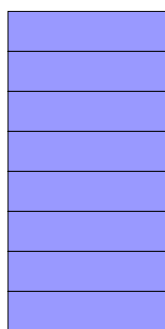


# X86 assembly quick tutorial (real mode)

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## The State Machine

Memory



CPU

Instruction pointer

The CPU program:

```
while (TRUE)
{
    fetch the instruction
    execute the instruction
    (update the instruction pointer)
}
```

What instructions do:

- Change the state of CPU
  - ALU operation
  - Jumps
- Read data from memory
- Write data to memory

# CPU State: Register Set

General-purpose registers 16bit 32bit

	AH	AL	AX	EAX
	BH	BL	BX	EBX
	CH	CL	CX	ECX
	DH	DL	DX	EDX
	BP			EBP
	SI			ESI
	DI			EDI
	SP			ESP

Segment registers (16bit)

CS
DS
SS
ES
FS
GS

Flags (32bit)

EFLAGS
--------

Instruction Pointer (32bit)

EIP
-----

Address the register by: %ax, %ebx, etc

# A little bit on EFLAGS

Function of EFLAGS:

- Control the behavior of CPU
- Save the status of last instruction

Bit	Name	Comment
0	CF: carry flag	
6	ZF: zero flag	
7	SF: sign flag	
9	IF: interrupt	sti; cli;
10	DF: direction	std; cld;
11	OF: overflow	

## Memory Addressing

Format:

**segment:displacement(base, index)**

Offset = Base + Index + Displacement

Address = (Segment << 4) + Offset

Displacement: constant

Base: %bx, %bp

Index: %si, %di

Segment: %cs, %ds, %ss, %es

## Memory Addressing (data)

**segment:displacement(base, index)**

■ The components are all optional

■ Default segment:

- %bp: %ss
- %bx, %si, %di: %ds

■ Examples

100  
(%si) = %ds:(%si)  
(%bp) = %ss:(%bp)  
(%bx,%si) = %ds:(%bx,%si)  
-10(%bp) = %ss:-10(%bp)  
%ds:-10(%bx, %si)

## Instructions: arithmetic & logic

- `add/sub{l,w,b} source, dest`
- `inc/dec/neg{l,w,b} dest`
- `cmp{l,w,b} source, dest`
- `and/or/xor{l,w,b} source, dest`
- ...
- Restrictions
  - No more than one memory operand

## Instructions: Data Transfer

- `mov{lwb} source, dest`
- `xchg{lwb} source, dest`
  - Segment registers can only appear with registers
- `movsb`
  - `movb %ds:(%si) %es:(%di)`
  - $\%si \leftarrow \%si + inc$
  - $\%di \leftarrow \%di + inc$       If DF = 0 then inc = 1  
                                         else inc = -1
  - $\%cx \leftarrow \%cx - 1$
  - Often used with `%cx` to move a number of bytes

## Example

- Move 0x200 bytes from 0x0100:0x0000 to 0x0080:0x0000

```
movw $0x0100, %ax
movw %ax, %ds      /* setup %ds */
movw $0x0080, %ax
movw %ax, %es      /* setup %es */
movw $0, %ax
movw %ax, %si      /* setup %si */
movw %ax, %di      /* setup %di */
movw $0x200, %cx
cld                /* setup direction flag */
repeat:
movsb
cmp $0, %cx
jnz repeat
```

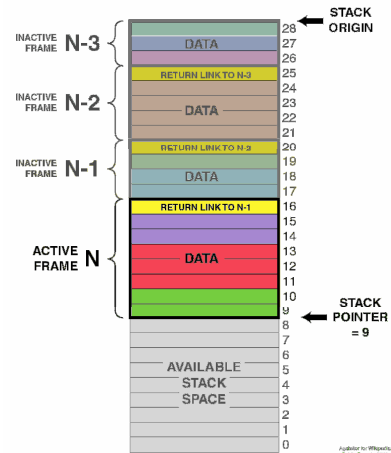
## Example (cont.)

- Move 0x200 bytes from 0x0100:0x0000 to 0x0080:0x0000

```
movw $0x0100, %ax
movw %ax, %ds      /* setup %ds */
movw $0x0080, %ax
movw %ax, %es      /* setup %es */
movw $0, %ax
movw %ax, %si      /* setup %si */
movw %ax, %di      /* setup %di */
movw $0x200, %cx
cld                /* setup direction flag */
rep
movsb
```

## Instructions: stack access

- **pushw source**
  - $\%sp \leftarrow \%sp - 2$
  - $\%ss:(\%sp) \leftarrow \text{source}$
- **popw dest**
  - $\text{dest} \leftarrow \%ss:(\%sp), \text{dest}$
  - $\%sp \leftarrow \%sp + 2$
- **Setup up the stack before you actually use it**



## Instructions: unconditional jump

- **jmp label**
  - $\%ip \leftarrow \text{label}$
- **ljmp NEW\_CS, offset**
  - $\%ip \leftarrow \text{label}; \%cs \leftarrow \text{NEW\_CS}$
- **call label**
  - push  $\%ip + ?$  (address of call instruction)
  - $\%ip \leftarrow \text{label}$
- **ret**
  - pop  $\%ip$
- Also **lcall** and **lret**

## Instructions: conditional jump

- **j\* label**: jump to label if flag \* is 1
- **jn\* label**: jump to label if flag \* is 0
- \*: bits of %eflags  
Examples: js, jz, jc, jns, jnz, jnc, ...

## BIOS Service

- Use BIOS service through interruption
  - Store the parameters to the registers
  - Call the interruption
- **int INT\_NUM**

## Example: BIOS INT 0x13 Function 2

- ah = 2
- al = number of sectors to read
- ch = cylinder number bits 0-8
- cl, bits 6&7 = cylinder number bits 8-9.
- bits 0-5 = starting sector number, 1 to 63
- dh = starting head number, 0 to 255
- dl = drive number
- es:bx = pointer where to place information read from diskette
  
- Returns:
- ah = return status (0 if successful)
- carry = 0 successful, = 1 if error occurred

## Note for project 1

- In our project, the bootloader is working in real mode (16 bits).
- Bootloader code is loaded by BIOS, so it did not have %ds, %ss, %sp setup properly when it is loaded.
- In bootloader, all the code and data share the same 512 bytes. So data will have the same segment as code.