

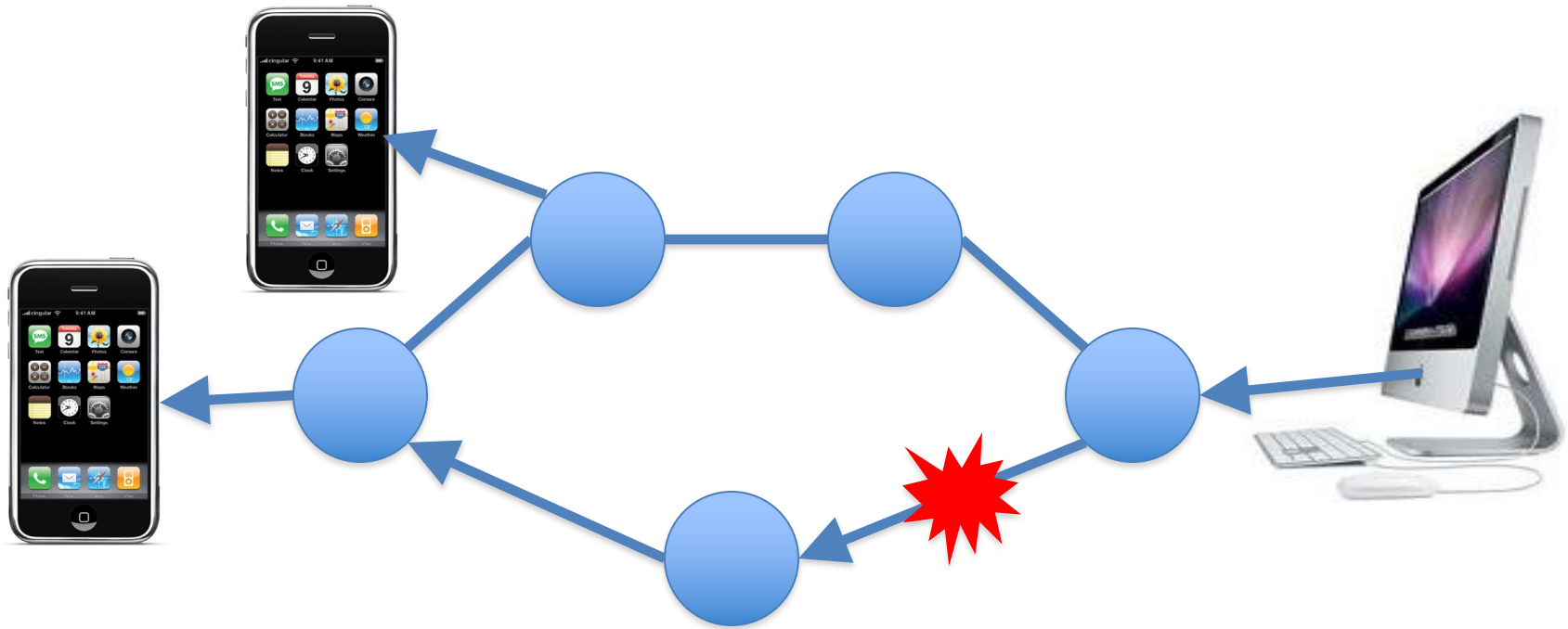
Routing Convergence

Lecture 10

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COS 461: Computer Networks

Routing Changes



- **Topology changes:** new route to the same place
- **Host mobility:** route to a different place

Topology Changes

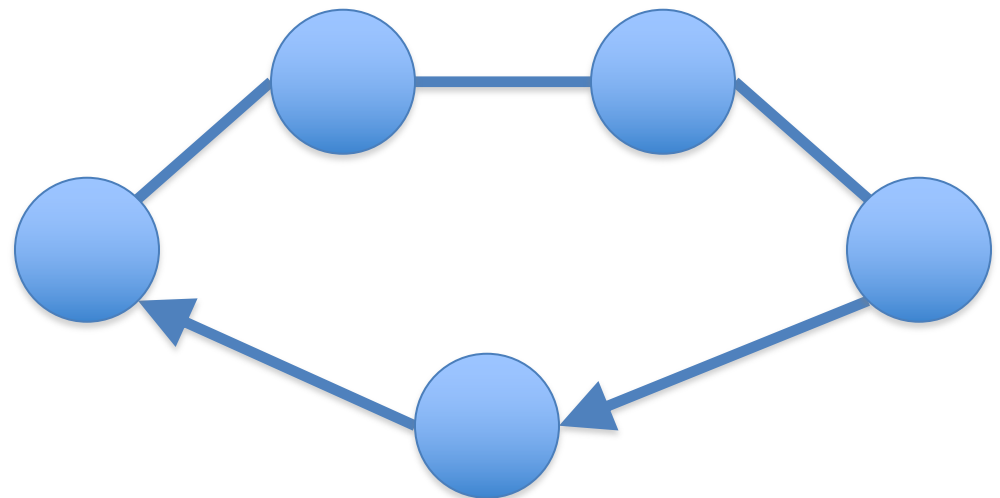
Two Types of Topology Changes

- **Planned**

- Maintenance: shut down a node or link
- Energy savings: shut down a node or link
- Traffic engineering: change routing configuration

- **Unplanned Failures**

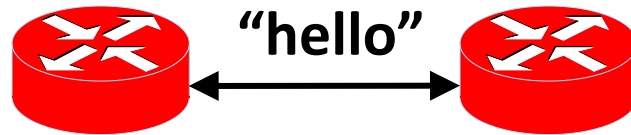
- Fiber cut,
faulty equipment,
power outage,
software bugs, ...



Detecting Topology Changes

- **Beaconing**

- Periodic “hello” messages in both directions
- Detect a failure after a few missed “hellos”



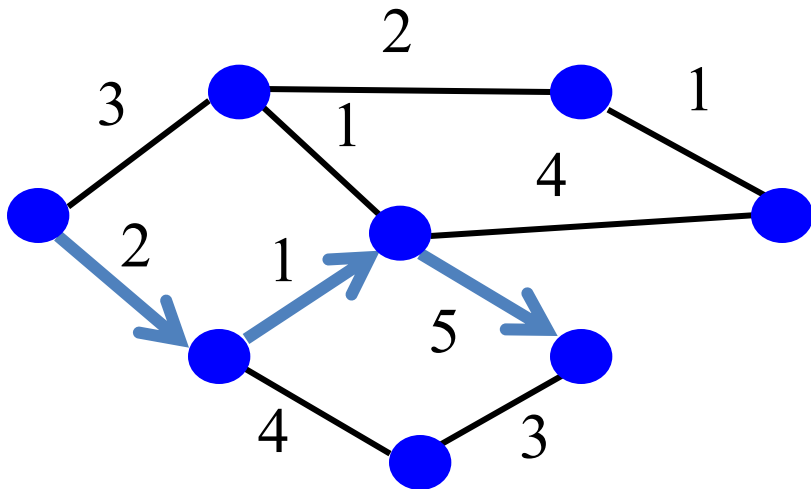
- **Performance trade-offs**

- Detection delay
- Overhead on link bandwidth and CPU
- Likelihood of false detection

Routing Convergence: Link-State Routing

Convergence

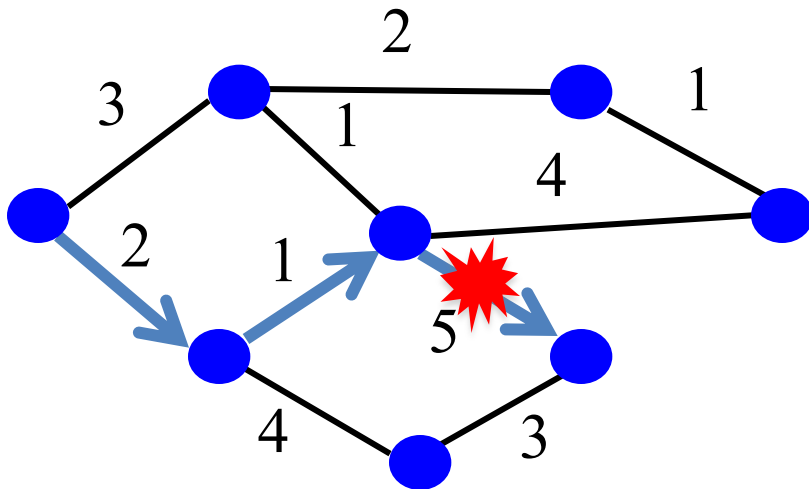
- **Control plane**
 - All nodes have consistent information
- **Data plane**
 - All nodes forward packets in a consistent way



Transient Disruptions

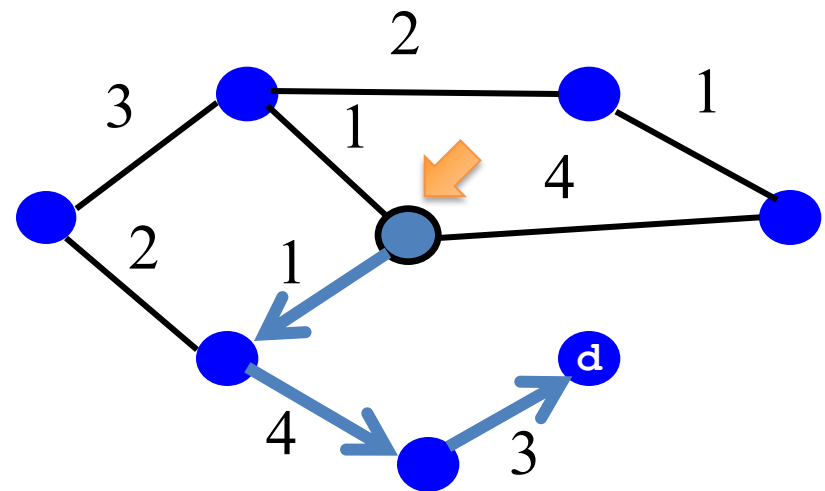
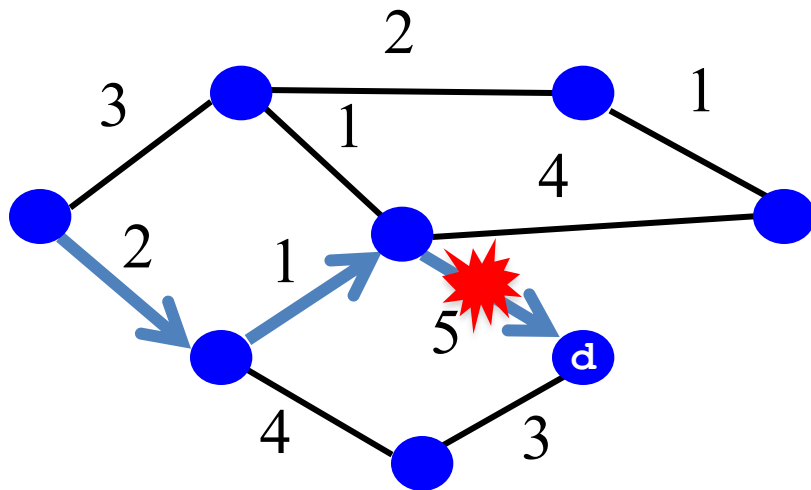
- **Detection delay**

- A node does not detect a failed link immediately
- ... and forwards data packets into a “blackhole”
- Depends on timeout for detecting lost hellos



Transient Disruptions

- **Inconsistent link-state database**
 - Some routers know about failure before others
 - Inconsistent paths cause transient forwarding loops



Convergence Delay

- Sources of convergence delay
 - Detection latency
 - Updating control-plane information
 - Computing and install new forwarding tables
- Performance during convergence period
 - **Lost packets** due to blackholes and TTL expiry
 - **Looping packets** consuming resources
 - **Out-of-order packets** reaching the destination
- Very bad for VoIP, online gaming, and video

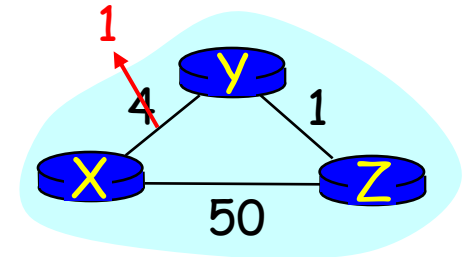
Slow Convergence in Distance-Vector Routing

Distance Vector: Link Cost Changes

- Link cost decreases and recovery

- Node updates the distance table

- **Rule:** Least-cost path's cost changed? notify neighbors



D^Y = Distances known to Y

D^Y		via	
	X	Z	
to: X	4	6	

D^Z		via	
	X	Y	
to: X	50	5	

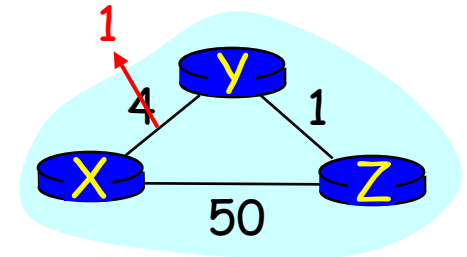


Distance Vector: Link Cost Changes

- Link cost decreases and recovery

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- **Rule:** Least-cost path's cost changed? notify neighbors



D^Y = Distances known to Y

D^Y		via	
	X	Z	
to: X	4	6	

D^Y		X	Z
X	1	6	

D^Z		via	
	X	Y	
to: X	50	5	

D^Z		X	Y
X	50	5	

$c(X,Y)$
change



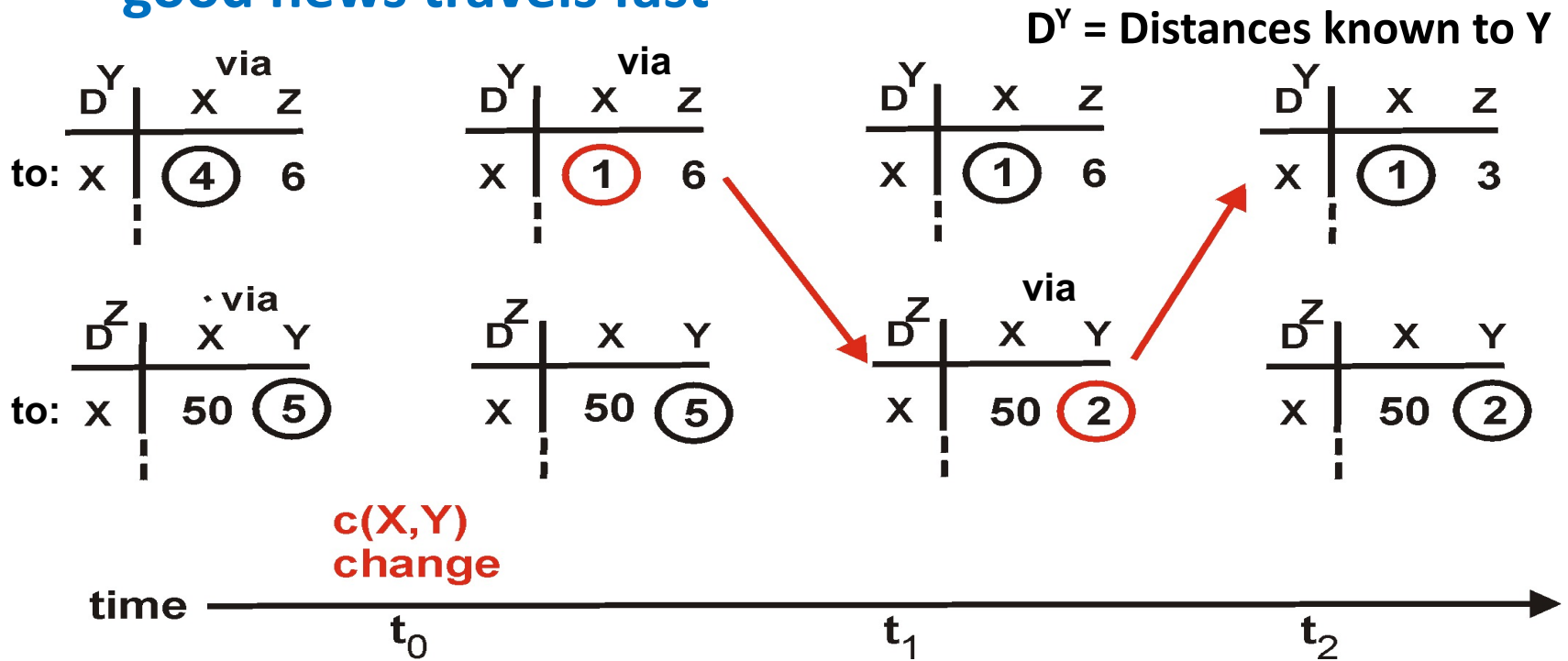
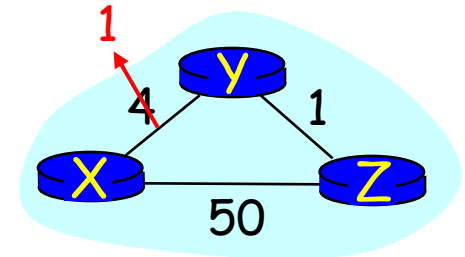
Distance Vector: Link Cost Changes

- Link cost decreases and recovery

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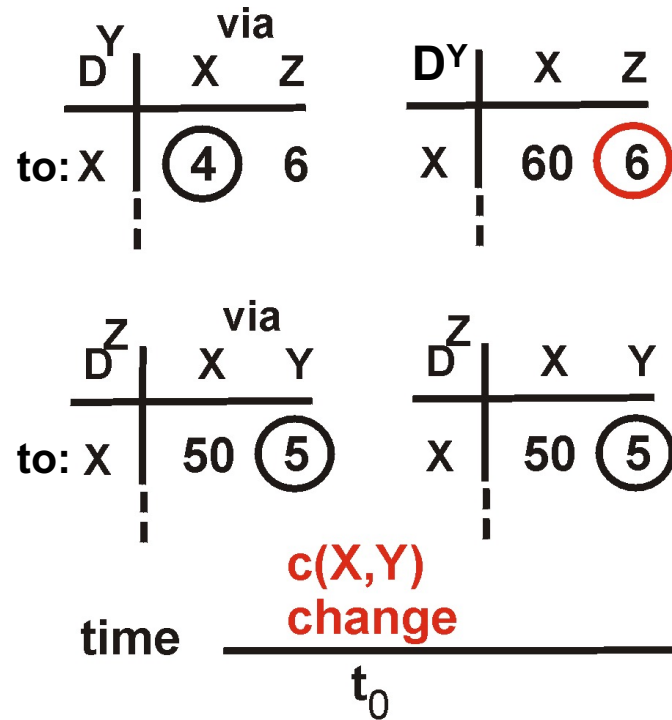
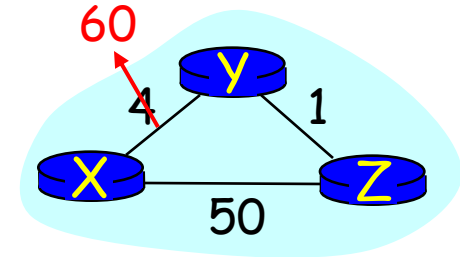
- **Rule:** Least-cost path's cost changed? notify neighbors

“good news travels fast”



Distance Vector: Link Cost Changes

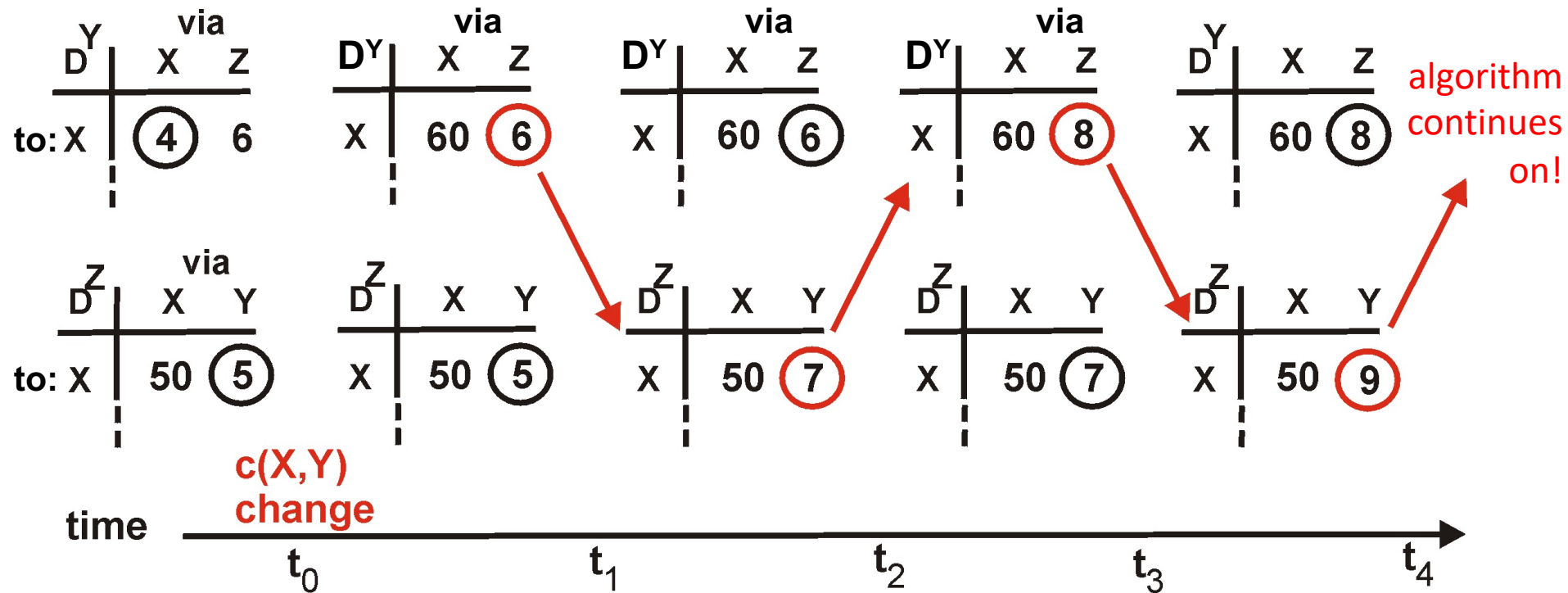
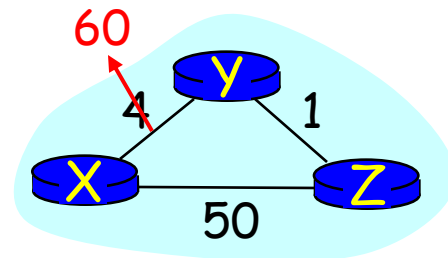
- Link cost increases and failures
 - **“Count to infinity”** problem!



Distance Vector: Link Cost Increase

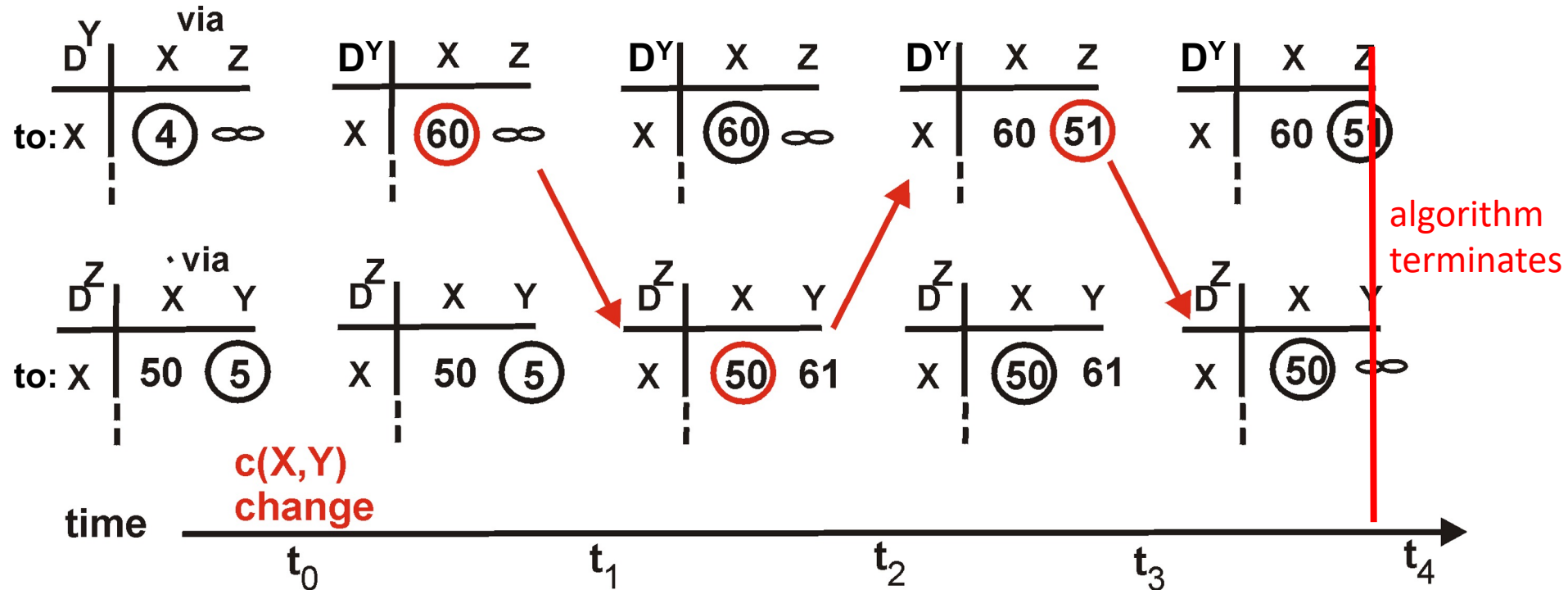
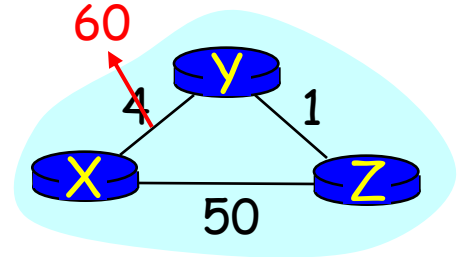
- Link cost increases and failures

– “Count to infinity” problem!



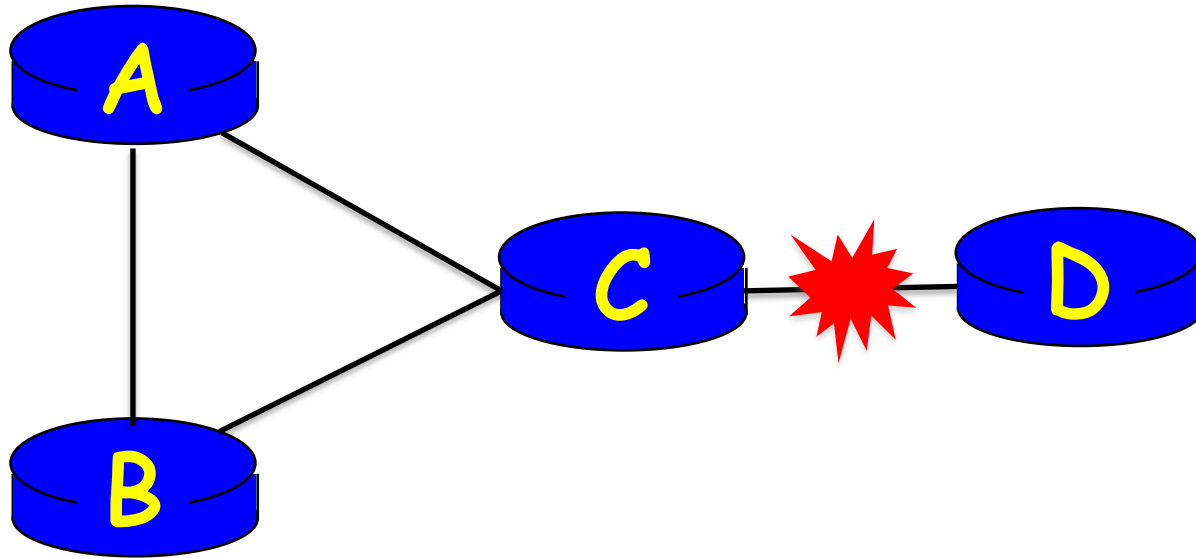
Distance Vector: Poison Reverse

- If Z routes through Y to X,
then Z tells Y its (Z's) distance to X is ∞
(so Y won't route to X via Z)



Distance Vector: Poison Reverse

- Can still have problems in larger networks



1. A and B use ACD and BCD, so A and B both “poison” to C.
2. But when CD withdrawn (cost goes to infinity), B switches to BACD, so BC no longer poisoned to C.
3. C then starts using CBACD. Loop.

Redefining Infinity

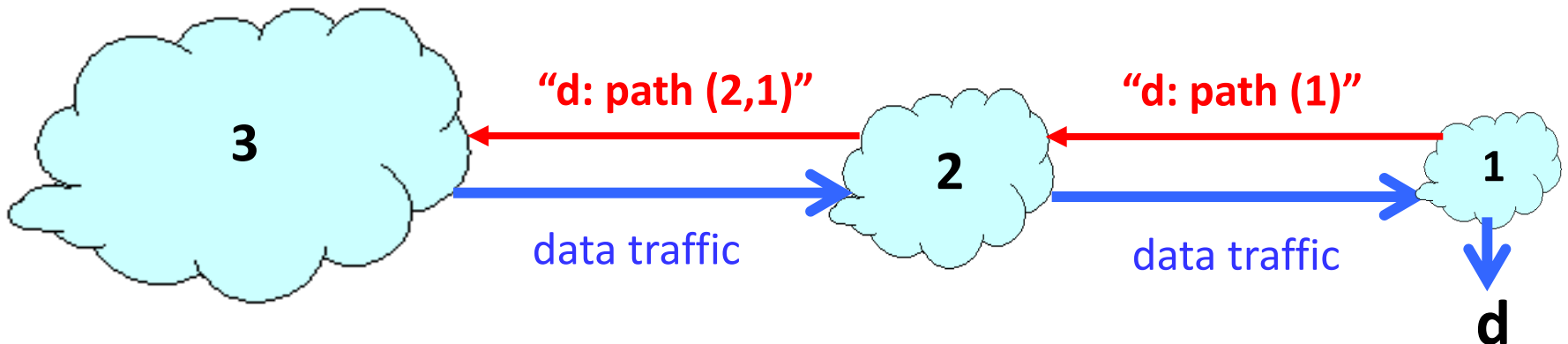
- Avoid “counting to infinity”
 - By making “infinity” smaller!
- Routing Information Protocol (RIP)
 - All links have cost 1
 - Valid path distances of 1 through 15
 - ... with 16 representing infinity
- Used mainly in small networks

Reducing Convergence Time With Path-Vector Routing

(*e.g.*: Border Gateway Protocol)

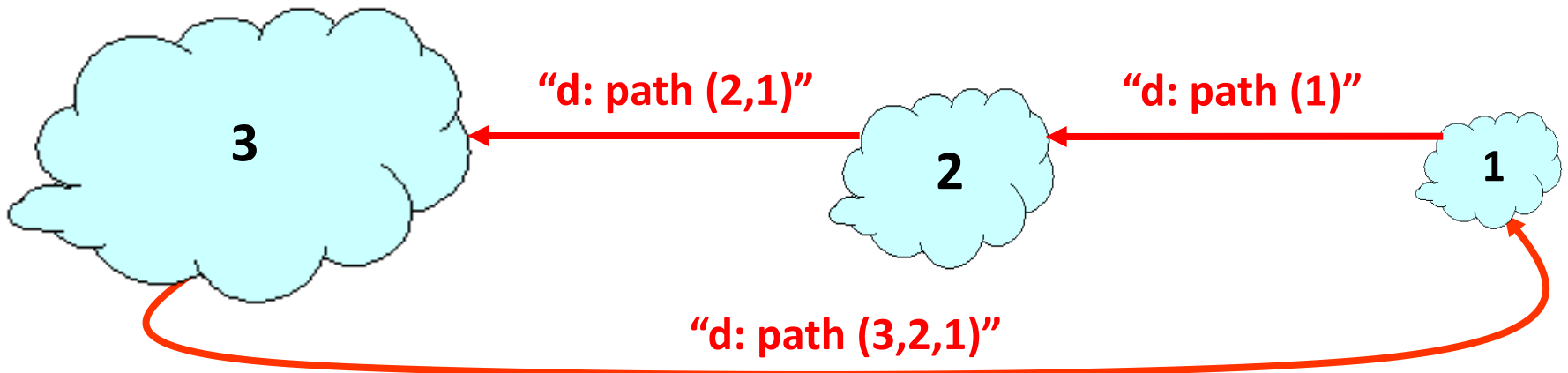
Path-Vector Routing

- Extension of distance-vector routing
 - Support flexible routing policies
 - Avoid count-to-infinity problem
- Key idea: advertise the entire path
 - Distance vector: send distance metric per dest d
 - Path vector: send the entire path for each dest d



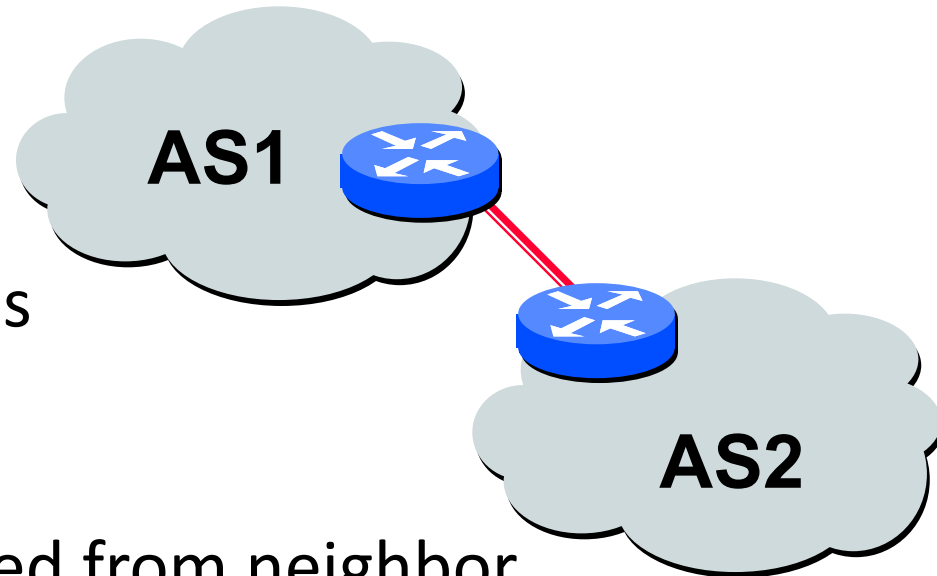
Faster Loop Detection

- Node can easily detect a loop
 - Look for its own node identifier in the path
 - E.g., node 1 sees itself in the path “3, 2, 1”
- Node can simply discard paths with loops
 - E.g., node 1 simply discards the advertisement

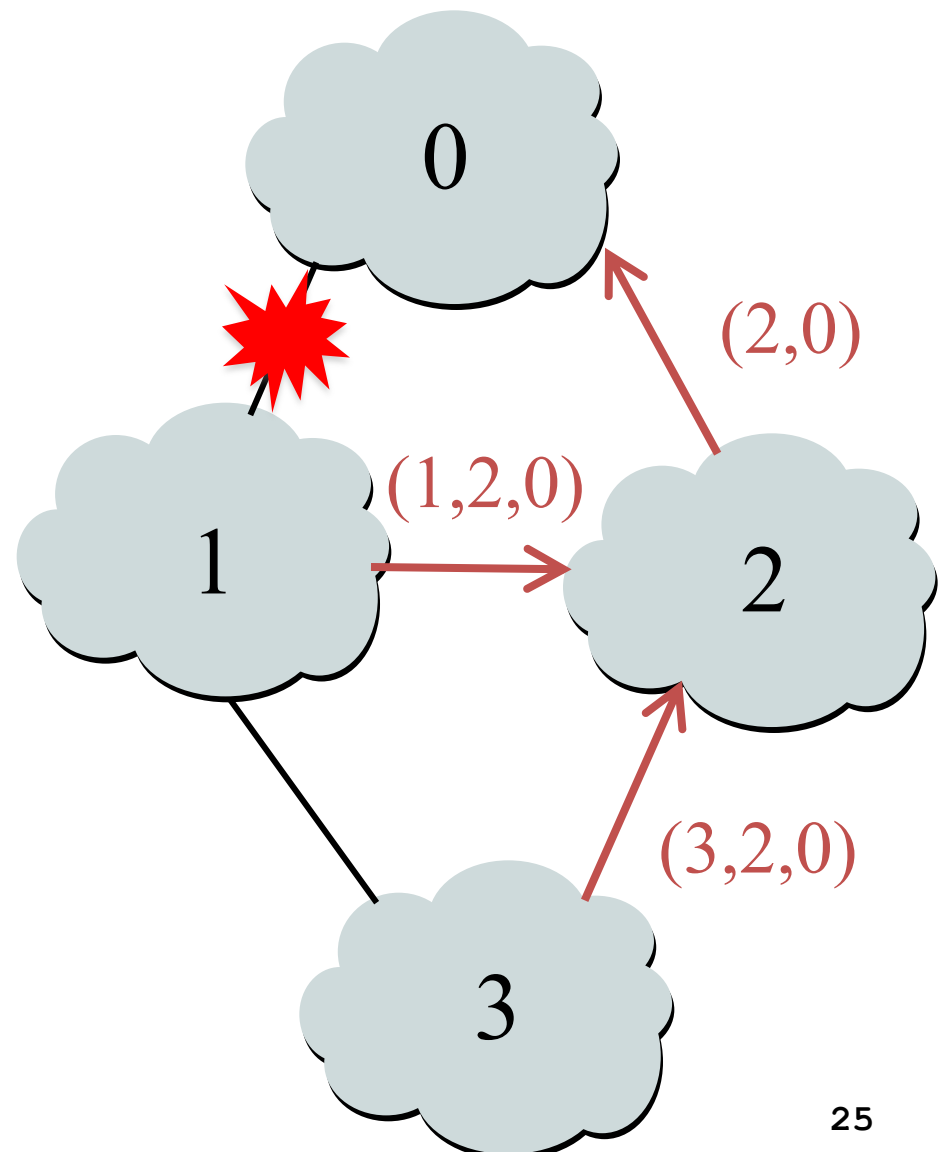
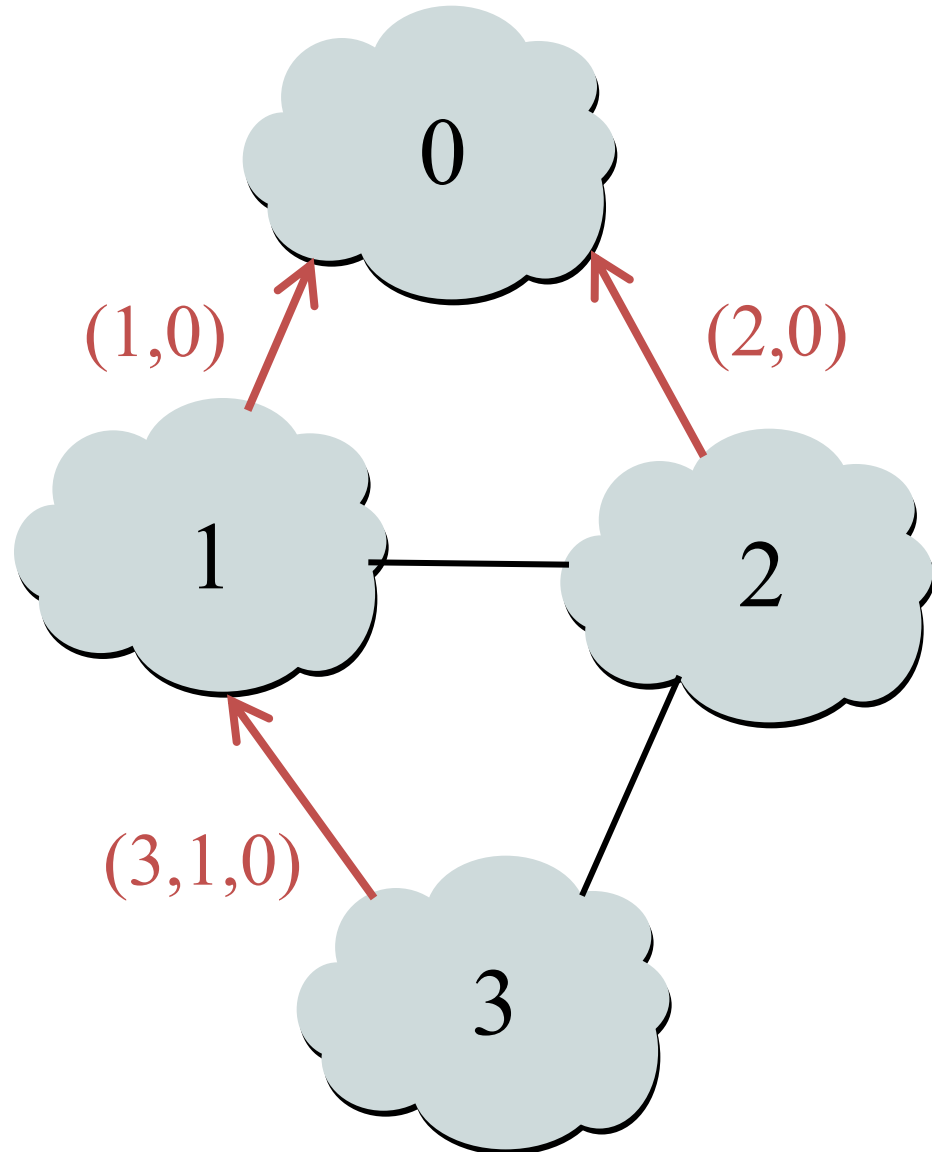


BGP Session Failure

- **BGP runs over TCP**
 - BGP only sends updates when changes occur
 - TCP doesn't detect lost connectivity on its own
- **Detecting a failure**
 - Keep-alive: 60 seconds
 - Hold timer: 180 seconds
- **Reacting to a failure**
 - Discard all routes learned from neighbor
 - Send new updates for any routes that change



Routing Change: Before and After



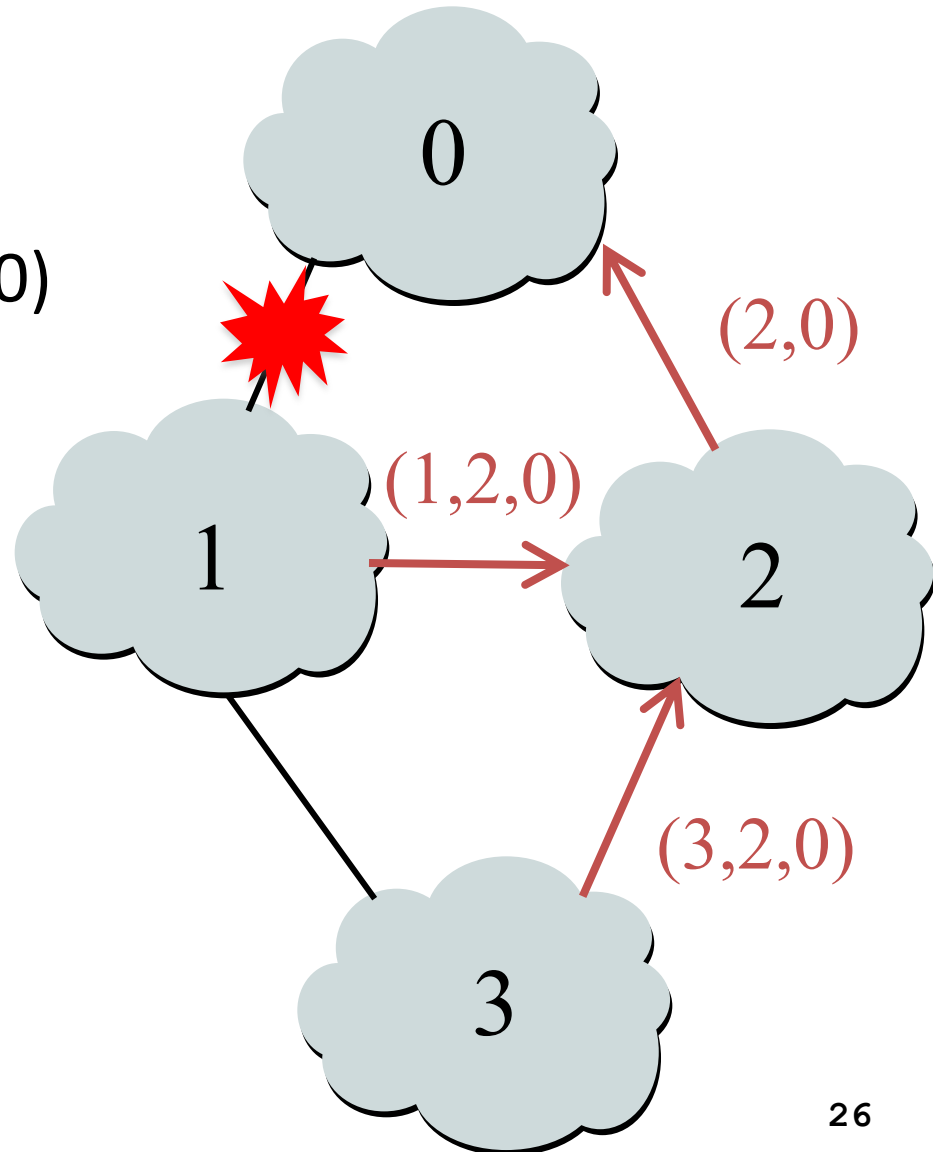
Routing Change: Path Exploration

- **AS 1**

- Delete the route (1,0)
- Switch to next route (1,2,0)
- Send route (1,2,0) to AS 3

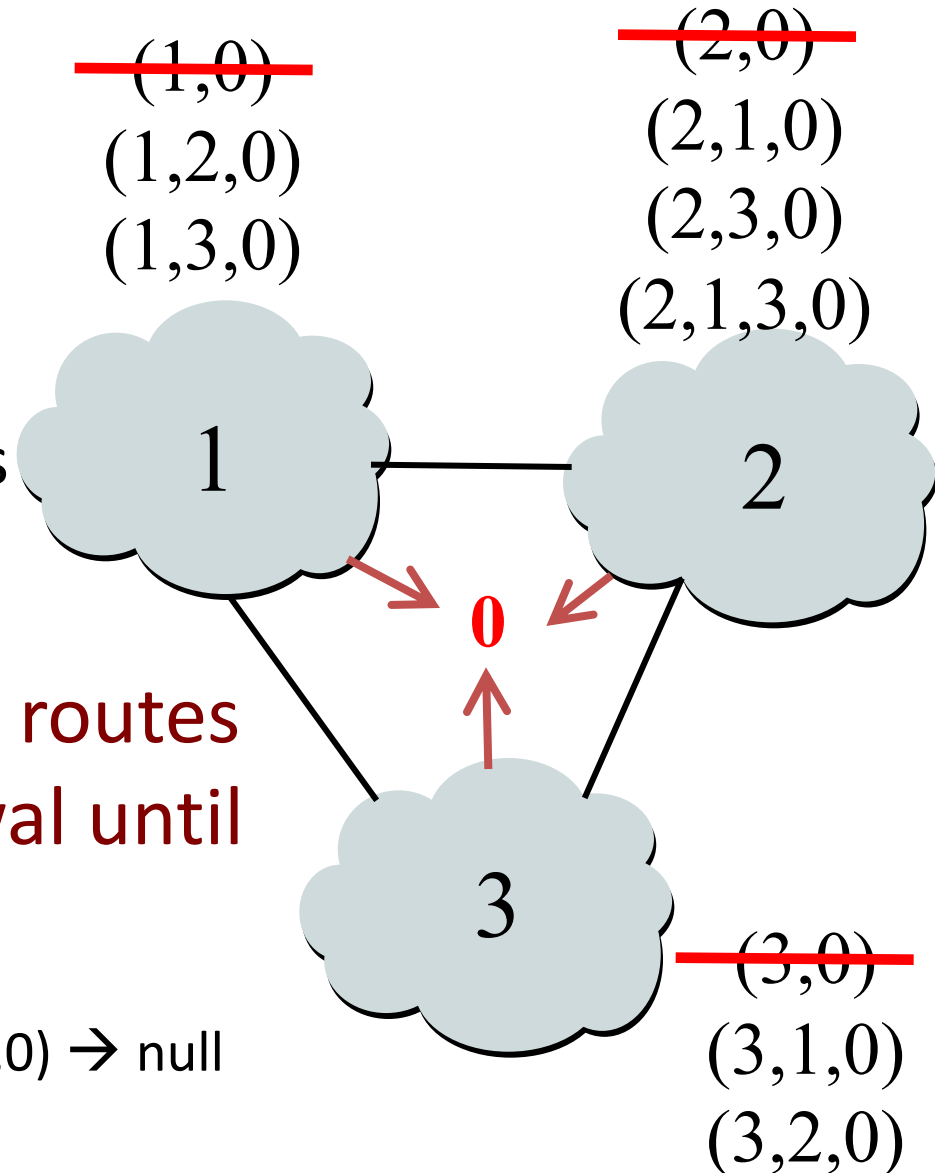
- **AS 3**

- Sees (1,2,0) replace (1,0)
- Compares to route (2,0)
- Switches to using AS 2



Routing Change: Path Exploration

- Initial: All AS use direct
- Then destination 0 dies
 - All ASes lose direct path
 - All switch to longer paths
 - Eventually withdrawn



- How many intermediate routes following (2,0) withdrawal until no route known to 2?

(2,0) → (2,1,0) → (2,3,0) → (2,1,3,0) → null

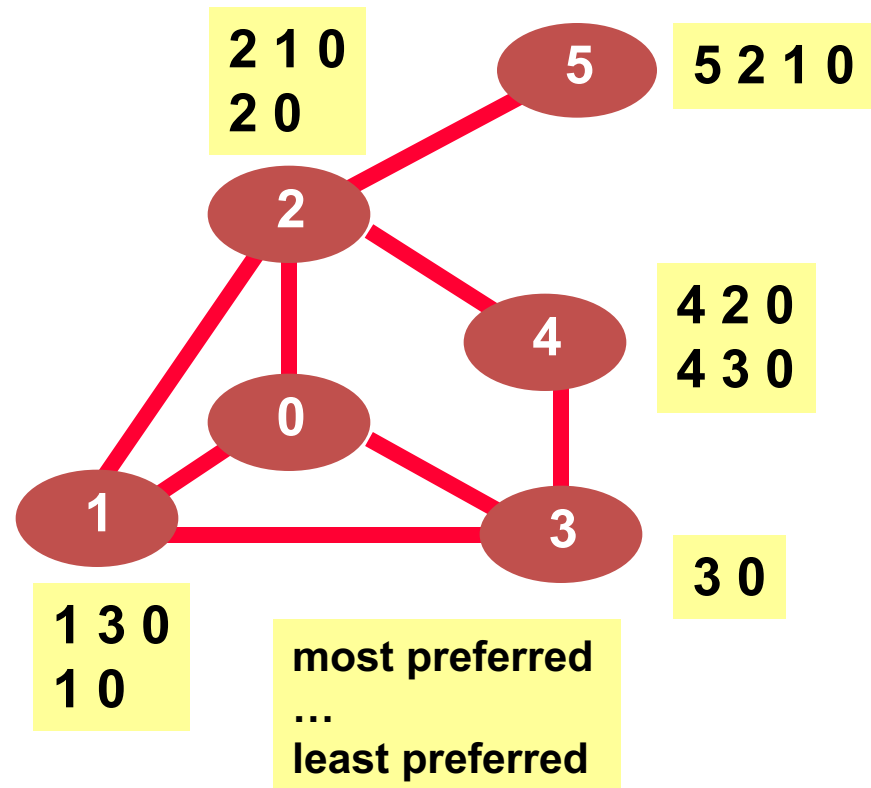
BGP Converges Slowly

- **Path vector avoids count-to-infinity**
 - But, ASes still must explore many alternate paths to find highest-ranked available path
- **Fortunately, in practice**
 - Most popular destinations have stable BGP routes
 - Most instability lies in a few unpopular destinations
- **Still, lower BGP convergence delay is a goal**
 - Can be tens of seconds to tens of minutes

BGP Instability

Stable Paths Problem (SPP) Instance

- **Node**
 - BGP-speaking router
 - Node 0 is destination
- **Edge**
 - BGP adjacency
- **Permitted paths**
 - **Set** of routes to 0 at each node
 - **Ranking** of the paths



SPP Solution

- **Solution is:**

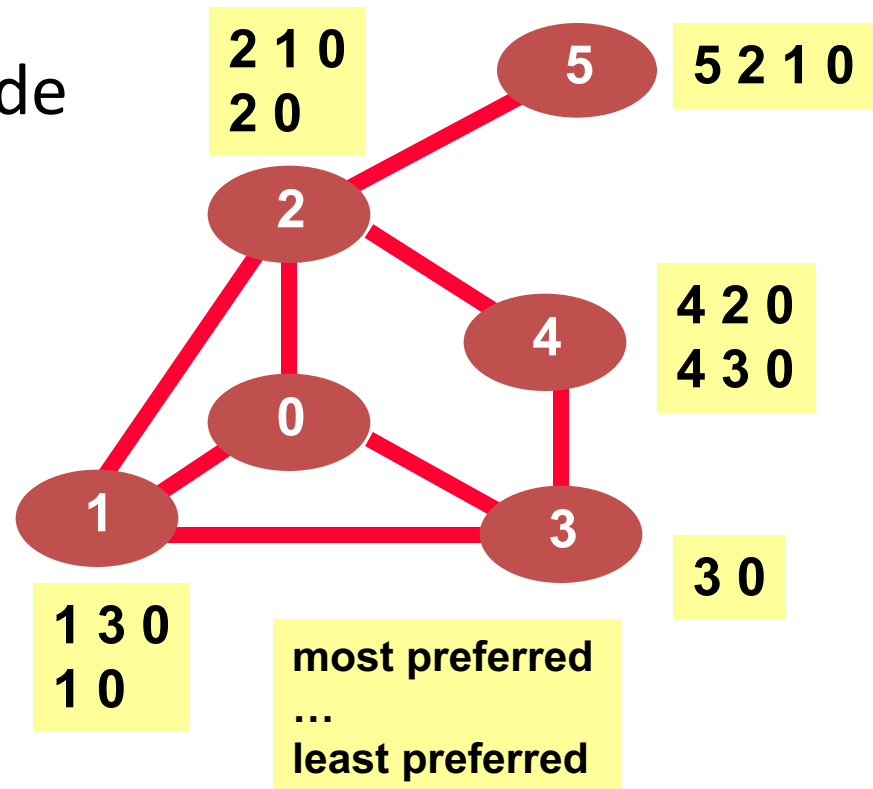
- Path assignments per node
 - Can be the “null” path

- **If node u has path uwP**

- $\{u,w\}$ is edge in graph
- w is assigned path wP

- **Each node is assigned**

- Highest ranked path consistent with its neighbors



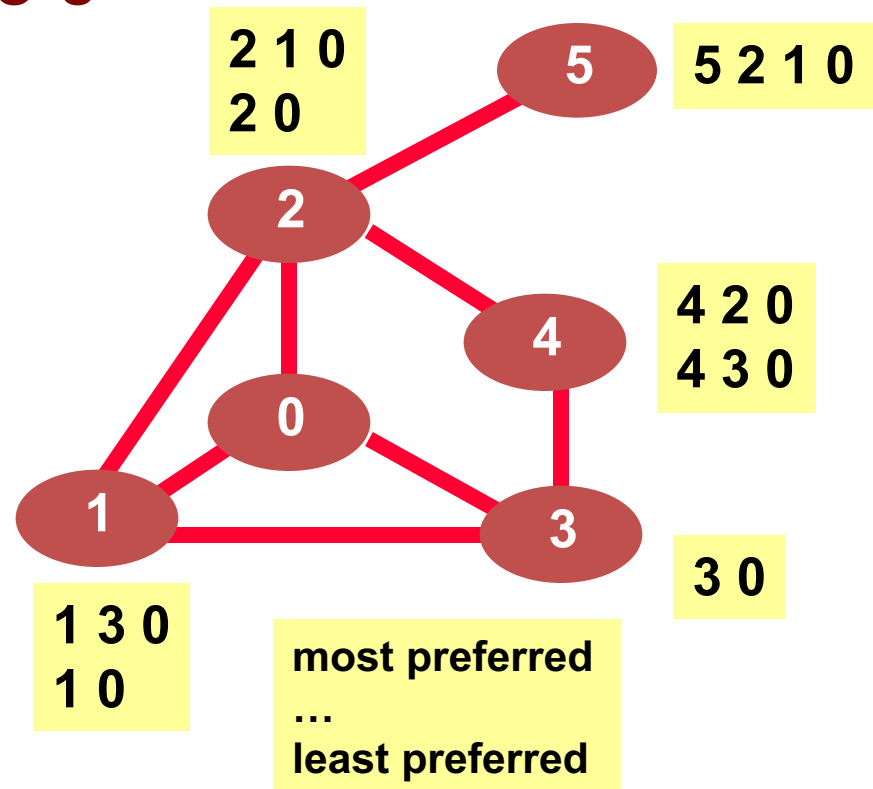
Stable Paths Problem (SPP) Instance

- 1 will use a direct path to 0

(Y) True (M) False

- 5 has a path to 0

(Y) True (M) False



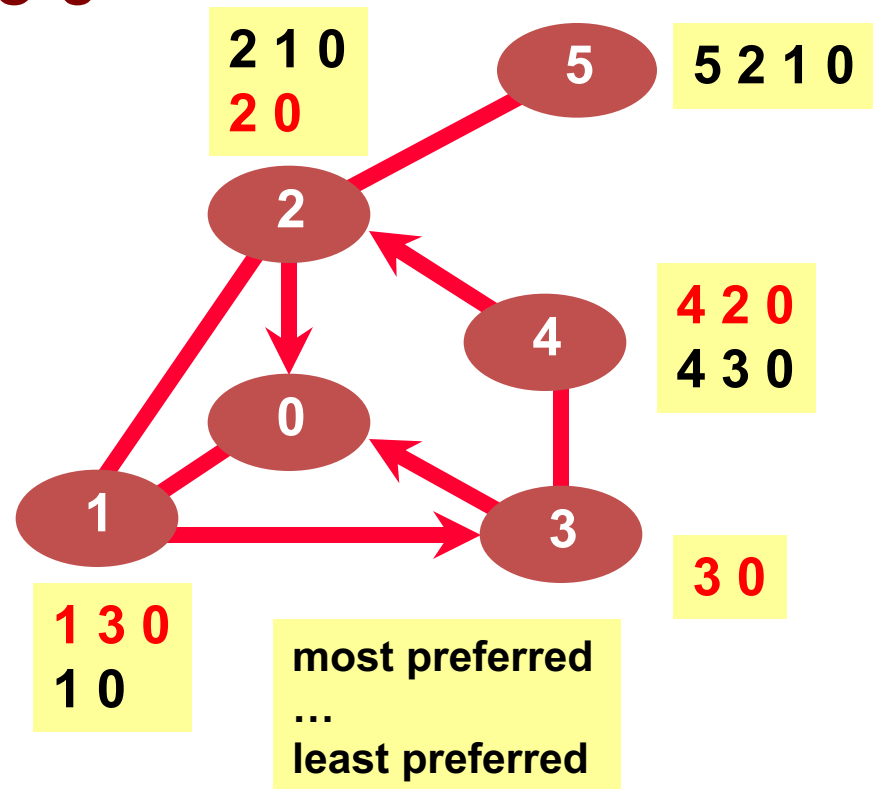
Stable Paths Problem (SPP) Instance

- 1 will use a direct path to 0

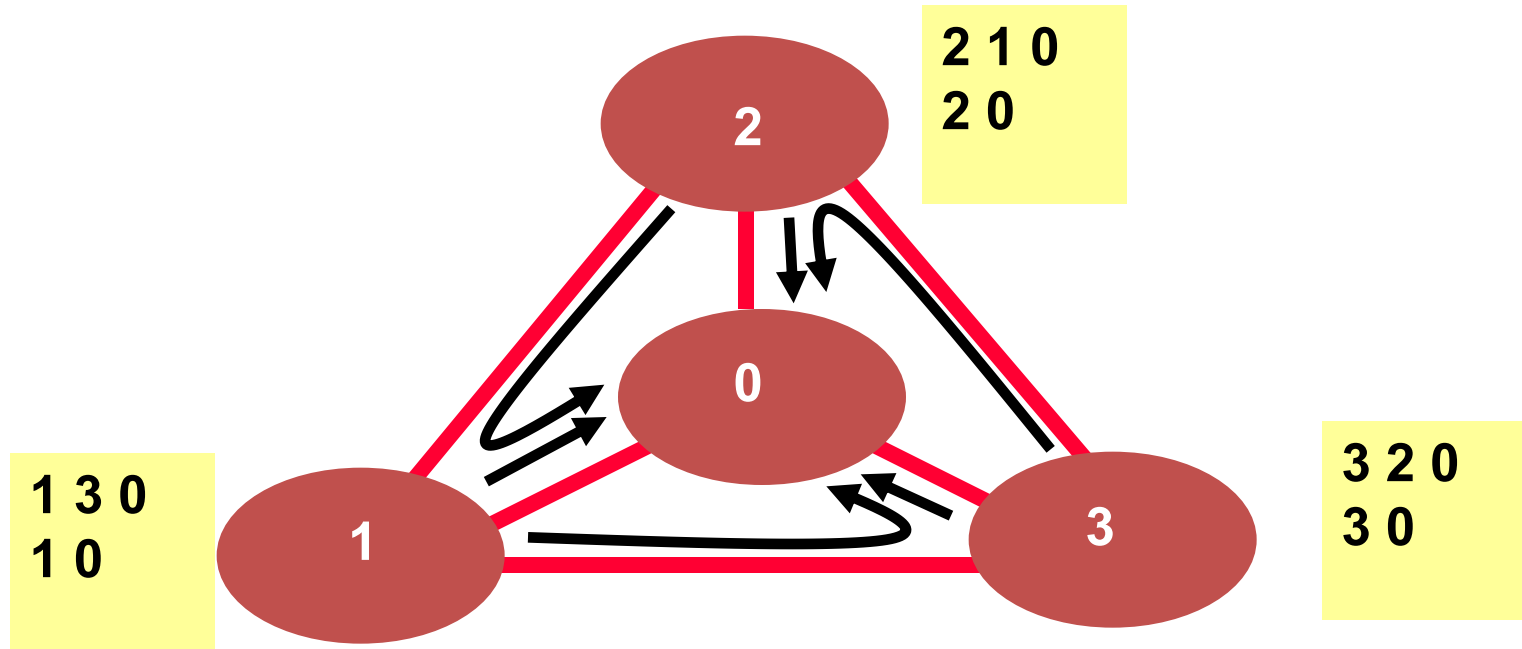
(Y) True (M) False

- 5 has a path to 0

(Y) True (M) False



An SPP May Have No Solution



Avoiding BGP Instability

- **Detecting conflicting policies**
 - Computationally expensive
 - Requires too much cooperation
- **Detecting oscillations**
 - Observing the repetitive BGP routing messages
- **Restricted routing policies and topologies**
 - Policies based on business relationships

Conclusion

- **The only constant is change**
 - Planned topology and configuration changes
 - Unplanned failure and recovery
- **Routing-protocol convergence**
 - Transient period of disagreement
 - Blackholes, loops, and out-of-order packets
- **Routing instability**
 - Permanent conflicts in routing policy
 - Leading to bi-stability or oscillation