COS 318: Operating Systems Message Passing

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http://www.cs.princeton.edu/courses/archive/fall11/cos318/



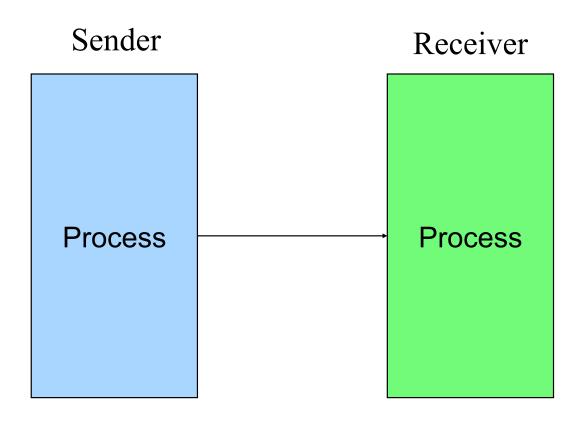


Today's Topics

- Message passing
 - Semantics
 - How to use
- Implementation issues
 - Synchronous vs. asynchronous
 - Buffering
 - Indirection
 - Exceptions

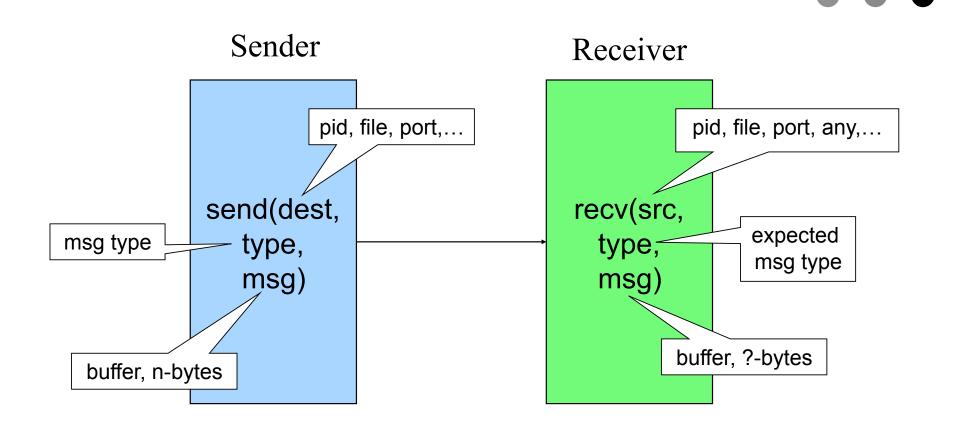


Big Picture





Send and Receive Primitives

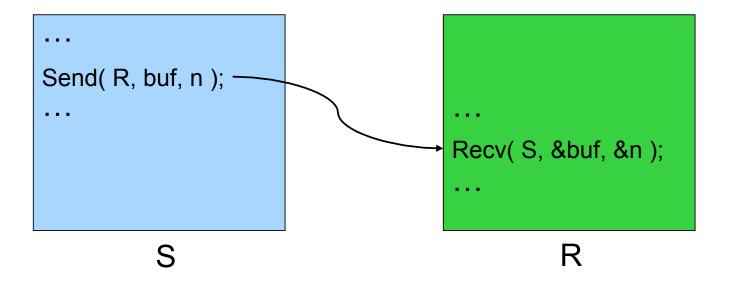


Many ways to design the message passing API



Synchronous Message Passing

- Move data between processes
 - Sender: when data is ready, send it to the receiver process
 - Receiver: when the data has arrived and when the receive process is ready to take the data, move the data
- Synchronization
 - Sender: signal the receiver process that a particular event happens
 - Receiver: block until the event has happened





Example: Producer-Consumer

```
Producer() {
    ...
    while (1) {
        produce item;
        recv(Consumer, &credit);
        send(Consumer, item);
    }
}
```

```
Consumer() {
    ...
    for (i=0; i<N; i++)
        send(Producer, credit);
    while (1) {
        recv(Producer, &item);
        send(Producer, credit);
        consume item;
    }
}</pre>
```

Questions

- Does this work?
- Would it work with multiple producers and 1 consumer?
- Would it work with 1 producer and multiple consumers?
- What about multiple producers and multiple consumers?



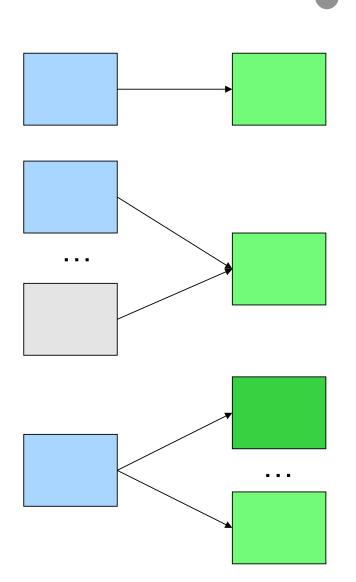
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Implementation Issues

- Buffering messages
- Direct vs. indirect
- Unidirectional vs.
 bidirectional
- Asynchronous vs. synchronous
- Event handler vs. receive
- How to handle exceptions?





Buffering Messages

No buffering

- Sender must wait until the receiver receives the message
- Rendezvous on each message

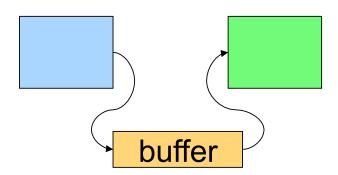


Bounded buffer

- Finite size
- Sender blocks on buffer full
- Use mesa-monitor to solve the problem

Unbounded buffer

- "Infinite" size
- Sender never blocks



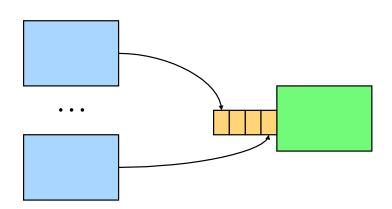


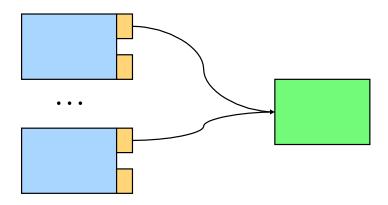
Direct Communication

- A single buffer at the receiver
 - More than one process may send messages to the receiver
 - To receive from a specific sender, it requires searching through the whole buffer



- A sender may send messages to multiple receivers
- To get a message, it also requires searching through the whole buffer

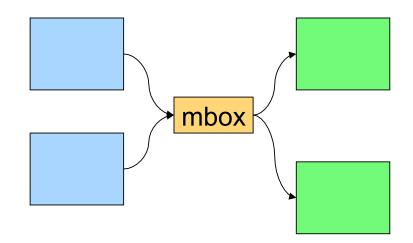


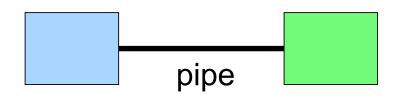




Indirect Communication

- Use mailbox as the abstraction
 - Allow many-to-many communication
 - Require open/close a mailbox
- Buffering
 - A buffer, its mutex and condition variables should be at the mailbox
- Message size
 - Not necessarily. One can break a large message into packets
- Mailbox vs. pipe
 - A mailbox allows many to many communication
 - A pipe implies one sender and one receiver







Synchronous vs. Asynchronous: Send

Synchronous

- Block on if resource is busy
- Initiate data transfer
- Block until data is out of its source memory

send(dest, type, msg)

msg transfer resource

Asynchronous

- Block if resource is busy
- Initiate data transfer and return
- Completion
 - Require applications to check status
 - Notify or signal the application

```
status = async_send( dest, type, msg )
...
if !send_complete( status )
   wait for completion;
...
use msg data structure;
```



Synchronous vs. Asynchronous: Receive

Synchronous

Return data if there is a message

msg transfer resource

recv(src, type, msg)

- Asynchronous
 - Return data if there is a message
 - Return status if there is no message (probe)

```
status = async_recv( src, type, msg );
if ( status == SUCCESS )
   consume msg;
```

```
while ( probe(src) != HaveMSG )
    wait for msg arrival
recv( src, type, msg );
consume msg;
```



Event Handler vs. Receive

- hrecv(src, type, msg, func)
 - msg is an arg of func
 - Execute "func" on a message arrival
- Which one is more powerful?
 - Recv with a thread can emulate a Handler
 - Handler can be used to emulate recv by using Monitor
- Pros and Cons

```
void func( char * msg ) {
    ...
}
...
hrecv( src, type, msg, func)
...
```

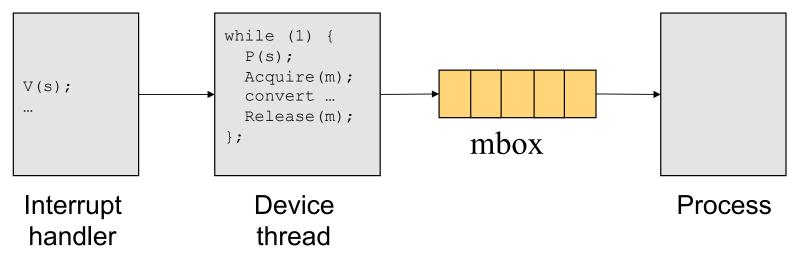
```
Create a thread

while(1) {
  recv(src,type, msg);
  func(msg);
}
```



Example: Keyboard Input

- How do you implement keyboard input?
 - Need an interrupt handler
 - Generate a mbox message from the interrupt handler
- Suppose a keyboard device thread converts input characters into an mbox message
 - How would you synchronize between the keyboard interrupt handler and device thread?
 - How can a device thread convert input into mbox messages?





Exception: Process Termination

- R waits for a message from S, but S has terminated
 - Problem: R may be blocked forever



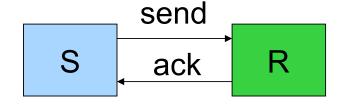
- S sends a message to R, but R has terminated
 - Problem: S has no buffer and will be blocked forever





Exception: Message Loss

- Use ack and timeout to detect and retransmit a lost message
 - Require the receiver to send an ack message for each message
 - Sender blocks until an ack message is back or timeout status = send(dest, msg, timeout);
 - If timeout happens and no ack, then retransmit the message
- Issues
 - Duplicates
 - Losing ack messages





Exception: Message Loss, cont'd

Retransmission must handle

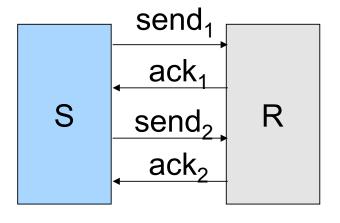
- Duplicate messages on receiver side
- Out-of-sequence ack messages on sender side

Retransmission

- Use sequence number for each message to identify duplicates
- Remove duplicates on receiver side
- Sender retransmits on an out-ofsequence ack

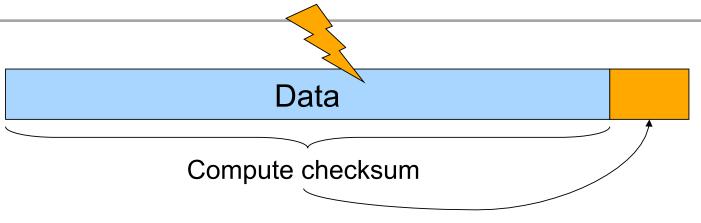
Reduce ack messages

- Bundle ack messages
- Receiver sends noack messages: can be complex
- Piggy-back acks in send messages





Exception: Message Corruption



Detection

- Compute a checksum over the entire message and send the checksum (e.g. CRC code) as part of the message
- Recompute a checksum on receive and compare with the checksum in the message

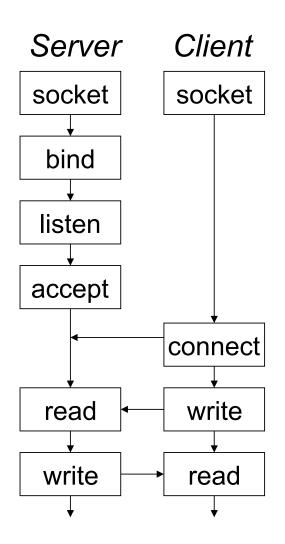
Correction

- Trigger retransmission
- Use correction codes to recover



Example: Sockets API

- Abstraction for TCP and UDP
 - Hides details of network peculiarities
- Addressing
 - IP address and port number (2¹⁶ ports available for users)
- Create and close a socket
 - sockid = socket(af, type,
 protocol);
 - Sockerr = close(sockid);
- Bind a socket to a local address
 - sockerr = bind(sockid, localaddr, addrlength);
- Negotiate the connection
 - listen(sockid, length);
 - accept(sockid, addr, length);
- Connect a socket to destination
 - connect(sockid, destaddr, addrlength);





Summary

- Message passing
 - Move data between processes
 - Implicit synchronization
 - API design is important
- Implementation issues
 - Synchronous method is most common
 - Asynchronous method provides overlapping but requires careful design considerations
 - Indirection makes implementation flexible
 - Exception needs to be carefully handled

