COS 318: Operating Systems
 Implementing Threads

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(http://www.cs.princeton.edu/courses/cos318/)



# Today's Topics

- Non-preemptive versus preemptive threads
- Kernel vs. user threads
- Too many cookies problem

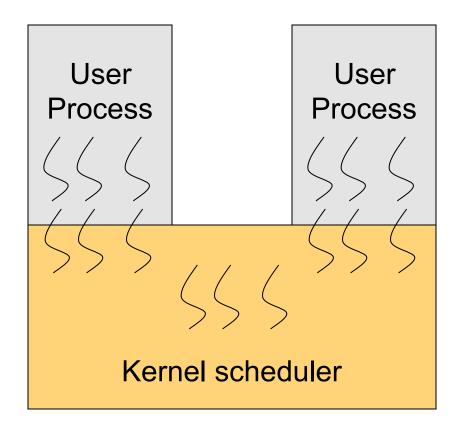


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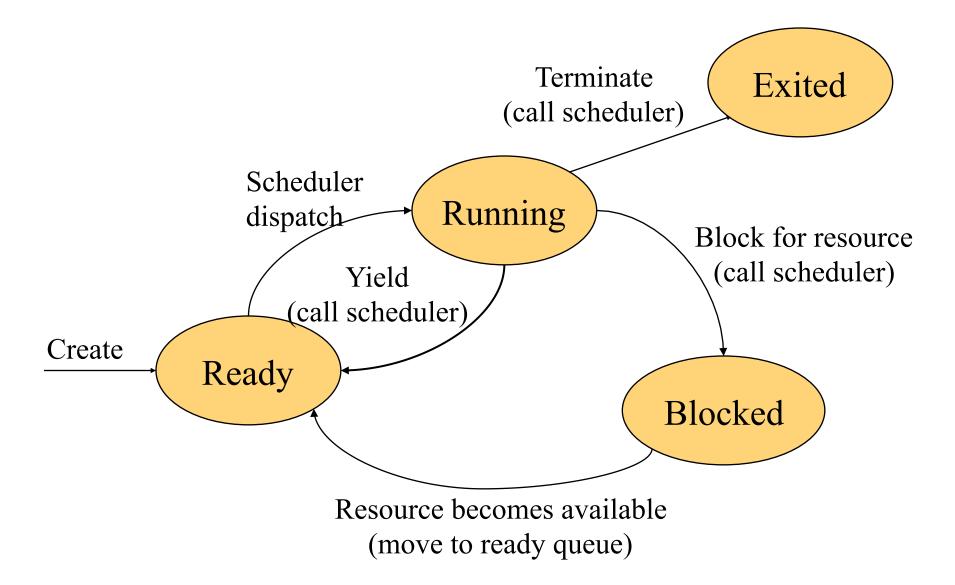
# Revisit Monolithic OS Structure

- Kernel has its address space, shared with all processes
- Kernel consists of
  - Boot loader
  - BIOS
  - Key drivers
  - Threads
  - Scheduler
- Scheduler
  - Use a ready queue to hold all ready threads
  - Schedule in a thread with the same address space (thread context switch)
  - Schedule in a thread with a different address space (process context switch)





### **Non-Preemptive Scheduling**





### Scheduler

- A non-preemptive scheduler invoked by calling
  - block()
  - yield()
- The simplest form
   Scheduler:

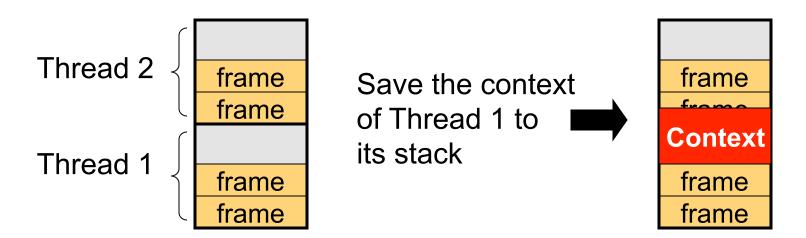
save current process/thread state choose next process/thread to run dispatch (load PCB/TCB and jump to it)

Scheduler can be viewed as just another kernel thread



# Where and How to Save Thread Context?

- Save the context on the thread's stack
  - Many processors have a special instruction to do it efficiently
  - But, need to deal with the overflow problem
- Check before saving
  - Make sure that the stack has no overflow problem
  - Copy it to the TCB residing in the kernel heap
  - Not so efficient, but no overflow problems



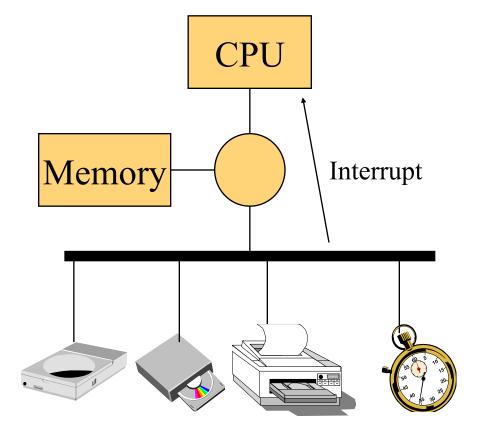


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# Preemption

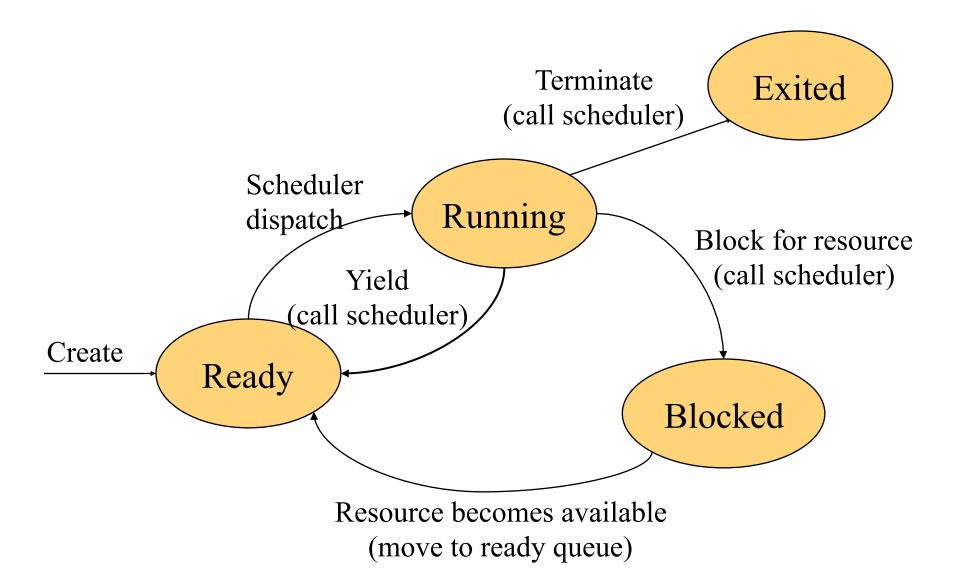
### Why

- Timer interrupt for CPU management
- Asynchronous I/O completion
- Interrupts
  - Between instructions
  - Within an instruction, except atomic ones
- Manipulate interrupts
  - Disable (mask) interrupts
  - Enable interrupts
  - Non-Masking Interrupts



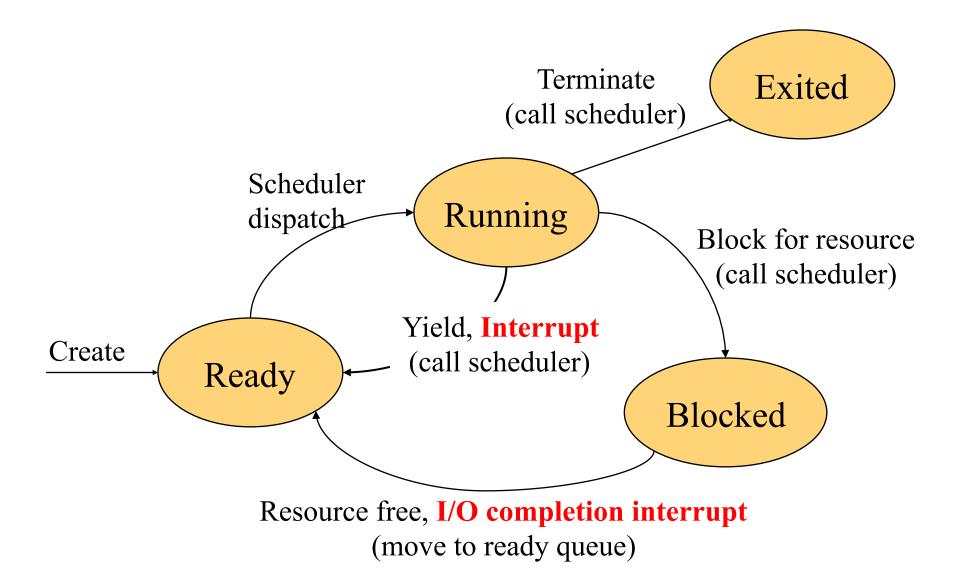


#### State Transition for Non-Preemptive Scheduling





### State Transition for Preemptive Scheduling





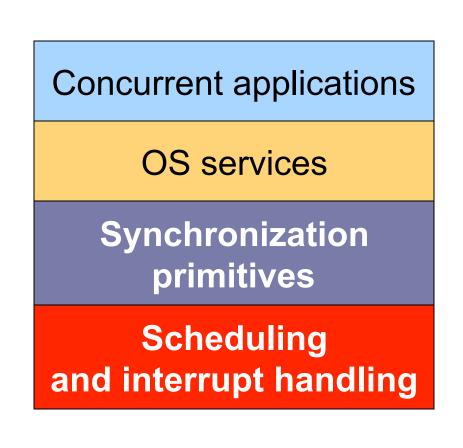
### Interrupt Handling for Preemptive Scheduling

- Timer interrupt handler:
  - Save the current process / thread to its PCB / TCB
  - ... (What to do here?)
  - Call scheduler
- I/O interrupt handler:
  - Save the current process / thread to its PCB / TCB
  - Do the I/O job
  - Call scheduler
- Issues
  - Disable/enable interrupts
  - Make sure that it works on multiprocessors



# Dealing with Preemptive Scheduling

- Problem
  - Interrupts can happen anywhere
- An obvious approach
  - Worry about interrupts and preemptions all the time
- What we want
  - Worry less of the time
  - Low-level behavior encapsulated in "primitives"
  - Synchronization primitives worry about preemption
  - OS and applications use synchronization primitives

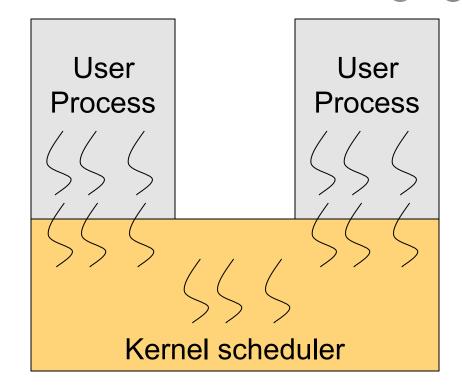




## User Threads vs. Kernel Threads



- Context switch at user-level without a system call (Java threads)
- Is it possible to do preemptive scheduling?
- What about I/O events?



- A user thread
  - Makes a system call (e.g. I/O)
  - Gets interrupted
- Context switch in the kernel



# Summary of User vs. Kernel Threads

#### User-level threads

- User-level thread package implements thread context switches
- OS doesn't know the process has multiple threads
- Timer interrupt (signal facility) can introduce preemption
- When a user-level thread is blocked on an I/O event, the whole process is blocked
- Allows user-level code to build custom schedulers

#### Kernel-threads

- Kernel-level threads are scheduled by a kernel scheduler
- A context switch of kernel-threads is more expensive than user threads due to crossing protection boundaries

### Hybrid

• It is possible to have a hybrid scheduler, but it is complex



### Interactions between User and Kernel Threads

#### Two approaches

- Each user thread has its own kernel stack
- All threads of a process share the same kernel stack

	Private kernel stack	Shared kernel stack
Memory usage	More	Less
System services	Concurrent access	Serial access
Multiprocessor	Yes	Not within a process
Complexity	More	Less



# "Too Many Cookies" Problem

- Want cookies, but don't want to buy too many cookies
- Any person can be distracted at any point

	RoomMate A	RoomMate B
15:00	Look in cabinet: out of cookies	
15:05	Leave for Wawa	
15:10	Arrive at Wawa	Look at fridge: out of cookies
15:15	Buy a bag of cookies	Leave for Wawa
15:20	Arrive home; put cookies away	Arrive at Wawa
15:25		Buy a bag of cookies
		Arrive home; put cookies away Oh No! Too many cookies.



### Thread A

if (noCookies) {
 if (noNote) {
 leave note;
 buy cookies;
 remove note;
 }

#### Thread B

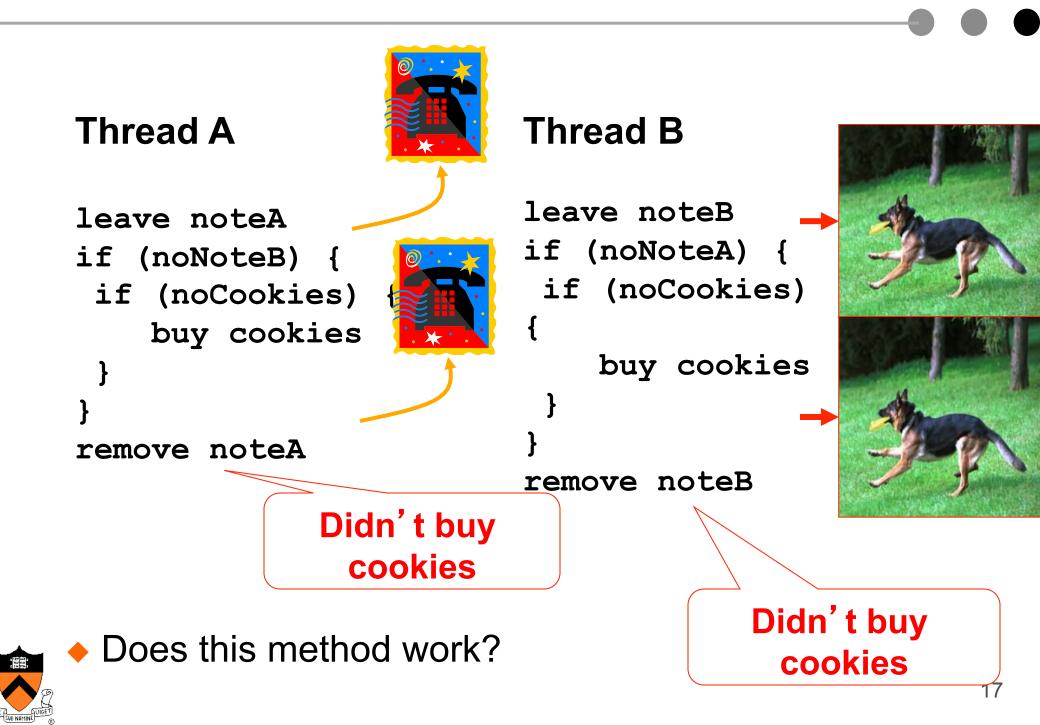
if (noCookies) {
 if (noNote) {
 leave note;
 buy cookies;
 remove note;



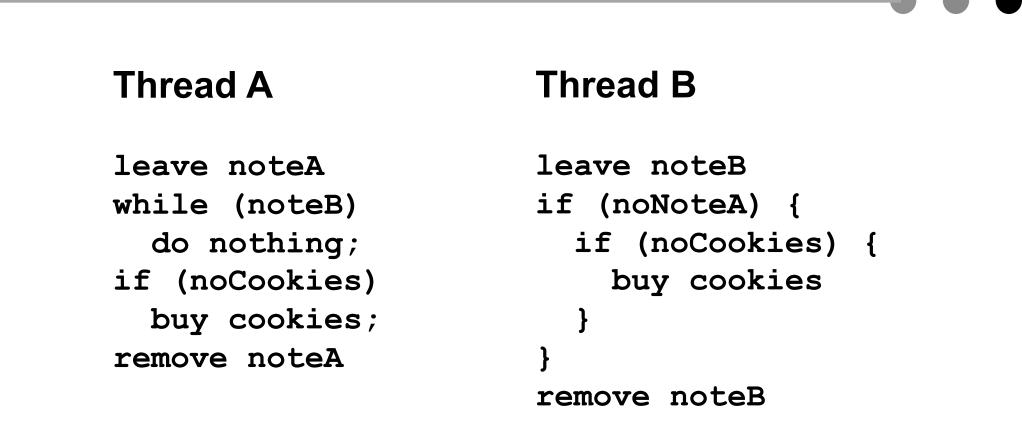
Any issue with this approach?



### **Another Possible Solution?**



### Yet Another Possible Solution?



#### Would this fix the problem?



### Remarks

#### The last solution works, but

- Life is too complicated
- A's code is different from B's
- Busy waiting is a waste
- What we want is:

Acquire(lock);
if (noCookies)
 buy cookies;
Release(lock);

**Critical section** 



## What Is A Good Solution

- Only one process/thread inside a critical section
- No assumption about CPU speeds
- A process/thread inside a critical section should not be blocked by any process outside the critical section
- No one waits forever
- Works for multiprocessors
- Same code for all processes/threads



# Summary

#### Non-preemptive threads issues

- Scheduler
- Where to save contexts
- Preemptive threads
  - Interrupts can happen any where!
- Kernel vs. user threads
  - Main difference is which scheduler to use
- Too many cookies problem
  - What we want is mutual exclusion

