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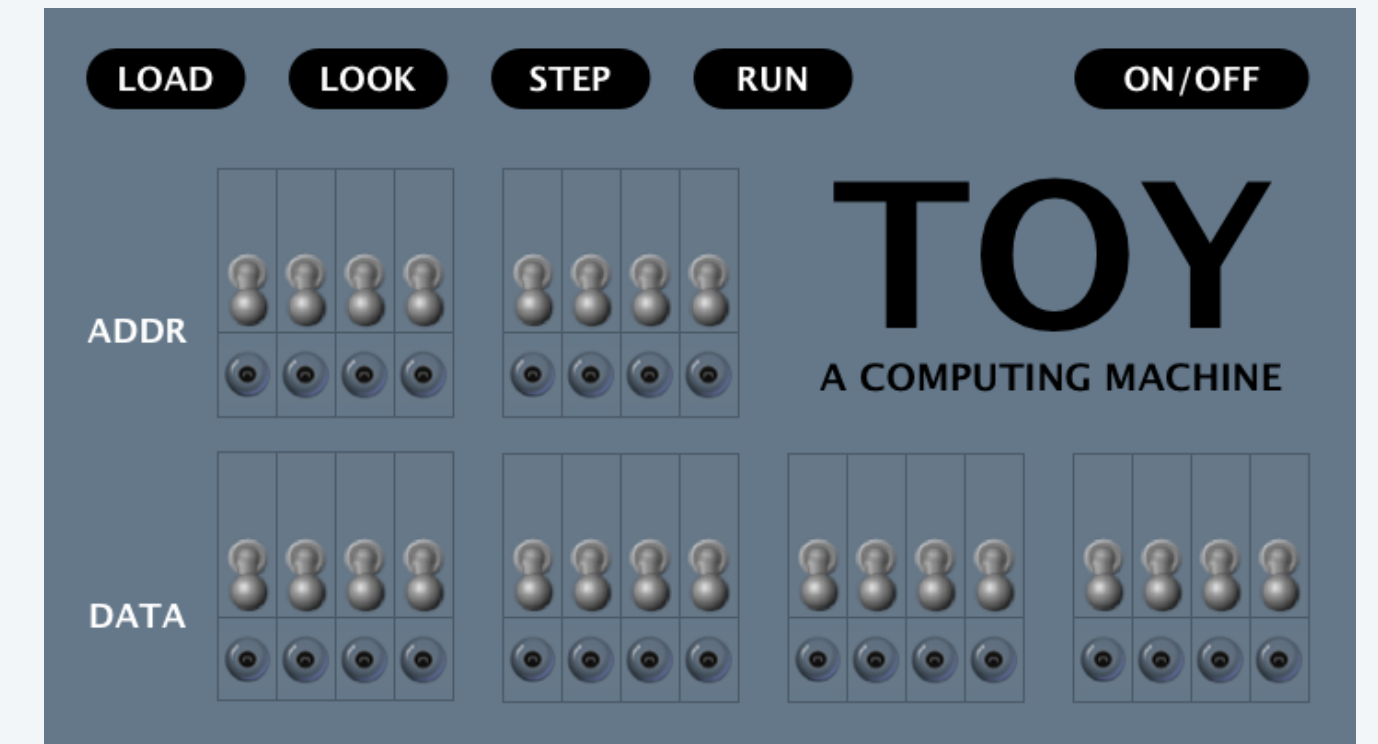
6. TOY MACHINE II

- ▶ *conditionals and loops*
- ▶ *input and output*
- ▶ *arrays*
- ▶ *von Neumann architecture*
- ▶ *TOY emulator*

Machine language programming in TOY

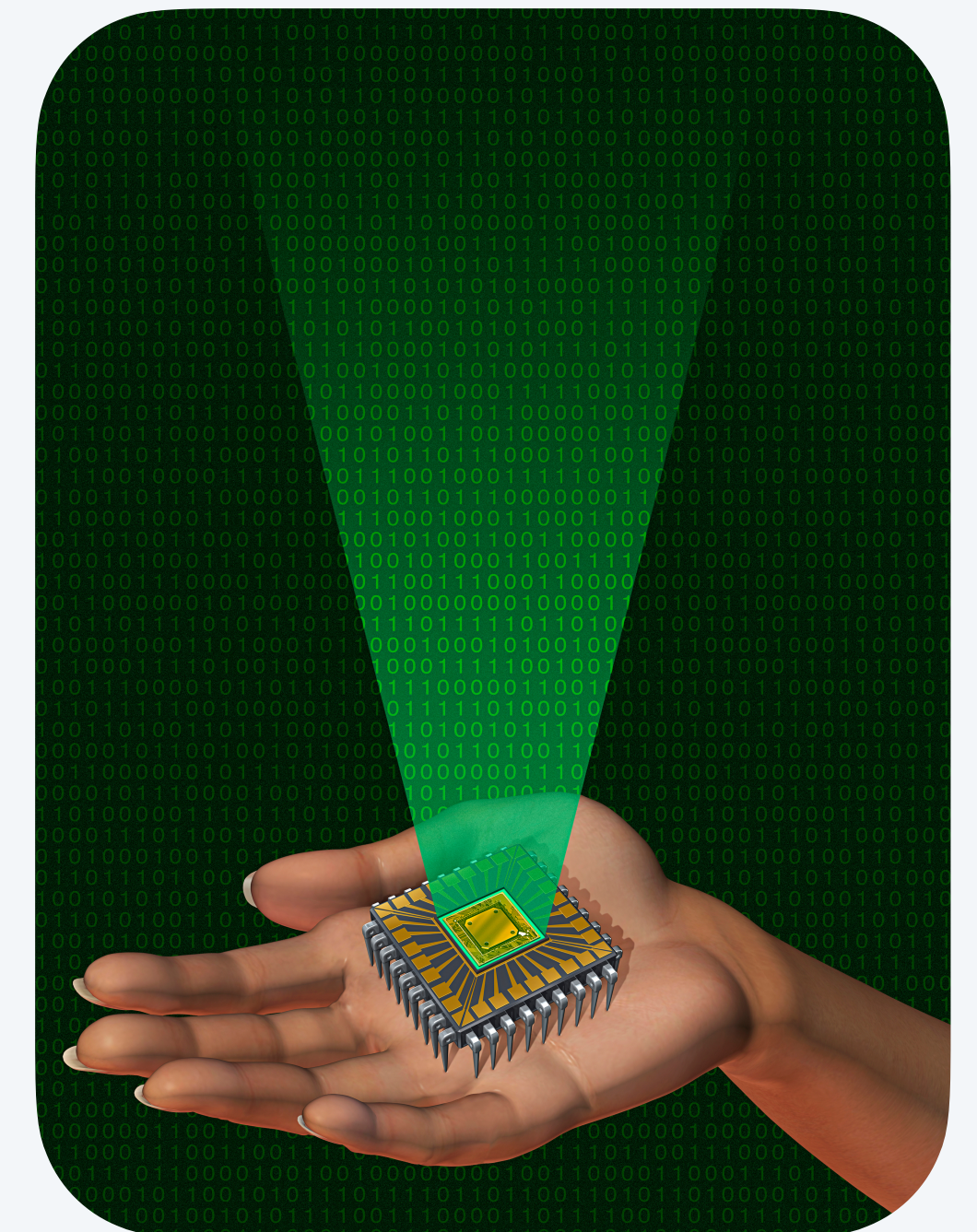
TOY machine.

- Arithmetic logic unit (ALU).
- Memory and registers.
- Program counter (PC) and instruction register (IR).
- Lights and switches.



TOY programming.

- Move data between memory and registers. | ← *last lecture*
- Arithmetic/logic operations.
- Conditionals and loops. | ← *this lecture*
- Arrays.
- Standard input and output.
- Functions. | ← *see textbook*
- Linked structures. | ← *see textbook*



Review: your first TOY program



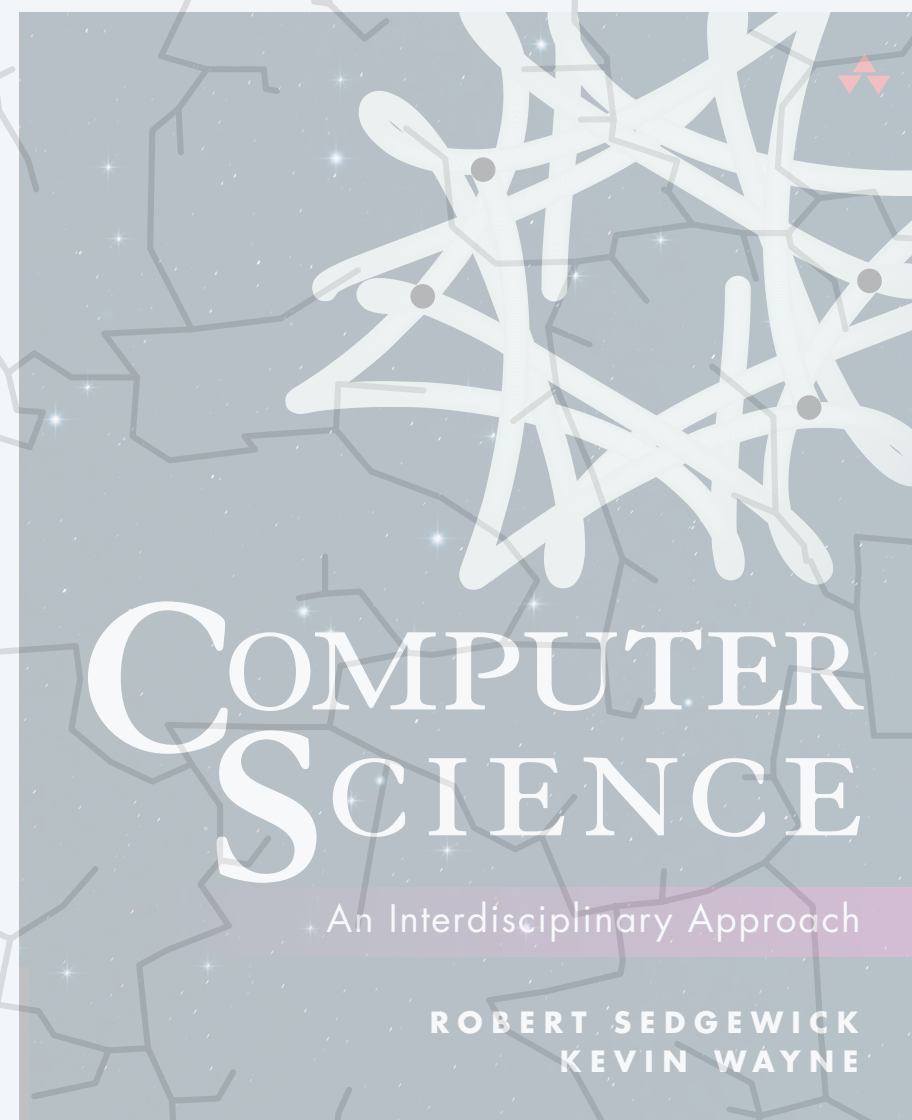
Add two integers.

- Load operands from memory into two registers.
- Add the two registers.
- Store the result in memory.

MEMORY		
⋮	⋮	
10:	8A15	R[A] = M[15]
11:	8B16	R[B] = M[16]
12:	1CAB	R[C] = R[A] + R[B]
13:	9C17	M[17] = R[C]
14:	0000	halt
15:	0008	input 1
16:	0005	input 2
17:	0000	output
⋮	⋮	

REGISTERS	
⋮	⋮
R[A]	0 0 0 0
R[B]	0 0 0 0
R[C]	0 0 0 0
⋮	⋮

PC
10



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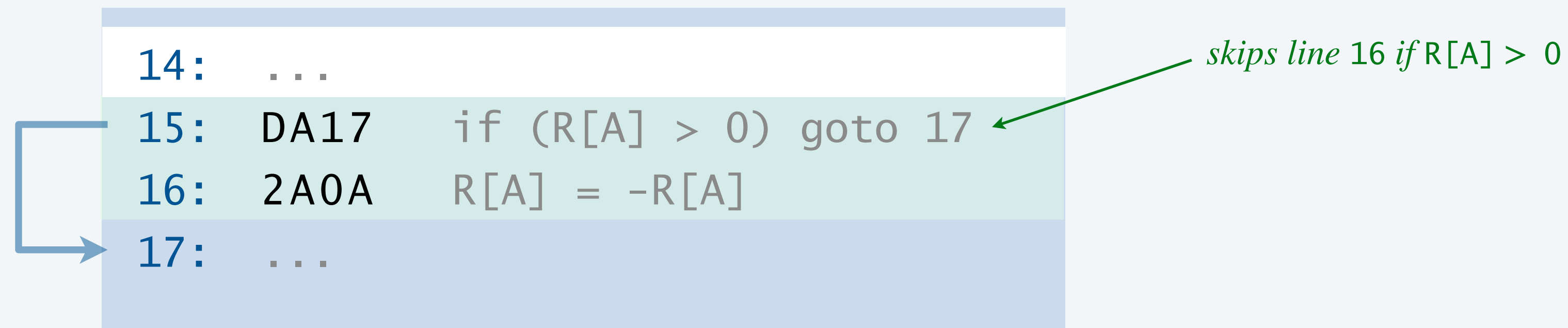
Conditionals and loops

To control the flow of instruction execution.

- Test a register's value.
- Change the PC, depending on the value.

opcode	instruction	pseudocode
C	<i>branch if zero</i>	if (R[d] == 0) PC = addr
D	<i>branch if positive</i>	if (R[d] > 0) PC = addr

Ex 1. Typical **if** statement.



replace R[A] with absolute value of R[A]

```
if (a <= 0) {
    a = -a;
}
```

replace a with |a|

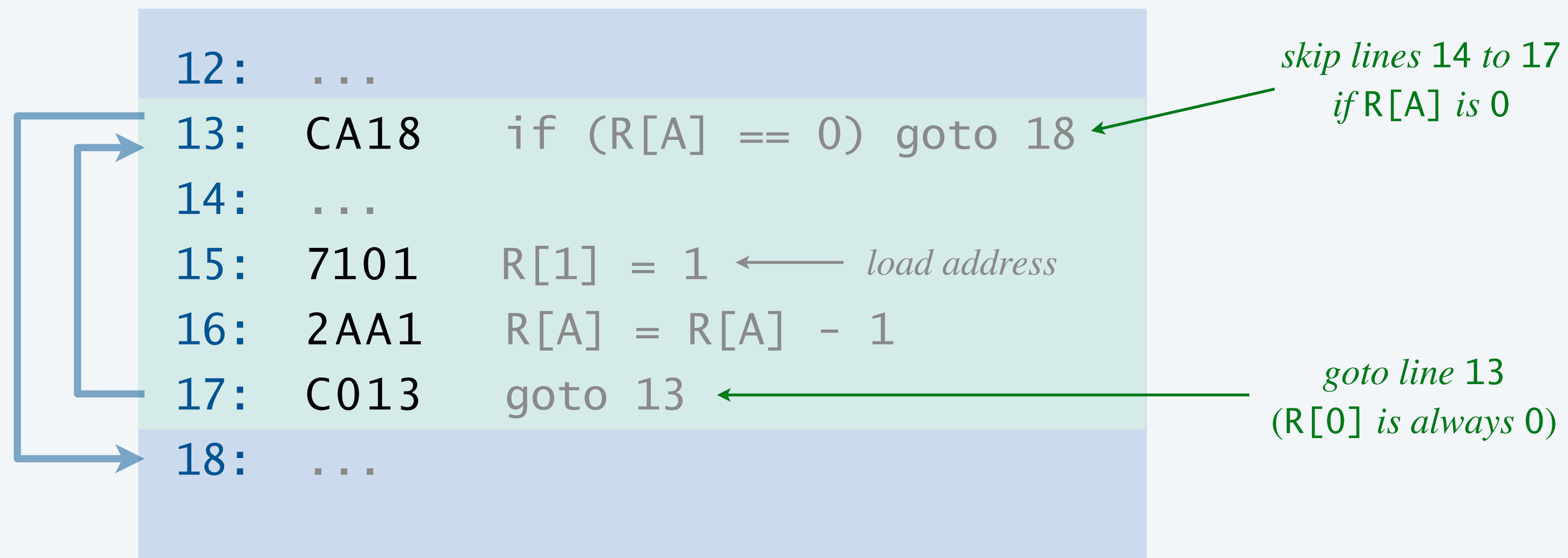
Conditionals and loops

To control the flow of instruction execution

- Test a register's value.
- Change the PC, depending on the value.

opcode	instruction	pseudocode
C	<i>branch if zero</i>	if (R[d] == 0) PC = addr
D	<i>branch if positive</i>	if (R[d] > 0) PC = addr

Ex 2. Typical `while` loop.



line 14 is repeated R[A] times
(assuming R[A] is non-negative)

```
while (a != 0) {  
    ...  
    a--;  
}
```

repeat a times

Multiplication

Goal. Compute product of two positive integers: $c = a \times b$.

Algorithm. Initialize $c = 0$; then, add b to c , a times.

opcode	instruction	pseudocode
C	<i>branch if zero</i>	if (R[d] == 0) PC = addr
D	<i>branch if positive</i>	if (R[d] > 0) PC = addr

10:	8A1A	R[A] = M[1A]
11:	8B1B	R[B] = M[1B]
12:	7C00	R[C] = 0
13:	CA18	if (R[A] == 0) goto 18
14:	1CCB	R[C] = R[C] + R[B]
15:	7101	R[1] = 1
16:	2AA1	R[A] = R[A] - 1
17:	C013	goto 13
18:	9C1A	M[1C] = R[C]
19:	0000	halt
1A:	0007	input a
1B:	0009	input b
1C:	0000	output c = a * b

*loop template
from previous slide*

```
int c = 0;
while (a != 0) {
    c = c + b;
    a--;
}
```

**multiplication: $c = a \times b$
(via repeated addition)**

input and output



Upon termination, which value is stored in R[A] ?

- A. 0000
- B. 7FFF
- C. FFFF
- D. Infinite loop

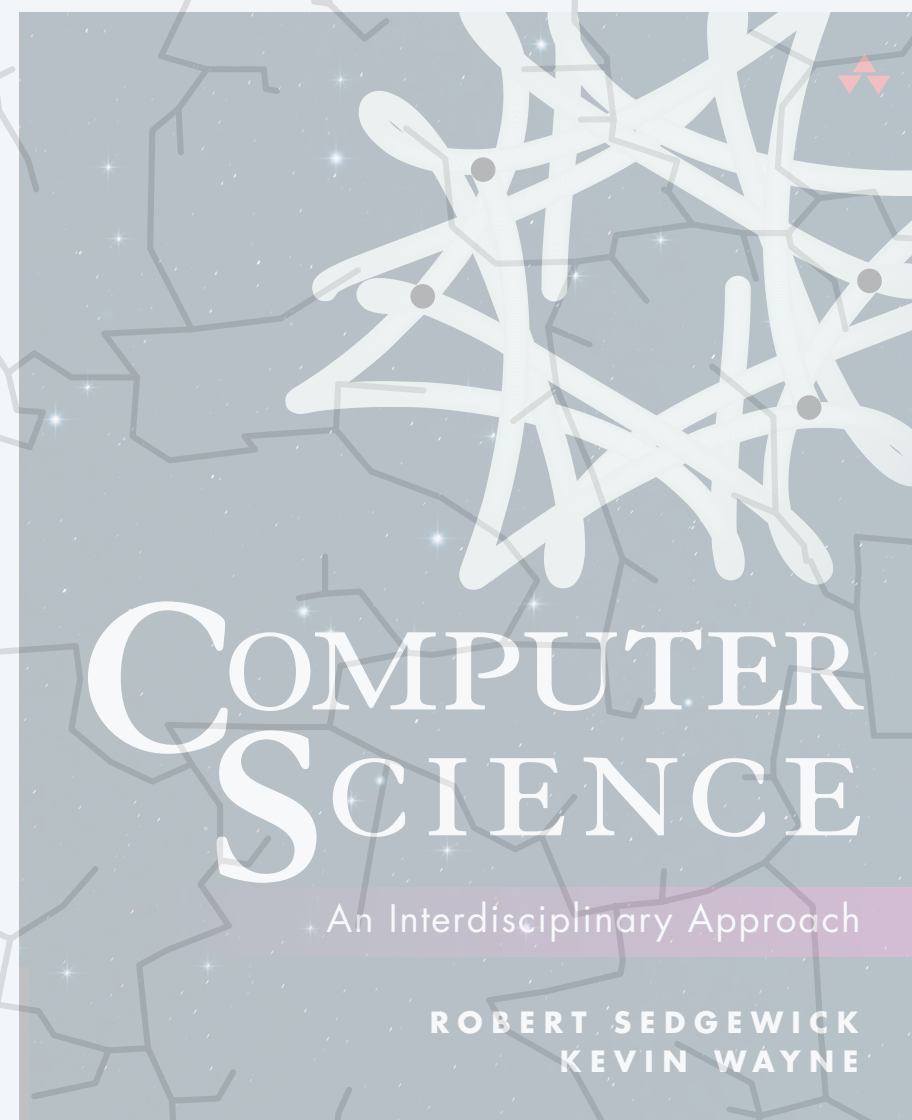
10:	7A00	R[A] = 0	
11:	7101	R[1] = 1	← R[1] is always 1
12:	1AA1	R[A] = R[A] + 1	
13:	C012	goto 12	← R[0] is always 0
14:	0000	halt	



Upon termination, which value is stored in R[B] ?

- A. 0000
- B. 0010
- C. 0016
- D. 1020
- E. 8000

10:	7101	R[1] = 1
11:	7A04	R[A] = 4 ₁₀
12:	7B01	R[B] = 1
13:	2AA1	R[A] = R[A] - 1
14:	1BBB	R[B] = R[B] + R[B]
15:	DA13	if (R[A] > 0) goto 13
16:	0000	halt



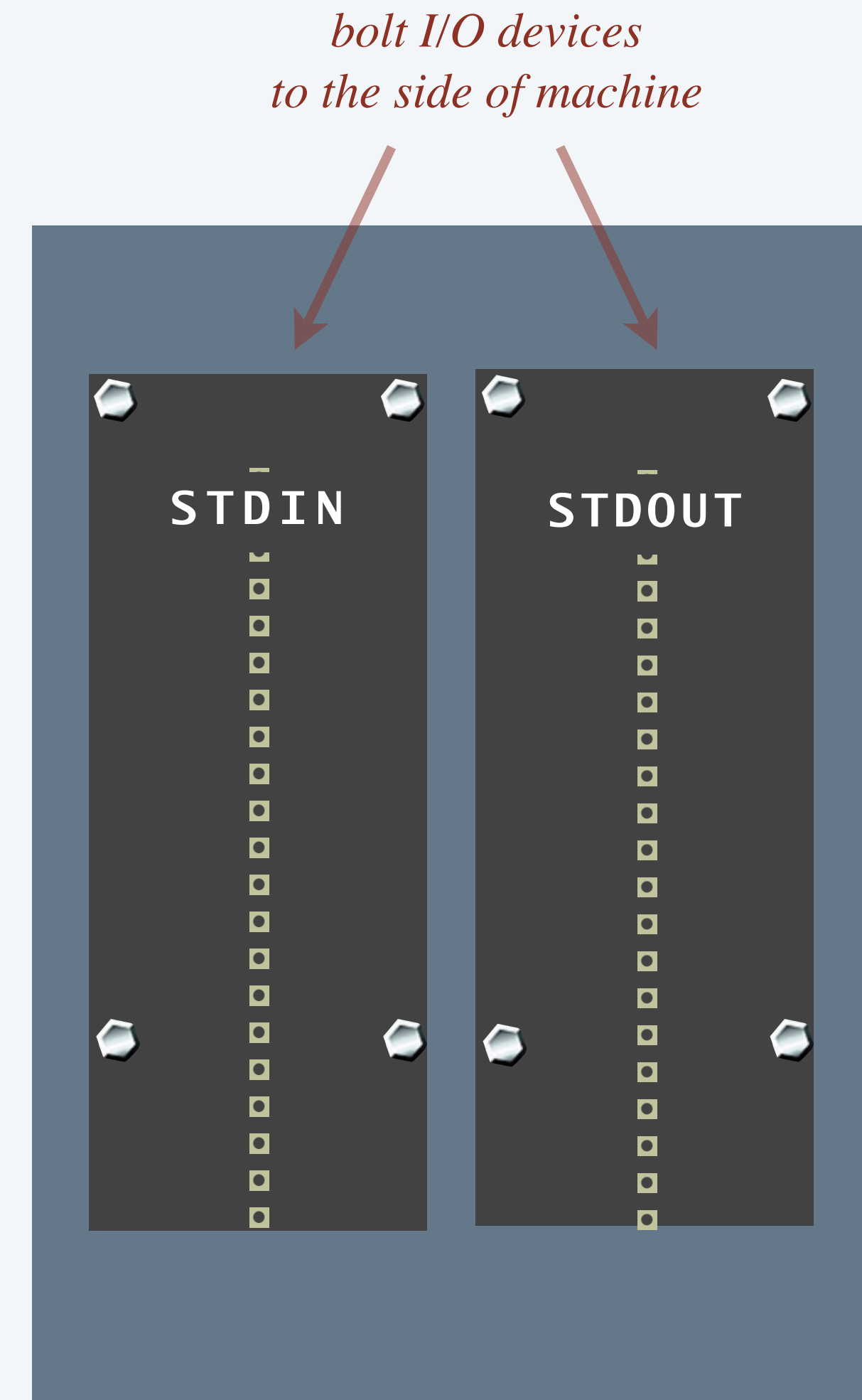
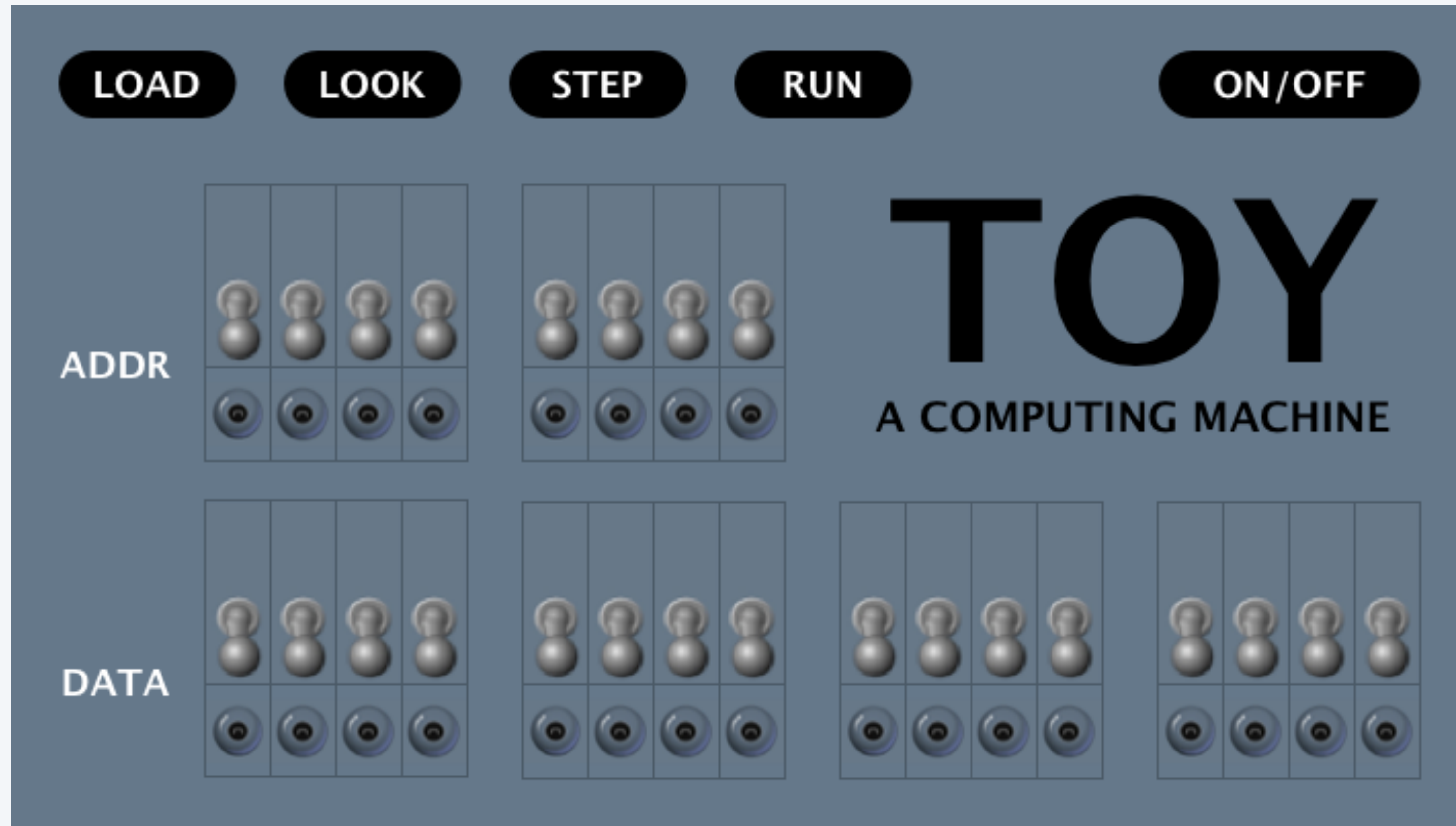
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6. TOY MACHINE II

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Standard input and output

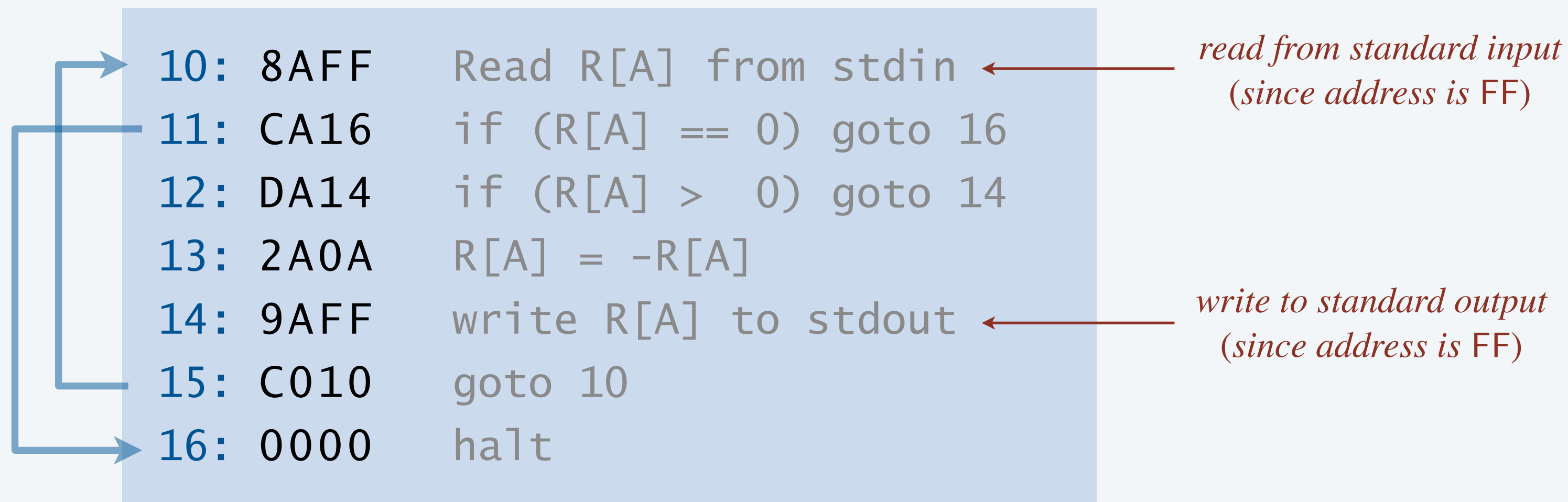
An immediate problem. Can't address real-world problems with just switches and lights for I/O.



Standard input and output: absolute value

Goal. Read integers from standard input (stop on 0000);
write absolute value to standard output.

opcode	operation	pseudocode
8	<i>load</i>	R[d] = M[addr]
9	<i>store</i>	M[addr] = R[d]



```
while (true) {  
    a = StdIn.readInt();  
    if (a == 0) break;  
    if (a <= 0) a = -a;  
    StdOut.println(a);  
}
```

Standard input and output trace

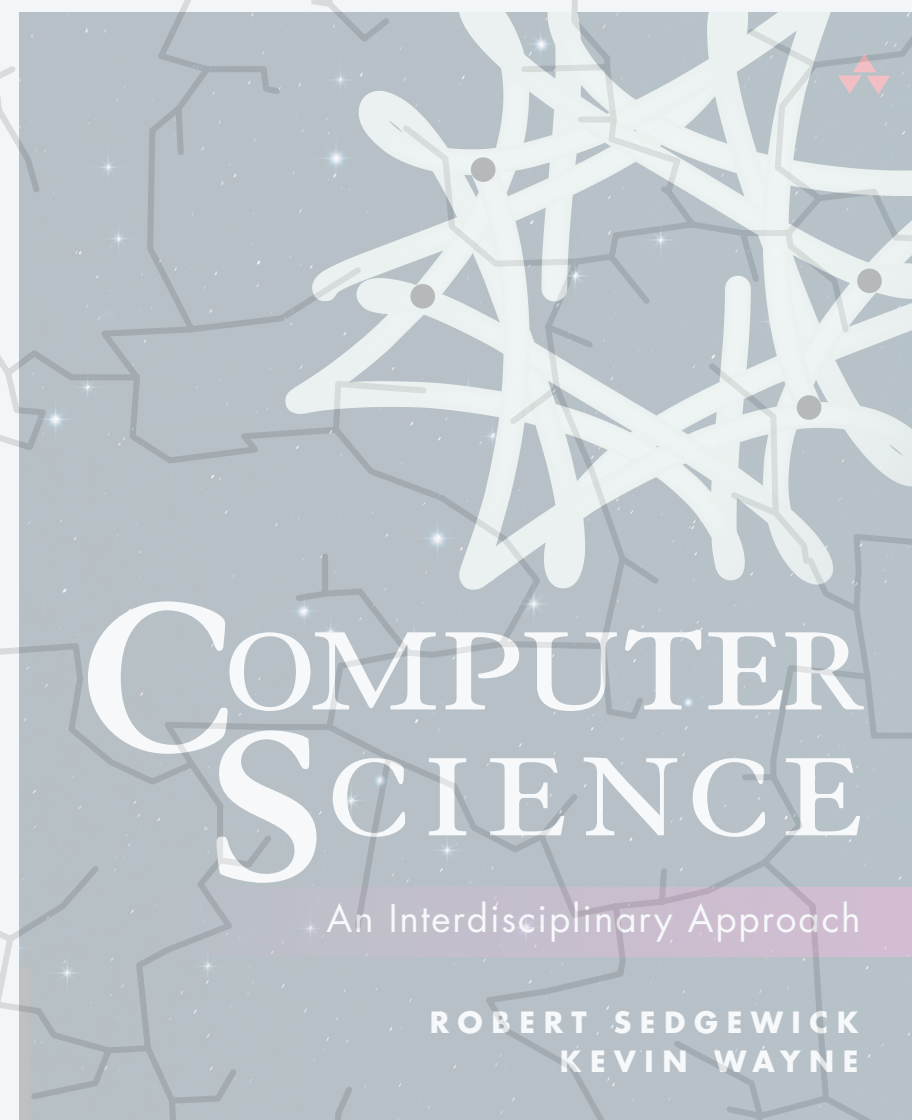


Goal. Read integers from standard input (stop on 0000);
write absolute value to standard output.

```
10: 8AFF  Read R[A] from stdin
11: CA16  if (R[A] == 0) goto 16
12: DA14  if (R[A] > 0) goto 14
13: 2A0A  R[A] = -R[A]
14: 9AFF  write R[A] to stdout
15: C010  goto 10
16: 0000  halt
```

STDIN	
○ ○ ○ ○ . ○ ○ ○ ○	1
○ ○ ○ ○ . ○ ○ ○ ●	
○ ○ ○ ○ . ○ ○ ○ ○	2
○ ○ ○ ○ . ○ ○ ● ○	
○ ○ ○ ○ . ○ ○ ○ ○	6
○ ○ ○ ○ . ○ ● ● ○	
● ● ● ● . ● ● ● ●	-1
● ● ● ● . ● ● ● ●	
○ ○ ○ ○ . ○ ○ ○ ○	0
○ ○ ○ ○ . ○ ○ ○ ○	

STDOUT	
○ ○ ○ ○ . ○ ○ ○ ○	1
○ ○ ○ ○ . ○ ○ ○ ●	
○ ○ ○ ○ . ○ ○ ○ ○	2
○ ○ ○ ○ . ○ ○ ● ○	
○ ○ ○ ○ . ○ ○ ○ ○	6
○ ○ ○ ○ . ○ ● ● ○	
○ ○ ○ ○ . ○ ○ ○ ○	1
○ ○ ○ ○ . ○ ○ ○ ●	
○ ○ ○ ○ . ○ ○ ○ ○	
○ ○ ○ ○ . ○ ○ ○ ○	



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Upon termination, which value is stored in R[C] ?

- A. 000A
- B. 0011
- C. 8B12
- D. AC0A

opcode	operation	pseudocode
7	<i>load address</i>	$R[d] = \text{addr}$
8	<i>load</i>	$R[d] = M[\text{addr}]$
A	<i>load indirect</i>	$R[d] = M[R[t]]$

10: 7A11	R[A] = 11	← <i>load address</i>
11: 8B12	R[B] = M[12]	← <i>load</i>
12: AC0A	R[C] = M[R[A]]	← <i>load indirect</i>
13: 0000	halt	

REGISTERS	
:	:
R[A]	0 0 0 0
R[B]	0 0 0 0
R[C]	0 0 0 0
:	:

PC
1 0

Arrays

To implement an array:

- Keep array elements contiguous in memory, say, starting at 80.
- Access array element i at $M[80 + i]$. using **load/store indirect**.

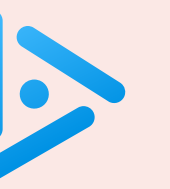
Goal. Print elements in an array of length $n > 0$ to standard output.

opcode	operation	pseudocode
7	<i>load address</i>	$R[d] = \text{addr}$
A	<i>load indirect</i>	$R[d] = M[R[t]]$
B	<i>store indirect</i>	$M[R[t]] = R[d]$

10: 7A80	$R[A] = 80$	← <i>array starts at $R[A] = 80$ and has length $R[B] = 9$</i>
11: 7B09	$R[B] = 9$	
12: 7101	$R[1] = 1$	
13: AC0A	$R[C] = M[R[A]]$	← <i>load next array element into $R[C]$</i>
14: 9CFF	write $R[C]$	
15: 1AA1	$R[A] = R[A] + 1$	← <i>address of next element in array</i>
16: 2BB1	$R[B] = R[B] - 1$	
17: CB13	if ($R[B] > 0$) goto 13	
18: 0000	halt	

array of length 9

```
80: CODE
81: CAFE
82: ABBA
83: 8BAD
84: FOOD
85: FACE
86: 1377
87: D1CE
88: C1A0
```



Suppose that we execute the same program, but initialize $R[A]$ to 10. What is the result?

- A. Prints 0010, 0011, 0012, ..., 0018.
- B. Prints 7A10, 7B09, 7101, ..., 0000. *← treats the TOY program as data
(and prints the program)*
- C. Crashes when $R[A]$ is 0013.
- D. Infinite loop.

```
10: 7A10  R[A] = 10  ← array now starts at R[A] = 10
11: 7B09  R[B] = 9
12: 7101  R[1] = 1
13: AC0A  R[C] = M[R[A]]
14: 9CFF  write R[C]
15: 1AA1  R[A] = R[A] + 1
16: 2BB1  R[B] = R[B] - 1
17: CB13  if (R[B] > 0) goto 13
18: 0000  halt
```


Indirection

Direct addressing. Specify memory address to access.

Indirect addressing. Specify register containing memory address to access.

Pointer. Variable/register that stores a memory address.

Indirection. Manipulating a value through its memory address.

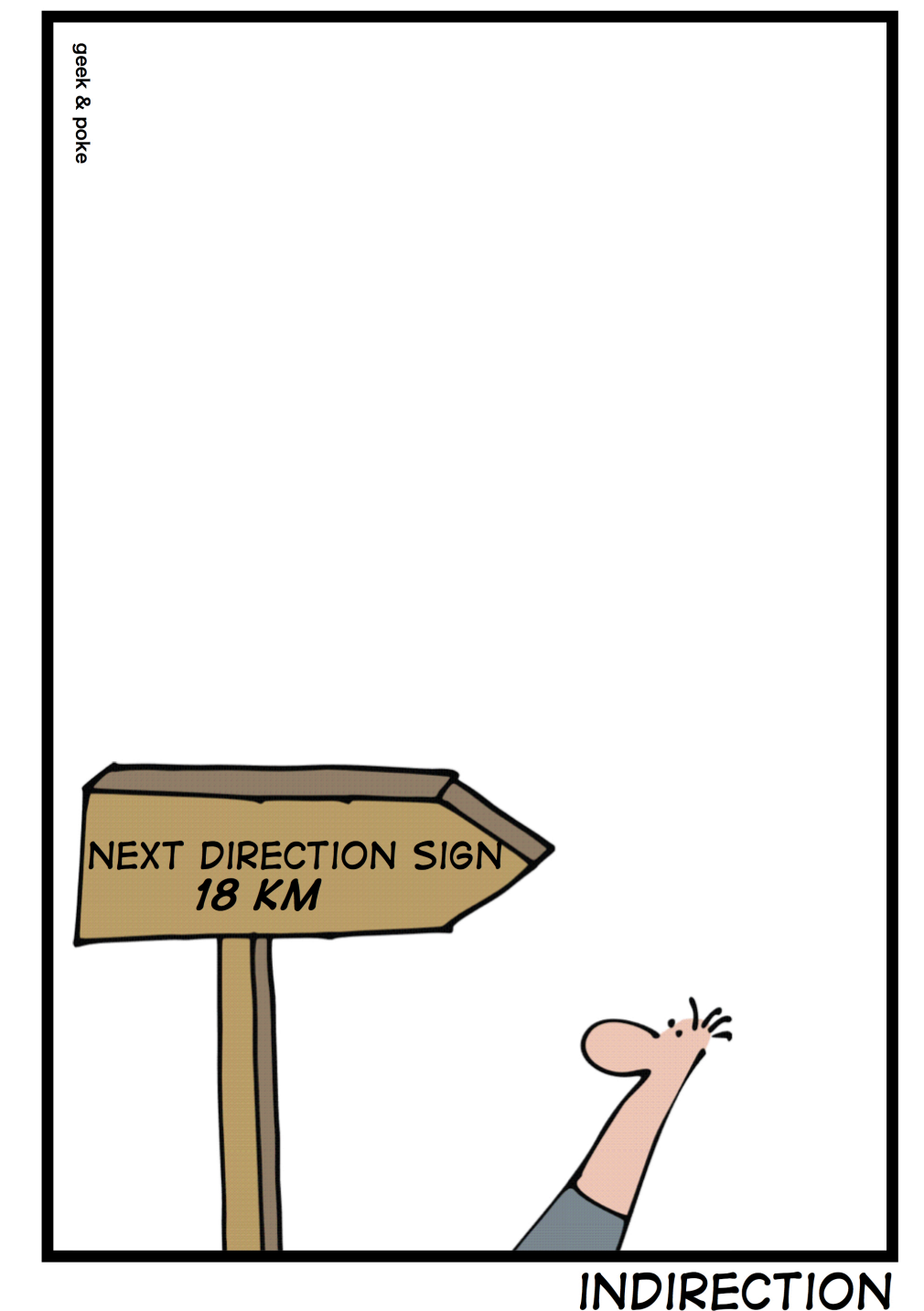
- TOY arrays.
- Java references.
- C pointers.
- ...

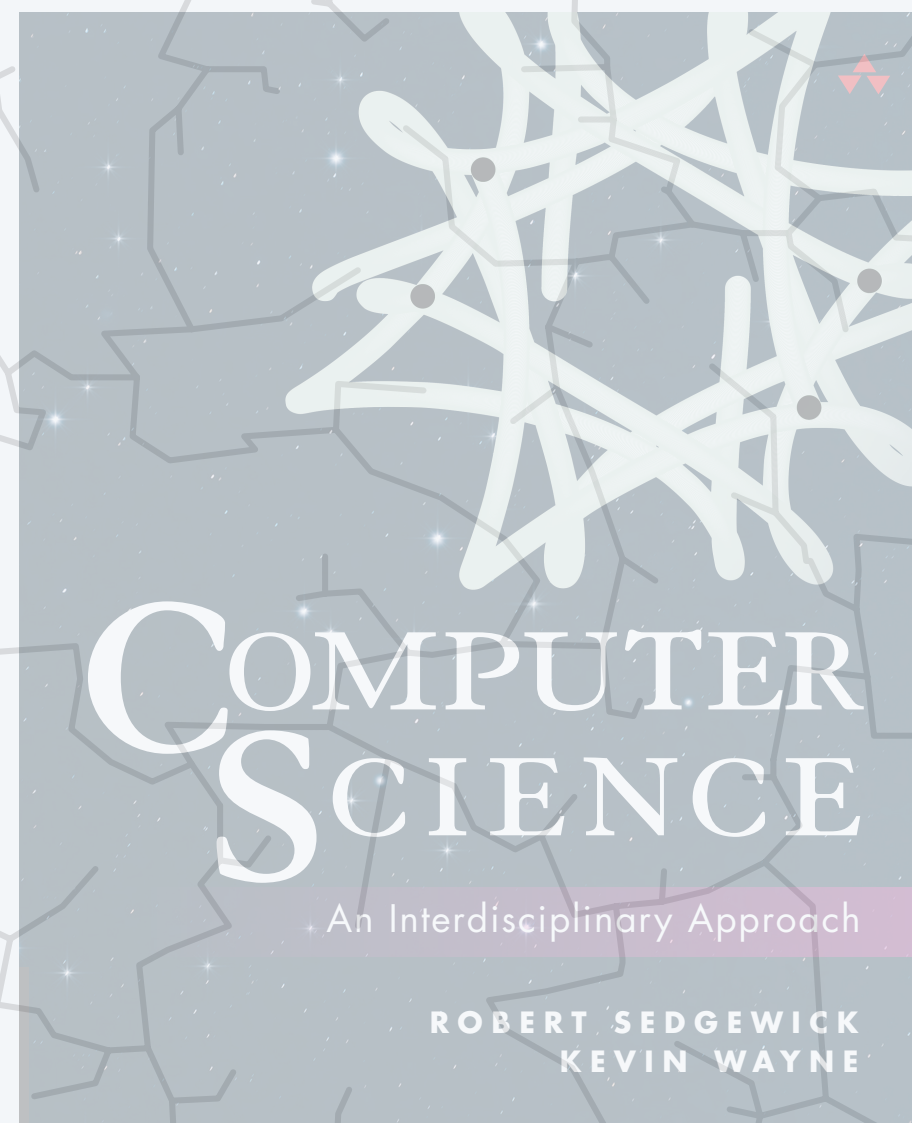
*“Any problems in computer science can be solved
with another level of indirection.”*

— *attributed to David Wheeler*



SIMPLY EXPLAINED





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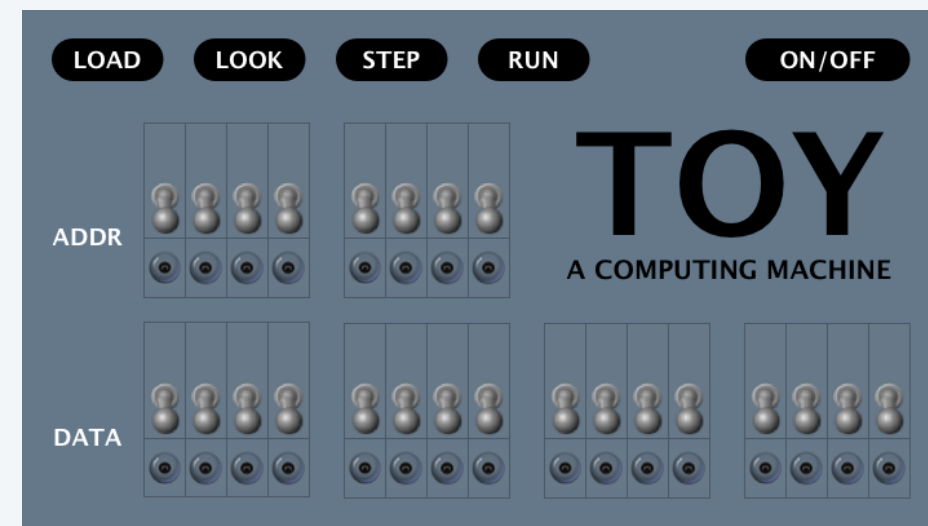
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- ▶ ***von Neumann architecture***
- ▶ *TOY emulator*

TOY vs. your laptop

Two different computing machines.

- Both implement basic data types, conditionals, loops, and other low-level constructs.
- Both can have arrays, functions, linked structures, and other high-level constructs.
- Both have unbounded input and output streams.



A few key differences.

- Performance: 1Hz vs. 3.5 GHz.
- Memory: 512 bytes vs. 32GB.
- Input/output devices: display, keyboard, trackpad, speakers, webcam, ...

An early computer

Electronic Numerical Integrator and Calculator (ENIAC).

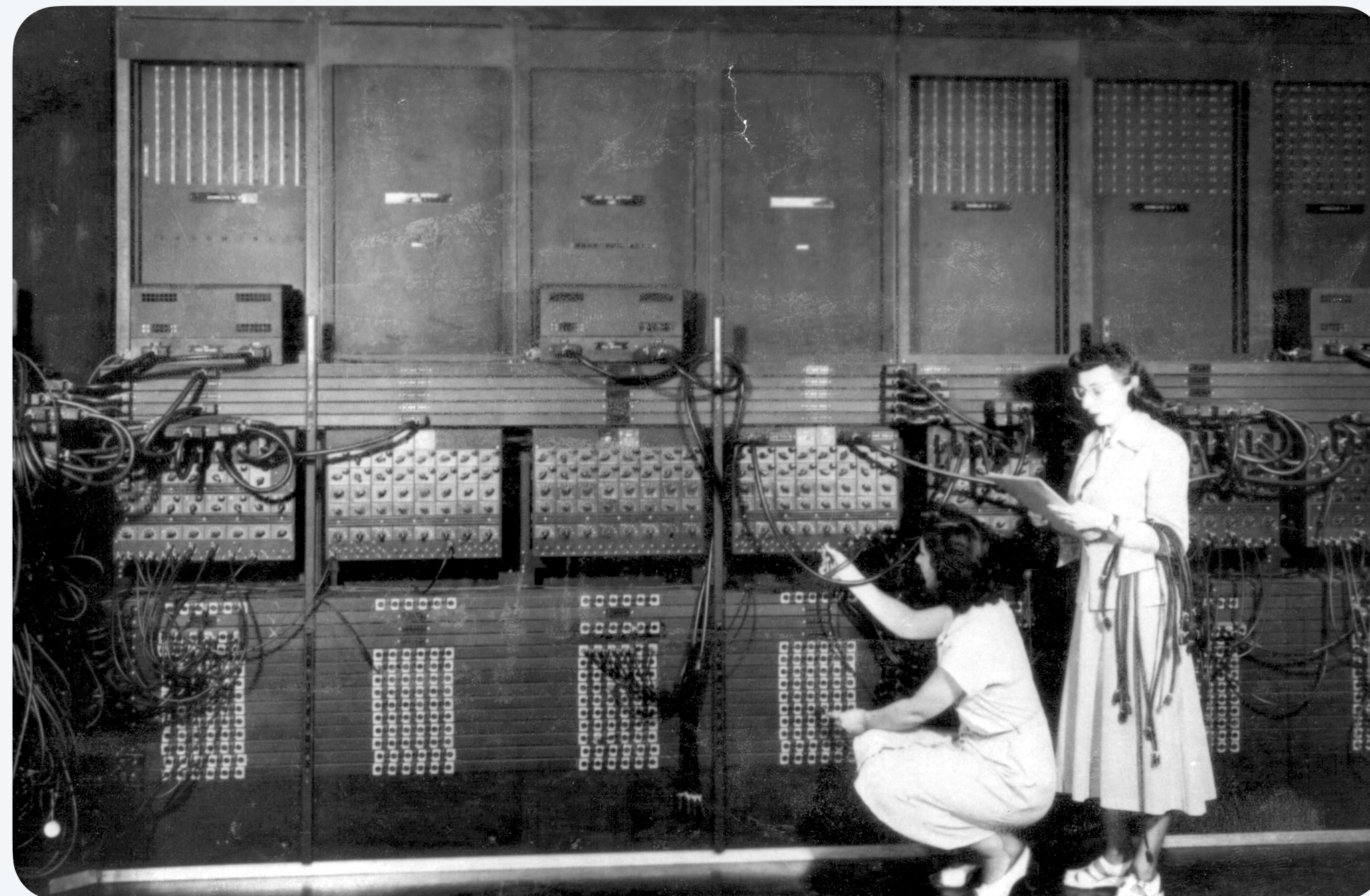
- First widely-known general-purpose electronic computer.
- “Programmable”, but no memory.
- **Programming**: change switches and cable connections.
- Data: enter numbers using punch cards.



J. Presper Eckert



John W. Mauchly



two programmers “programming” the ENIAC (1946)

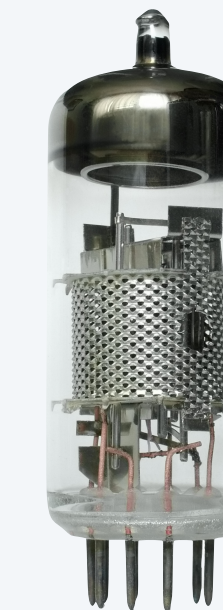
facts and figures

30 tons

30 × 50 × 8.5 feet

17,468 vacuum tubes

300 multiply/sec

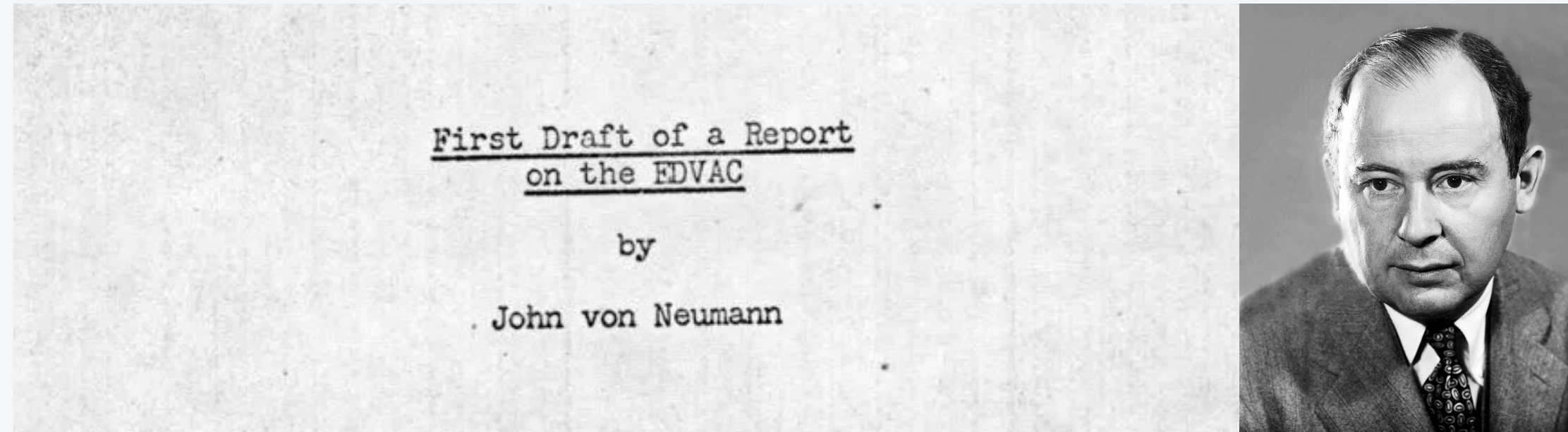


**one bit
(vacuum tube)**

Von Neumann architecture

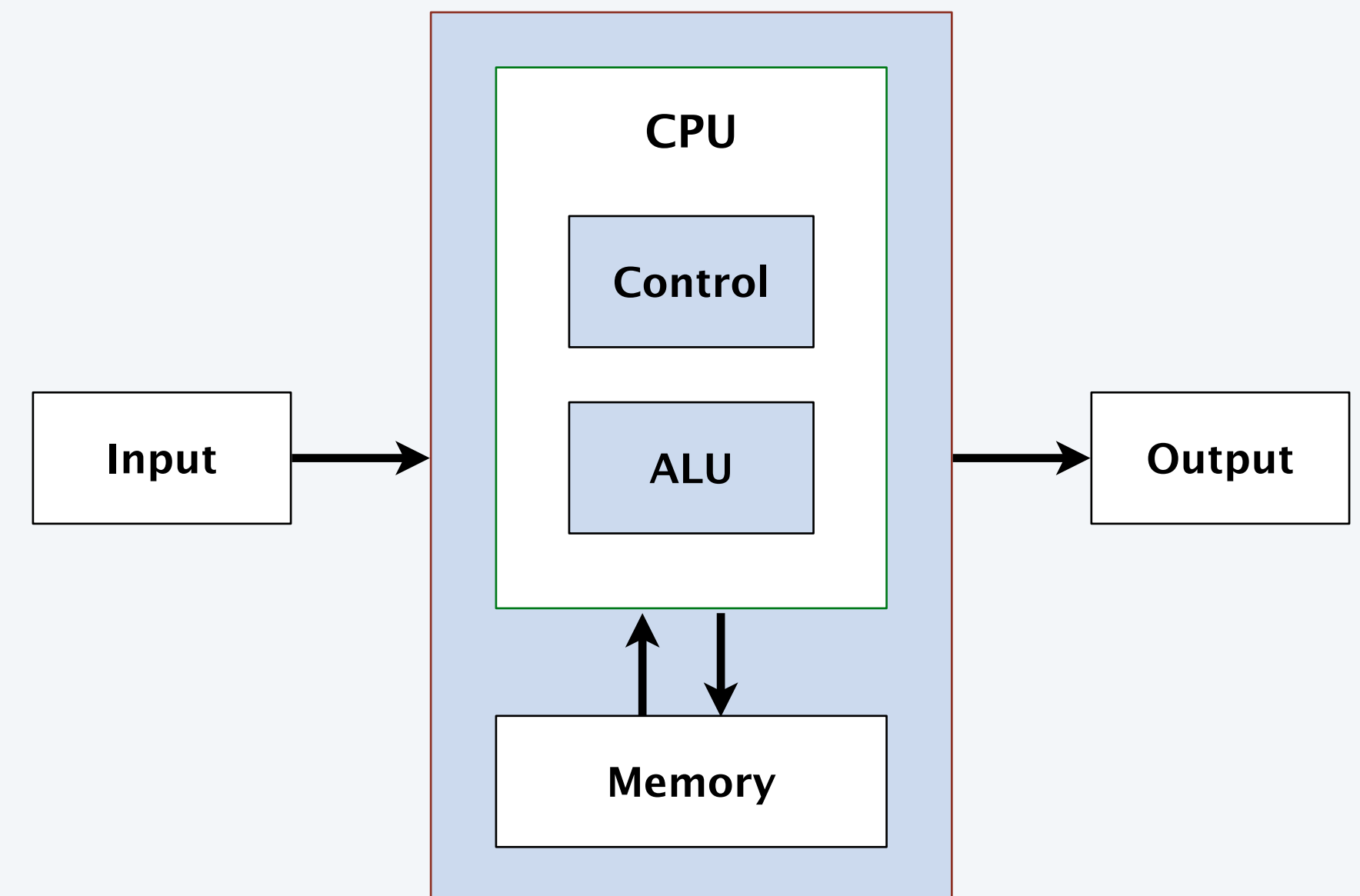
First Draft of a Report on the EDVAC (1945).

- Brilliant summation of a **stored-program** machine.
- Written by John von Neumann on a train.
- Based upon EDVAC design of Eckert-Mauchly; influenced by Turing.



Keys elements.

- Data and instructions encoded in binary.
- Store both data and instructions in same computer memory.
- ALU, control, memory, registers, and input/output.



Apollo Guidance Computer

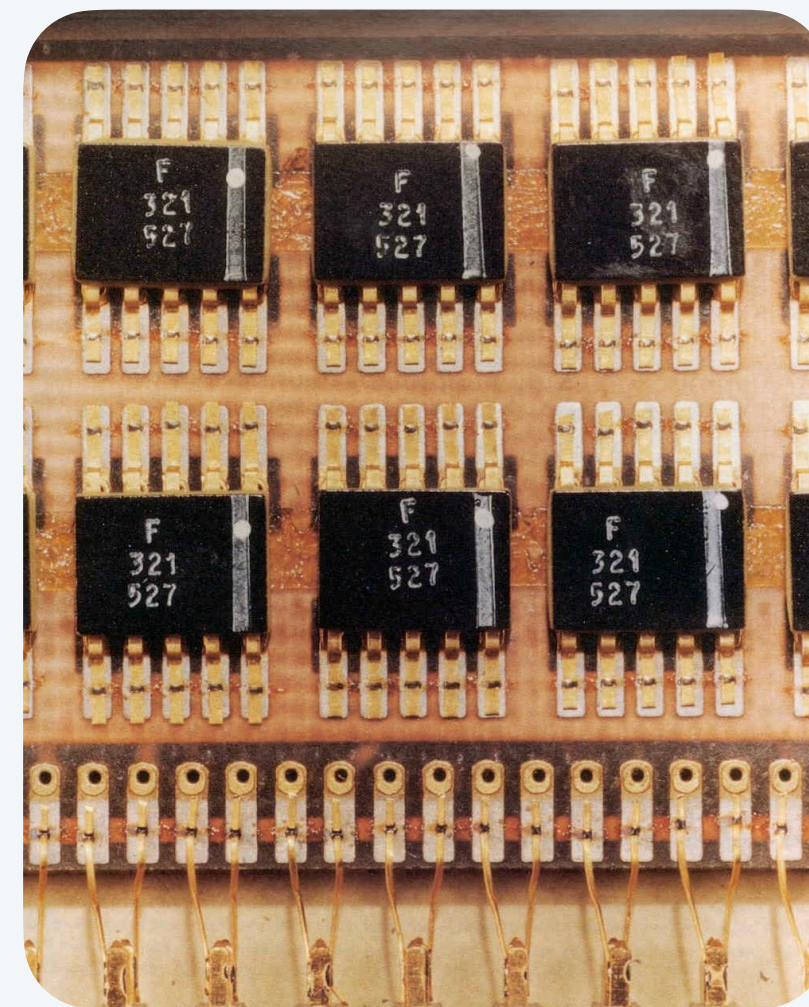
Apollo Guidance Computer. For guidance, navigation, and control of the spacecraft.

- First computer based on silicon integrated circuits.
- Weighed only 70 pounds!
- 1.024 MHz processor speed.
- 4 KB memory.

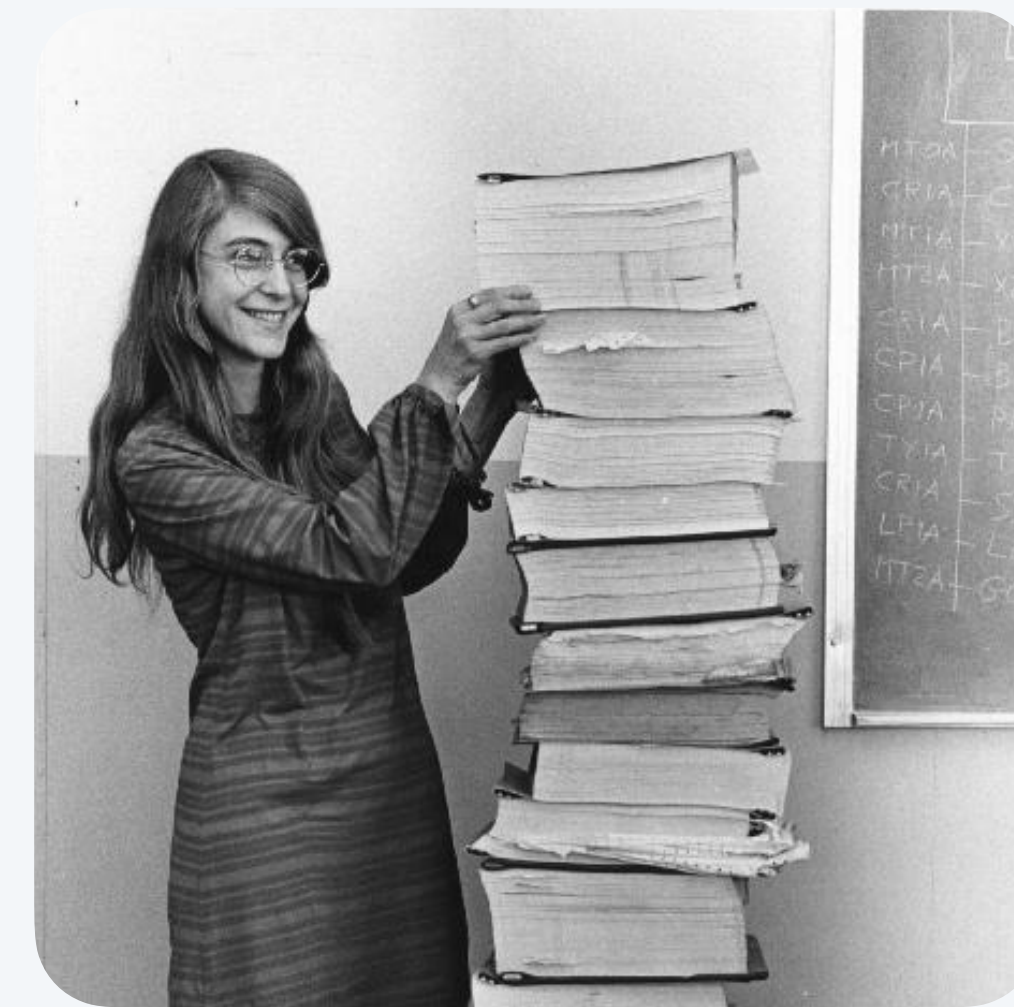
← *less powerful than
a USB-C charger*



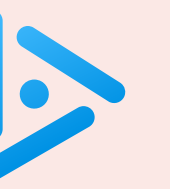
Apollo 11
(landed on moon)



integrated circuit



Margaret Hamilton
(lead NASA software engineer)



What does the following program print to standard output?

- A. 0000
- B. 0088
- C. 0088, 0088, 0088, 0088, ...
- D. Nothing.

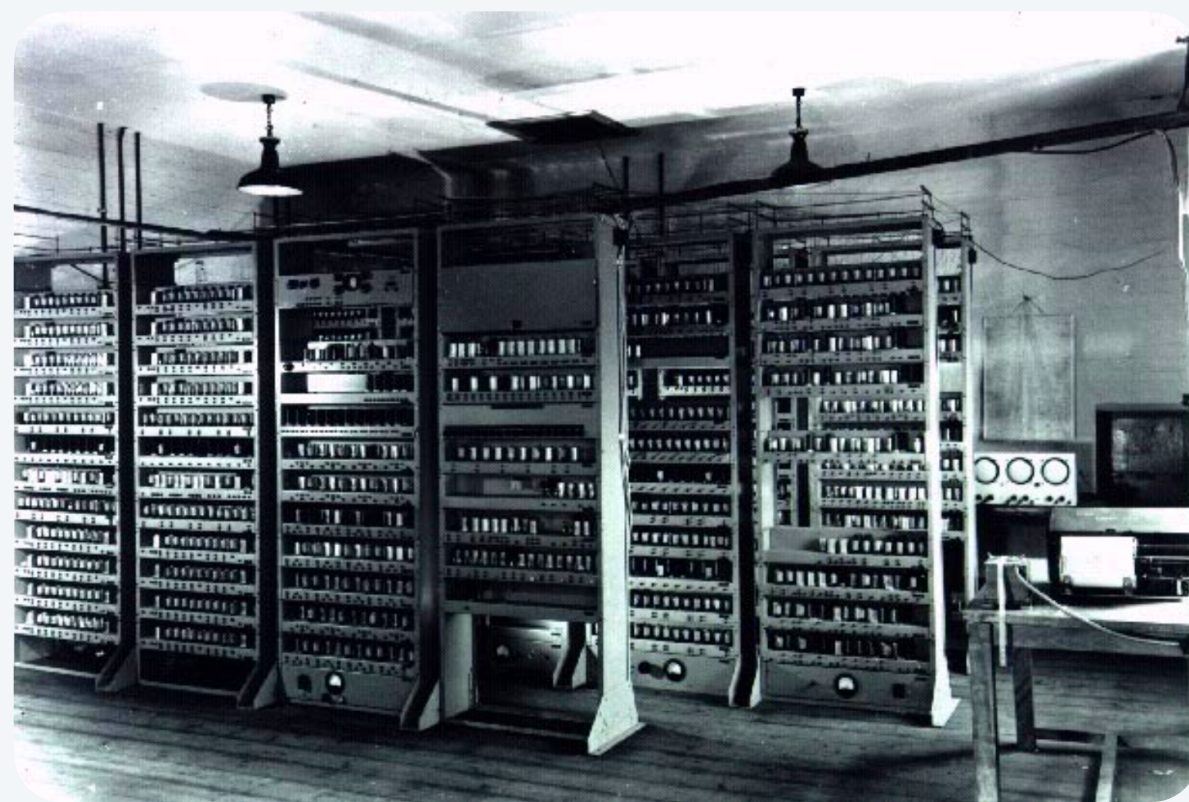
```
10: 7202  R[2] = 2
11: 7A88  R[A] = 88
12: AB16  R[B] = M[16] ← R[B] stores C017
13: 2BB1  R[B] = R[B] - 2 ← R[B] stores C015
14: BB16  M[16] = R[B]
15: 9AFF  write R[A] to stdout
16: C017  goto 15
17: 0000  halt
```

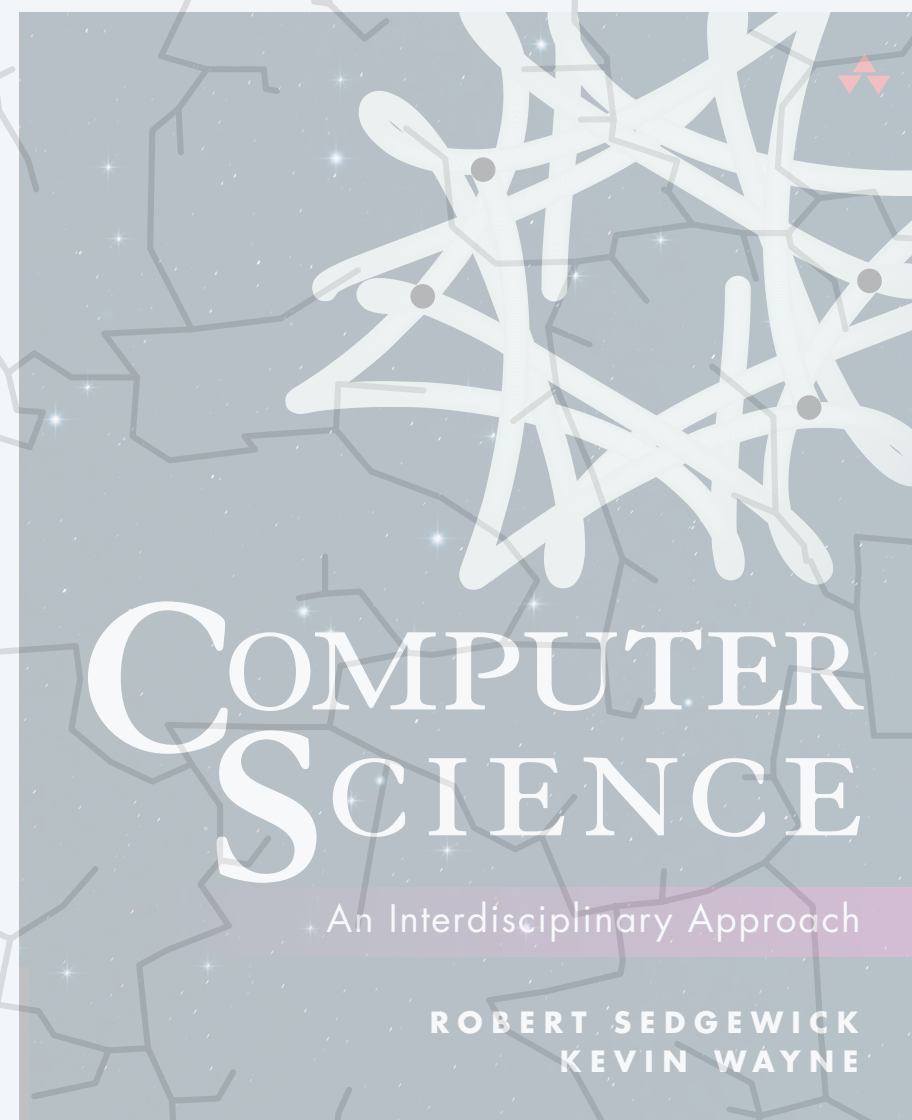

Implications

Stored-program (von Neumann) architecture is the basis of nearly all computers since the 1950s.

Practical implications.

- Programming: develop programs without rewiring.
- Download apps: load programs, not just data, into memory.
- Compilers: write programs that take programs as input (and produce programs as output).
- Code-injection attacks: trick program into treating input data as code.





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6. TOY MACHINE II

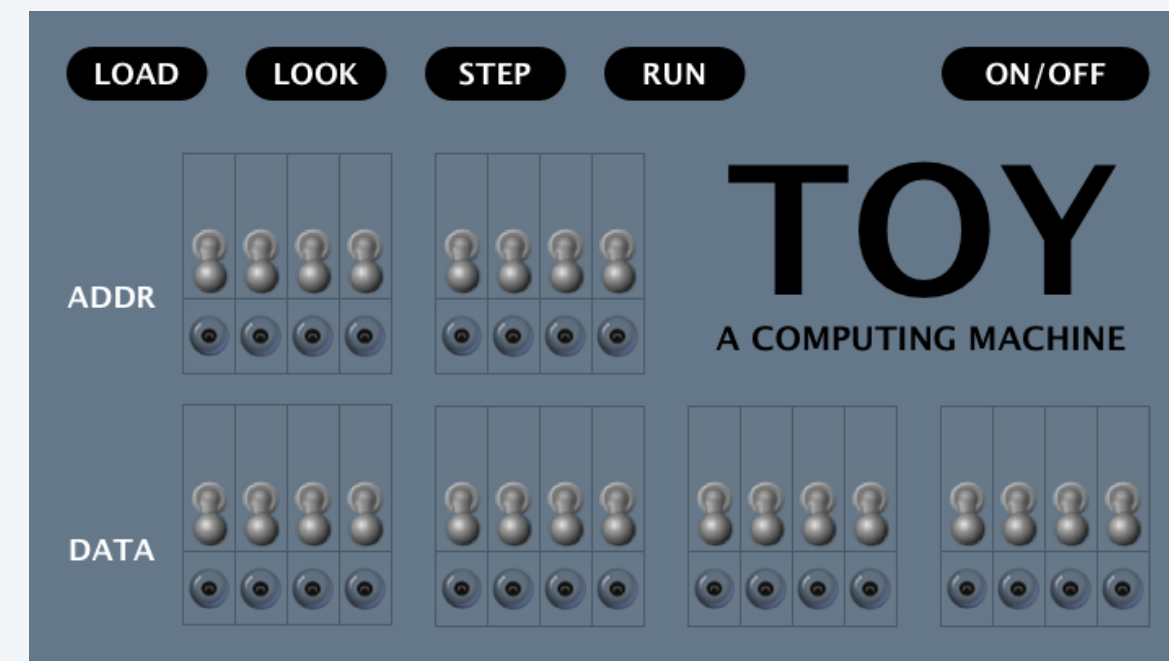
- ▶ *conditionals and loops*
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- ▶ *von Neumann architecture*
- ▶ ***TOY emulator***

TOY emulator

Q. How did we debug all our TOY programs?

A. We wrote a Java program to **emulate** a TOY machine.

Emulator. Hardware or software that enables one computer system to behave like another.



Remarks.

- YOU could write a TOY emulator (ahead).
- We designed TOY by refining this code.
- All computers are designed in this way.

estimated number of Android devices: 1 billion+



estimated number of TOY devices: 1 billion+

TOY emulator in Java: high-level design

Goal. Write a Java program that emulates the TOY machine.

```
public class TOYLite {  
    public static void main(String[] args) {  
        int pc = 0x10;           // program counter  
        int[] R = new int[16];  // registers  
        int[] M = new int[256]; // main memory  
  
        In in = new In(args[0]);  
        for (int i = pc; !in.isEmpty(); i++)  
            M[i] = Integer.parseInt(in.readString(), 16);  
  
        while (true) {  
            // 1. fetch instruction and increment PC  
            // 2. decode instruction  
            // 3. execute instruction  
        }  
    }  
}
```

hex literal (starts with 0x) (points to 0x10)

base 16 (points to 16)

```
~/cos126/toy> more add.toy  
8AFF |  
8BFF | ← read R[A] and R[B]  
1CAB | from standard input  
9CFF ← print R[C] to standard output  
0000  
  
~/cos126/toy> java-introcs TOYLite add.toy  
0008  
0005  
000D  
↑ takes TOY program as input  
← emulates TOY program and produces same output
```

TOY emulator: fetch and increment

Fetch. Get instruction from memory location indexed by PC.

Increment. Increment PC by 1.

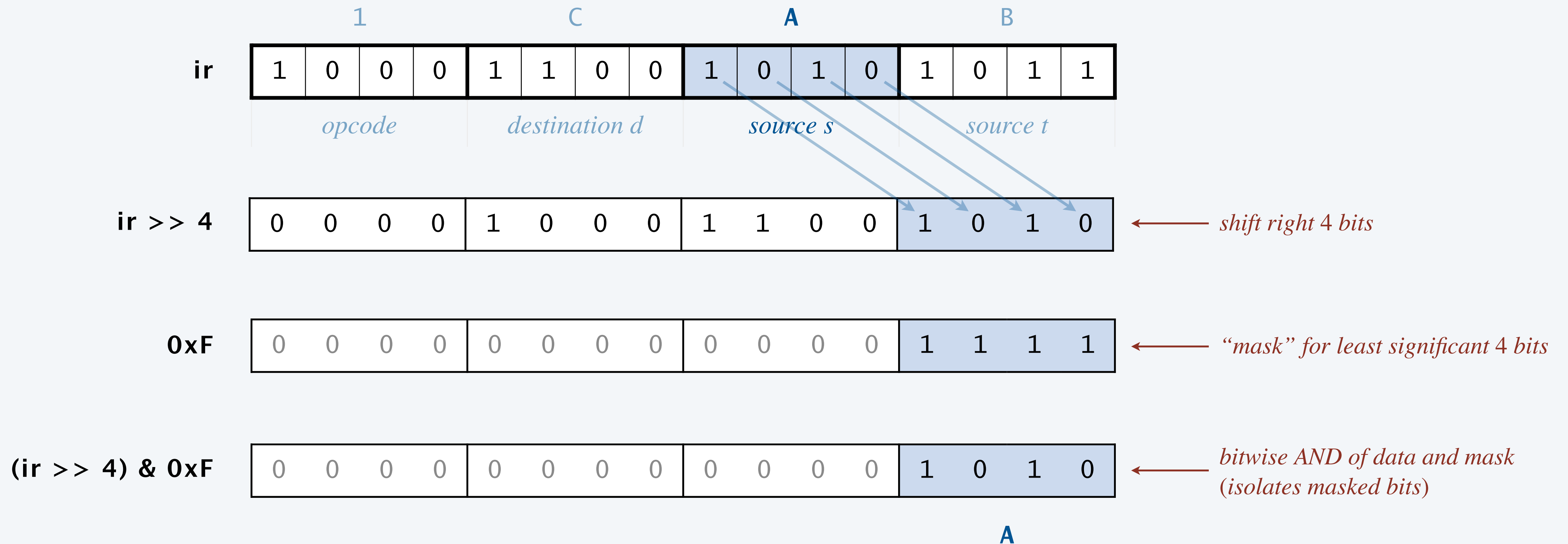
```
int ir = M[pc];    // fetch
pc++;             // increment
```

TOY emulator: decode instruction

Decode. Extract relevant components from instruction register (IR).

- Bitwise operations are the same in Java and TOY.
- Use **shift-and-mask** technique.

Ex. Extract source s from 1CAB.



TOY emulator: decode instruction

Decode. Extract relevant components from instruction register (IR).

- Bitwise operations are the same in Java and TOY.
- Use **shift-and-mask** technique.

```
int ir = M[pc];    // fetch
pc++;             // increment

int op  = (ir >> 12) & 0xF;    // opcode
int d   = (ir >>  8) & 0xF;    // destination d
int s   = (ir >>  4) & 0xF;    // source s
int t   = (ir >>  0) & 0xF;    // source t
int addr = (ir >>  0) & 0xFF;  // address
```

TOY emulator: execute instruction

Execute. Use Java `switch` statement to implement state change for each of 16 instructions.

```
if (op == 0) break;           // halt

switch (op) {
  case 1: R[d] = R[s] + R[t];   break;
  case 2: R[d] = R[s] - R[t];   break;
  case 3: R[d] = R[s] & R[t];   break;
  case 4: R[d] = R[s] ^ R[t];   break;
  case 5: R[d] = R[s] << R[t];  break;
  case 6: R[d] = R[s] >> R[t];  break;
  case 7: R[d] = addr;          break;
  case 8: R[d] = M[addr];        break;
  case 9: M[addr] = R[d];        break;
  case 10: R[d] = M[R[t]];        break;
  case 11: M[R[t]] = R[d];        break;
  case 12: if (R[d] == 0) pc = addr; break;
  case 13: if (R[d] > 0) pc = addr; break;
  case 14: pc = R[d];            break;
  case 15: R[d] = pc; pc = addr;  break;
}
```

TOY emulator in Java

A few missing details.

- R[0] is always 0000.
- TOY standard input/output.
- 16-bit TOY word vs. 32-bit Java int.
- More flexible TOY program input format.

Full implementation. See booksite.

Implications.

- Can run any TOY program!
- Can develop TOY code on another machine.
- Easy to change TOY design.

```
public class TOYLite {
    public static void main(String[] args) {
        int pc = 0x10;           // program counter
        int[] R = new int[16];   // registers
        int[] M = new int[256];  // main memory

        In in = new In(args[0]);
        for (int i = pc; !in.isEmpty(); i++)
            M[i] = Integer.parseInt(in.readString(), 16);

        while (true) {
            int ir = M[pc++];     // fetch
            pc++;                 // increment

            int op = (ir >> 12) & 0xF; // opcode
            int d = (ir >> 8) & 0xF;  // destination d
            int s = (ir >> 4) & 0xF;  // source s
            int t = (ir >> 0) & 0xF;  // source t
            int addr = (ir >> 0) & 0xFF; // address

            if (op == 0) break;
            switch (op) {
                case 1: R[d] = R[s] + R[t]; break;
                case 2: R[d] = R[s] - R[t]; break;
                case 3: R[d] = R[s] & R[t]; break;
                case 4: R[d] = R[s] ^ R[t]; break;
                case 5: R[d] = R[s] << R[t]; break;
                case 6: R[d] = R[s] >> R[t]; break;
                case 7: R[d] = addr; break;
                case 8: R[d] = M[addr]; break;
                case 9: M[addr] = R[d]; break;
                case 10: R[d] = M[R[t]]; break;
                case 11: M[R[t]] = R[d]; break;
                case 12: if (R[d] == 0) pc = addr; break;
                case 13: if (R[d] > 0) pc = addr; break;
                case 14: pc = R[d]; break;
                case 15: R[d] = pc; pc = addr; break;
            }
        }
    }
}
```

← state

← parse input file

← fetch, increment

← decode instruction

← execute instruction

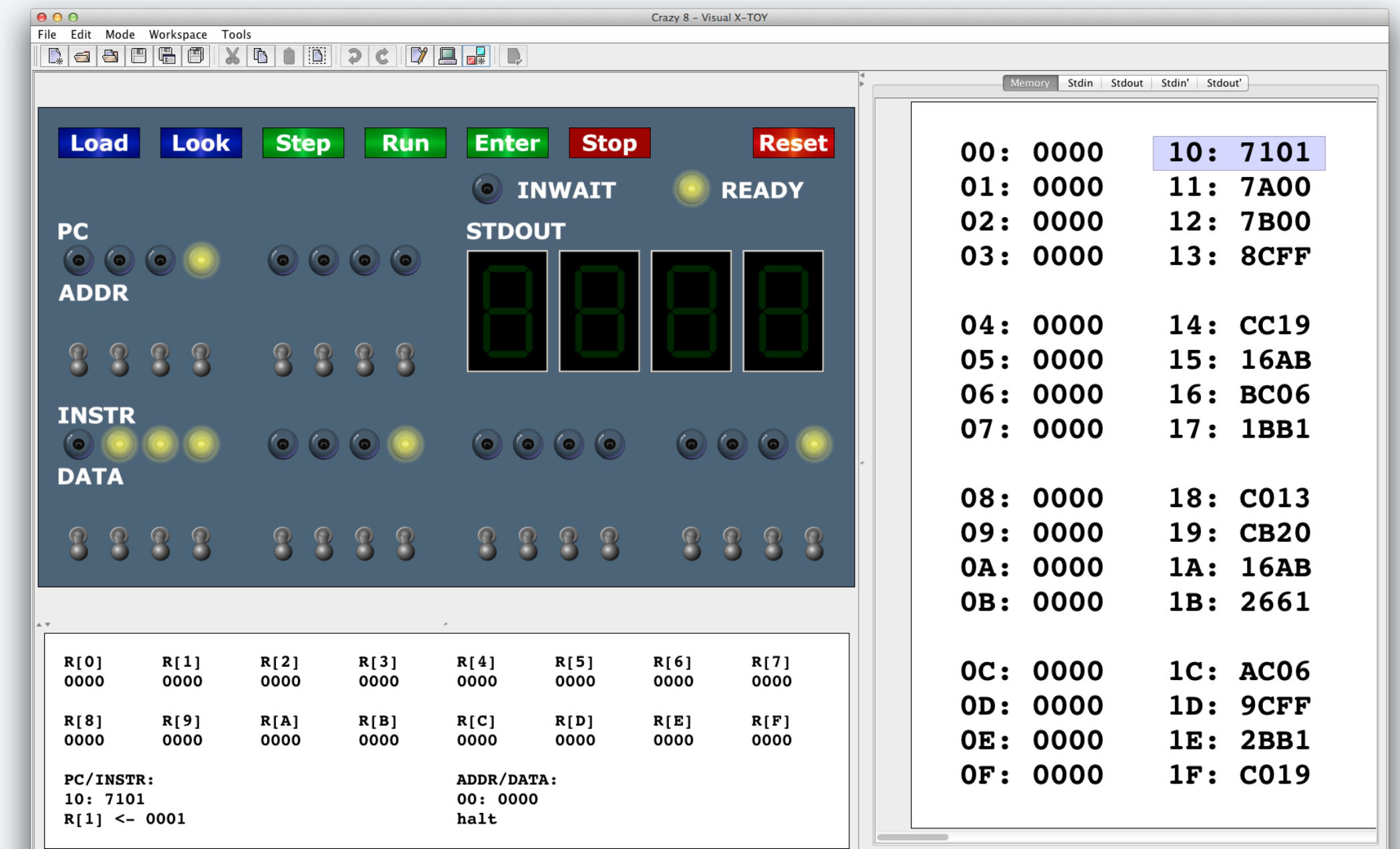
Visual X-TOY

Visual X-TOY. A Java IDE that emulates the TOY machine.

- GUI, text editor, auto-comments, debugger, many other features.
- Written by Brian Tsang '04 (using Java 1.3). ← *and still works 20 years later!*
- Available on the booksite.
- YOU can develop TOY software. ← *Assignment 8*

Same approach used for all new systems.

- Build simulator and development environment.
- Develop and test software.
- Build and sell hardware.



Backward compatibility

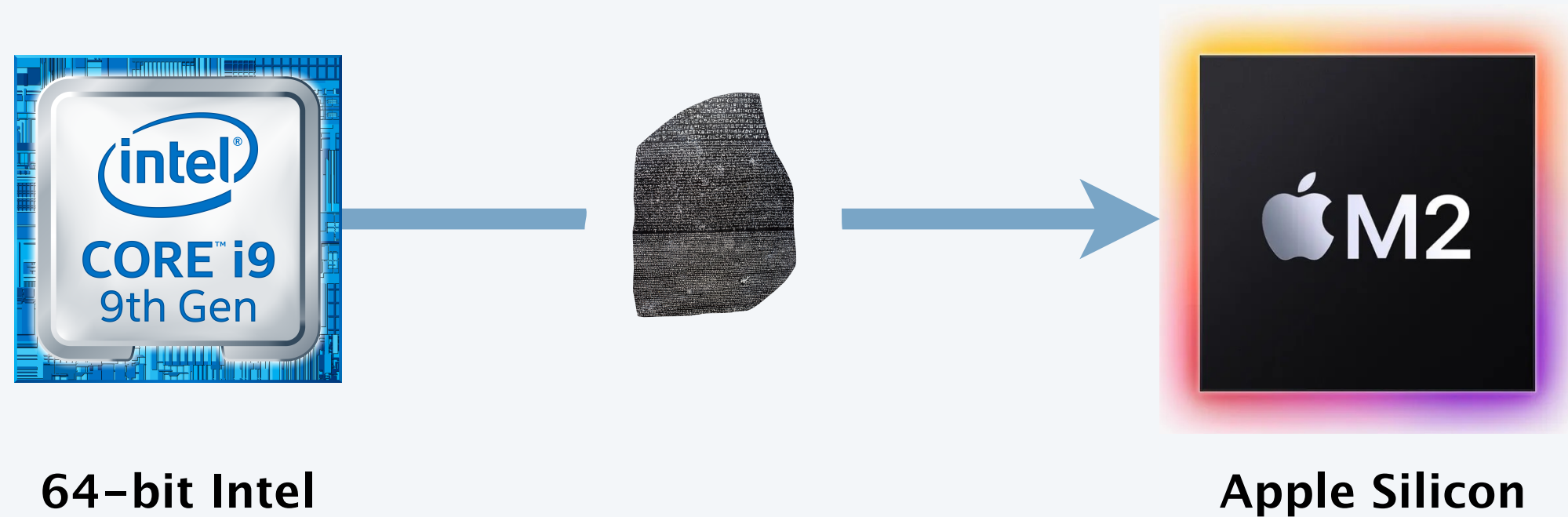
Q. How to run **old software** on a new machine architecture?

Approach 1. Rewrite it all: time-consuming, expensive, error-prone.

Approach 2. Write an **emulator** for old computer on the new one.

Ex 1. Pac-Man.

Ex 2. Rosetta 2. ← *run 64-bit Intel on Apple Silicon*



Pac-Man 1980s
(arcade machine)



Pac-Man 2020s
(Android phone)

Impact. Old software remains available.

Virtual machines

Virtual machine. Software-based emulation of a physical computer.

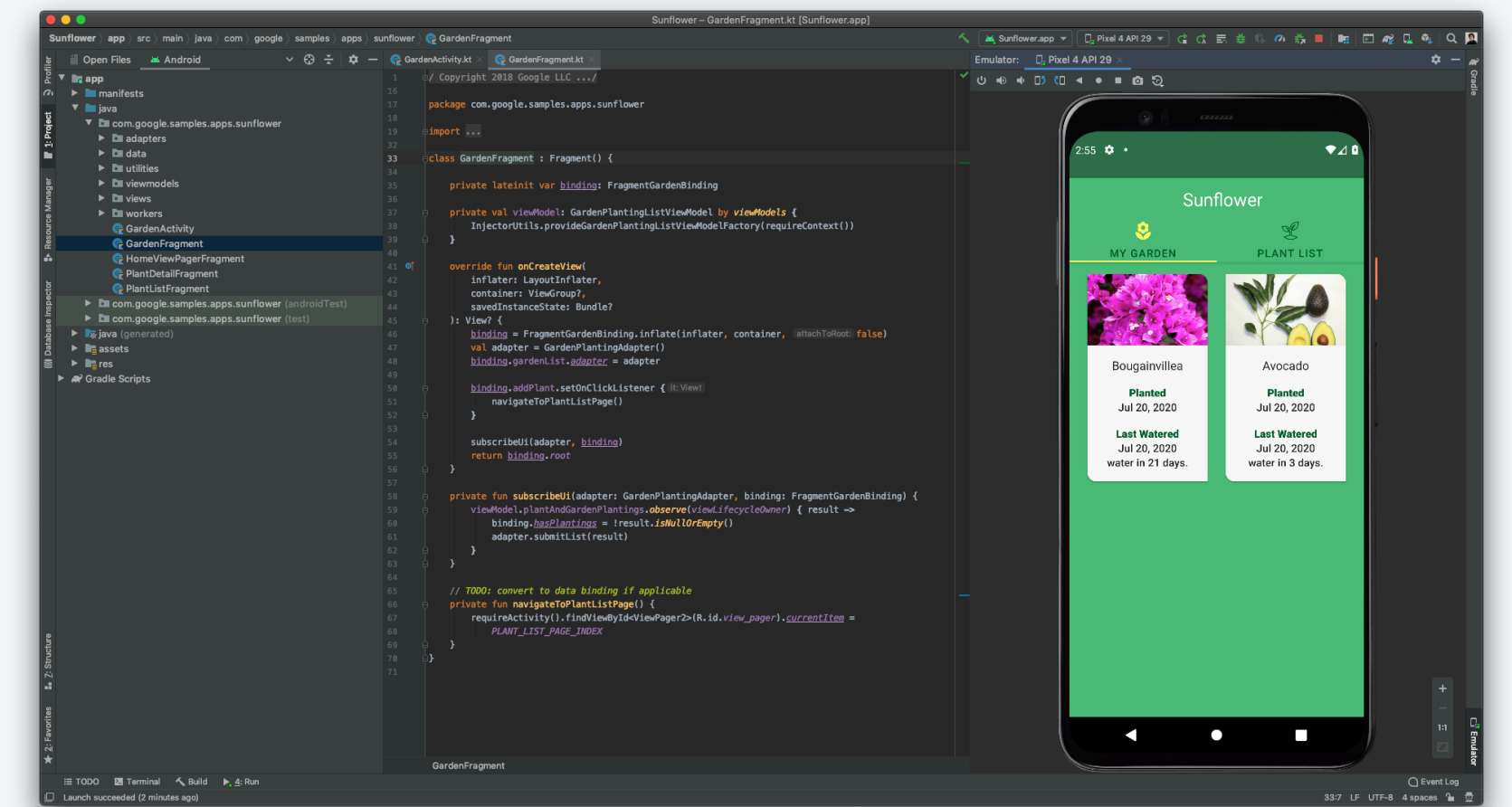
- Can run/develop software without having physical computer.
- Provides portability, scalability, flexibility, and security.

“write once, run anywhere”

Java virtual machine (JVM). Abstract machine that can execute Java .class files.

Mobile app IDEs. Provide emulator for Android, iPhone, Apple watch, ...

Cloud computing. Virtual CPU, memory, storage, OS, and network.



Amazon EC2



Google CE

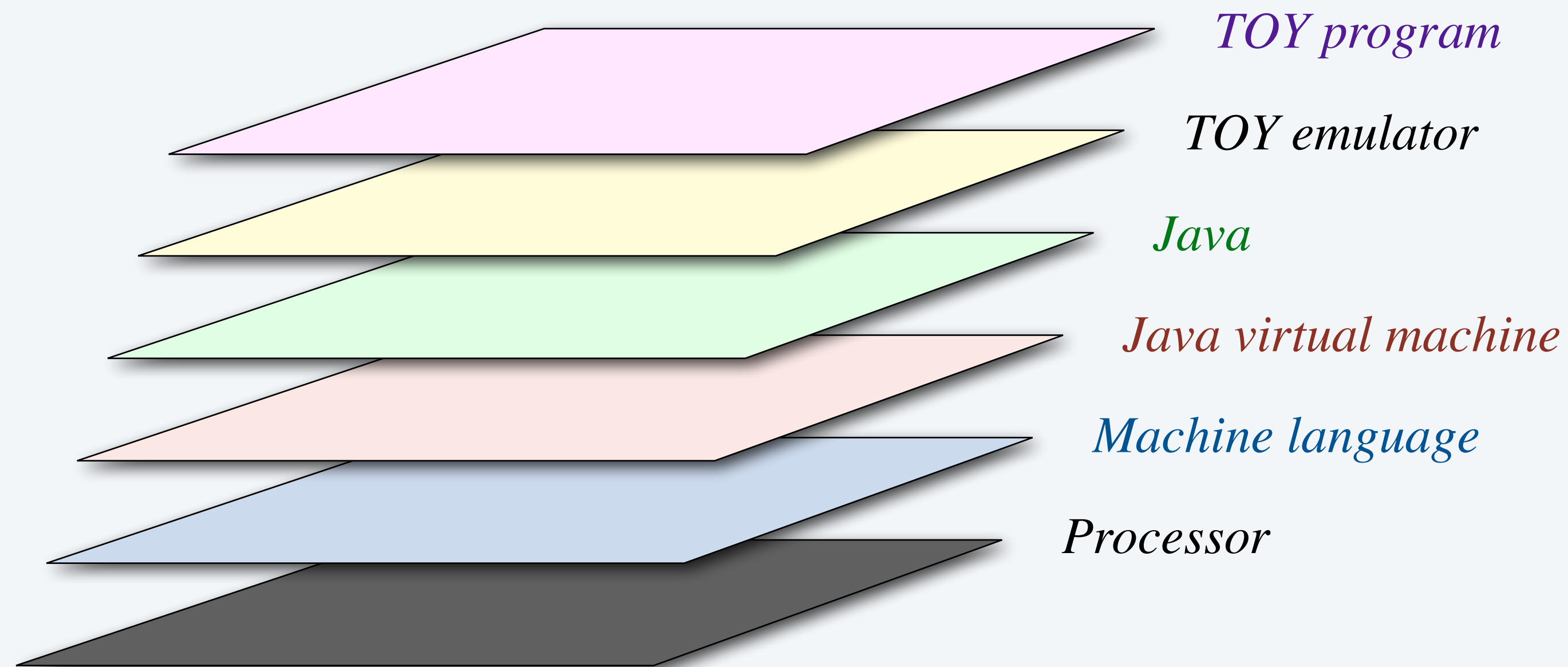


Microsoft Azure

Layers of abstraction

Computer systems are built by accumulating **layers of abstraction**.

Ex. Running a TOY program.

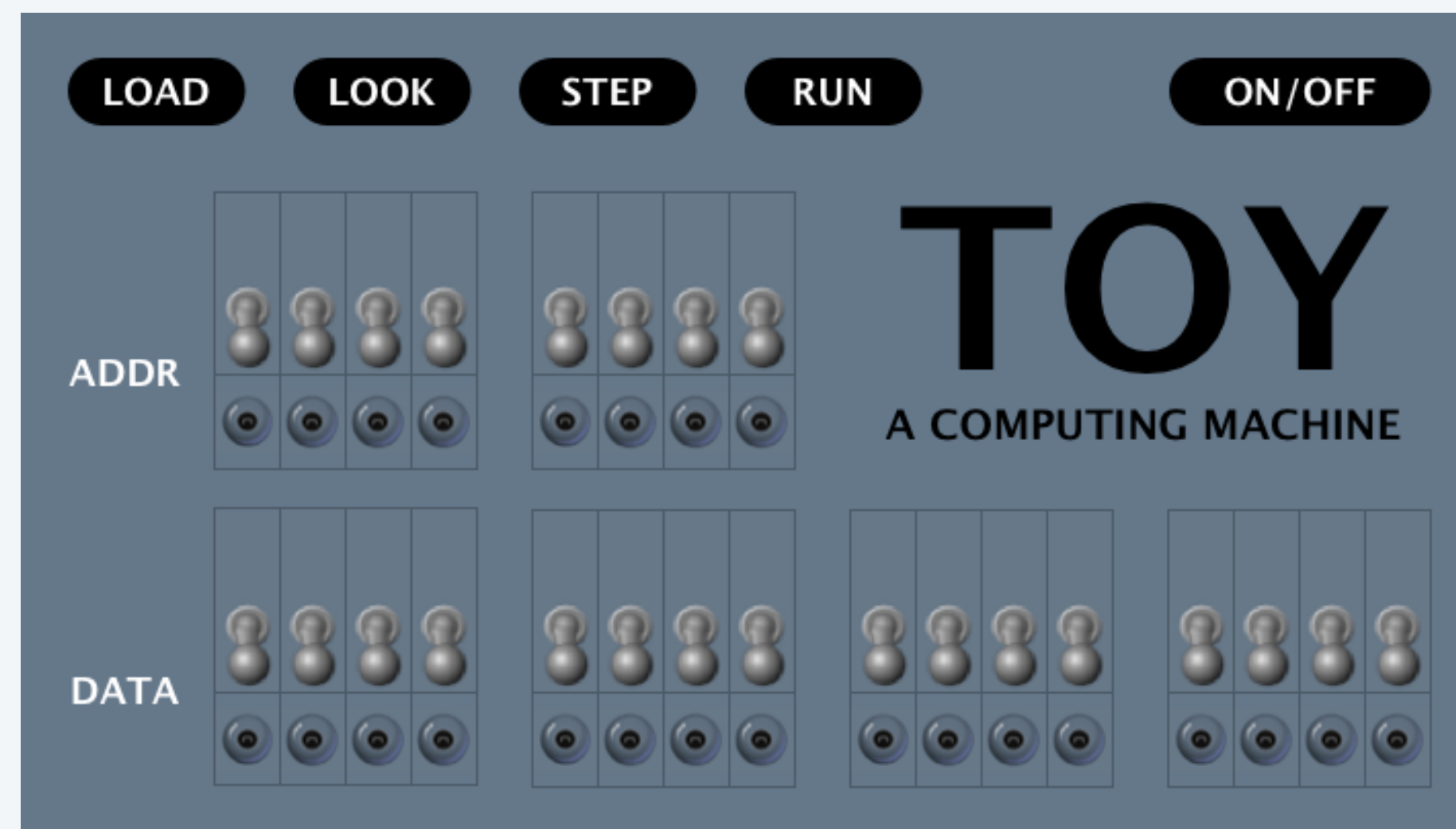


Digital computers. Encode “everything” in binary, including programs and data.

von Neumann machine. Store programs and data in same memory.

Indirection. Manipulate a value through its memory address.

Emulation. Make one system imitate another.



Credits

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