp = array[i];array[i] = array[j];array[j] = temp;}
void bubbleInner(int array[], size_t n, size_t pass)
{
    size_t k = 0;
    while (k < n - pass - 1) {
        if (\text{array}[k] > \text{array}[k + 1])swap(array, k, k + 1);
        k++;
    }
}
void bubbleSort(int array[], size_t n)
{
    size_t pass;
    for (pass = 0; pass < n - 1; pass++)
        bubbleInner(array, n, pass);
}
```
And here is a *buggy* implementation of bubbleInner() in AArch64 assembly language:

```
1 .equ ARRAY, 8
2 .equ N, 16
3 .equ PASS, 24
4 .equ K, 32
5
6 .global bubbleInner
7 bubbleInner:
8 sub sp, sp, 48
9 str x30, [sp]
10 str x0, [sp, ARRAY]
```

```
11 str x1, [sp, N]
12 str x2, [sp, PASS]
13 str xzr, [sp, K]
14
15 inner_loop:
16 ldr x0, [sp, K]
17 ldr x1, [sp, N]
18 ldr x2, [sp, PASS]
19 sub x3, x1, x2
20 sub x3, x3, 1
21 cmp x0, x3
22 bge afterInner
23
24 add x3, x0, 1
25 ldr x4, [sp, ARRAY]
26 ldr w5, [x4, x0, lsl 3]
27 ldr w6, [x4, x3, lsl 3]
28 cmp w5, w6
29 ble afterInner
30
31 mov x1, x0
32 mov x0, x4
33 mov x2, x3
34 bl swap
35
36 afterIf:
37 ldr x2, [sp, K]
38 add x2, x2, 1
39 str x2, [sp, K]
40 bl inner_loop
41
42 afterInner:
43 ldr x30, [sp]
44 add sp, sp, 48
45 ret
```
This program has a whopping *four (4)* mistakes, each with a different characteristic.

For each of the following bugs, *write the line number(s) of the offending instruction(s).* You need not identify the bug, just the line number. *(2 pts ea)*

(a) 2 buggy instructions (with the same bug) that will cause the assembler to emit an error.

b) 1 buggy instruction that will cause bubbleSort to fail to sort many simple array examples.

(d) 1 buggy instruction that does not compromise bubbleSort's behavior as-is, but would cause the program to do the wrong thing if we chose to optimize by inlining swap and not constructing a stackframe at all.

(e) Now write an "optimized" AArch64 assembly language version of bubbleSort() using the same strategy that you used in Part 2e of A5 $(bigital addopt.s) - i.e., storing all local variables and parameters in$ *callee-saved registers* instead of on the stack. You should assume that the .equ and .req definitions at right have been included in your assembly source file. *(14 pts)*

array .req x19 n .req x20 pass .req x21 .equ oldX19, 8 .equ oldX20, 16 .equ oldX21, 24

.global bubbleSort bubbleSort:

(f) Finally, write the assembly code for the swap() function, using *exactly 5 instructions*: 4 memory accesses using *scaled register offset* memory operands, plus a return instruction (which is provided for you). *Do not* write a prolog/epilog to manage a stackframe; thus, *use only caller-saved scratch registers*. *(8 pts)*

.global swap swap: ret