

Final Solutions

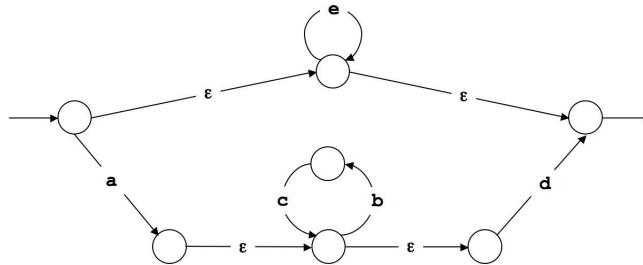
1. Analysis of algorithms.

- (a) It provides a worst-case running time of a sequence of operations, starting from an initially empty data structure. For example, starting from an initially empty Fibonacci heap, any sequence of x INSERT, y DECREASEKEY and z DELETEMIN operations takes at most $k(N + x + y + z \log N)$ steps for some constant $k > 0$.
- (b) Dijkstra's algorithm performs at most V INSERT, E DECREASEKEY and V DELETEMIN operations. Thus, the overall worst-case running time is $O(E + V \log V)$.
- (c) If we could implement INSERT and DELETEMIN in $O(1)$ time, then we could sort N elements in linear time (insert the N elements, then repeatedly delete the minimum). This would violate the $\Omega(N \log N)$ lower bound we have for sorting algorithm that access the data only through pairwise comparisons.

2. String searching.

- (a) Yes. bbbabbb
- (b) No.
- (c) Replace the edge labeled **b** from 2 to 1, and make it go from 2 to 2.

3. Pattern matching.



4. Convex hull.

- (a) H G E F C D B A
- (b)
 1. I H
 2. I H G
 3. I H G E
 4. I H G E F
 5. I H C
 6. I H C D
 7. I H C B
 8. I H C A

5. Geometry.

For simplicity, we assume no two endpoints have the same value.

- (a) The $2N$ events are the left and right endpoints of each interval.
- (b) To implement the sweep line, sort the endpoints and process in ascending order, say using mergesort.
- (c) Store the set of intervals intersecting the sweep line in a priority queue (say, a binary heap), using the right endpoint as the key.
- (d)
 - Left endpoint: insert the interval onto the PQ. Check the number of elements on the PQ, if it is the most so far, record the x value of the current left endpoint.
 - Right endpoint: perform a delete the min on the PQ. This removes the corresponding interval from the PQ.

Note that the PQ isn't strictly needed, since we could just increment a counter when processing a left endpoint, and decrement it when processing a right endpoint.

6. Digraphs and DFS.

- (a) Preorder: A B C F D E G H I.
- (b) Postorder: C F B E I H G D A.
- (c) Topological: A D G H I E B F C.

7. Undirected graphs and BFS.

The key idea is that a shortest cycle is comprised of a shortest path between two vertices, say v and w , that does not include edge $v-w$, plus the edge $v-w$. We can find the shortest such path by deleting $v-w$ from the graph and running breadth-first search from v (or w).

For each edge $v-w$

- Form a graph that is the same as G , except that edge $v-w$ is removed.
- Find the shortest path $\text{dist}(v, w)$ from v to w using BFS.
- Compute $\text{dist}(v, w) + 1$, which corresponds to the cycle consisting of the path from v to w , plus the edge $v-w$.
- If this is shorter than the best cycle found so far, save it.

We run BFS E times and each run takes $O(E + V)$ time. The overall algorithm takes $O(E(E + V))$ time.

Note that if you run BFS from s and stop as soon as you revisit a vertex (using a previously ununused edge), you may not get the shortest path containing s . For example, in the following graph, BFS might consider the edges $s-1$, $s-2$, $s-3$, $1-4$, $2-4$, thereby finding the cycle $s-1-4-2-s$ (instead of the shorter cycle $s-2-3$).

