## Lecture 15: Introduction to Deep Learning

#### COS 429: Computer Vision



## Image Classification: A core task in Computer Vision



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(assume given set of discrete labels) {dog, cat, truck, plane, ...}





## Challenges: Viewpoint variation



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## **Challenges**: Illumination



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## Challenges: Deformation



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### Challenges: Occlusion



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### Challenges: Background Clutter



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This image is CC0 1.0 public domain

### **Challenges**: Intraclass variation



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## An image classifier

def classify\_image(image):
 # Some magic here?
 return class\_label

Unlike e.g. sorting a list of numbers,

**no obvious way** to hard-code the algorithm for recognizing a cat, or other classes.

## Attempts have been made



John Canny, "A Computational Approach to Edge Detection", IEEE TPAMI 1986

## Data-Driven Approach

- 1. Collect a dataset of images and labels
- 2. Use Machine Learning to train a classifier
- 3. Evaluate the classifier on new images

def train(images, labels):
 # Machine learning!
 return model

def predict(model, test\_images):
 # Use model to predict labels
 return test\_labels

airplaneImage: Image: Imag

Example training set

## First classifier: Nearest Neighbor

def train(images, labels):
 # Machine learning!
 return model

Memorize all data and labels

def predict(model, test\_images):
 # Use model to predict labels
 return test\_labels

Predict the label
 of the most similar training image

## Example Dataset: CIFAR10

# 10 classes50,000 training images10,000 testing images

airplane	2	<u> </u>	×		-	J.	-	No.	-
automobile								P.	-
bird	1		1	-	4	r	2	3.	
cat	<b>i</b>					-	in.	-	-
deer	1			m	-	ey.	The second se	1	
dog	<b>7</b>		2	Ø	- 💮	E.		A	590
frog			1	Ser.	1		7	No.	17
horse		en vin	1 PE	家	A	$\mathcal{A}_{\mathcal{A}}$	2	j.	(m)
ship	de -	一道	3	-	-12		1100	-	
truck				200	Harris	and an	1	P.	1

Alex Krizhevsky, "Learning Multiple Layers of Features from Tiny Images", Technical Report, 2009.

## Example Dataset: CIFAR10

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airplane	🎮 🎇	) 	-		
automobile				i 🔁 💽	
bird		1	** *	12	1.2
cat	<b>1</b>				
deer	1 30		M. F		
dog	7			1. 2	AT ST
frog	<b>1</b>	30		<b>S</b> 🐳	30
horse		R. C			
ship	-	1	-		
truck			2	the state	

Alex Krizhevsky, "Learning Multiple Layers of Features from Tiny Images", Technical Report, 2009.

Test images and nearest neighbors



## Distance Metric to compare images

L1 distance: 
$$d_1(I_1, I_2) = \sum_p |I_1^p - I_2^p|$$



```
import numpy as np
```

```
class NearestNeighbor:
    def __init__(self):
        pass
```

def train(self, X, y):
 """ X is N x D where each row is an example. Y is 1-dimension of size N """
 # the nearest neighbor classifier simply remembers all the training data
 self.Xtr = X
 self.ytr = y

```
def predict(self, X):
    """ X is N x D where each row is an example we wish to predict label for """
    num_test = X.shape[0]
    # lets make sure that the output type matches the input type
    Ypred = np.zeros(num_test, dtype = self.ytr.dtype)
    # loop over all test rows
    for i in xrange(num_test):
        # find the nearest training image to the i'th test image
        # using the L1 distance (sum of absolute value differences)
        distances = np.sum(np.abs(self.Xtr - X[i,:]), axis = 1)
```

min\_index = np.argmin(distances) # get the index with smallest distance
Ypred[i] = self.ytr[min index] # predict the label of the nearest example

return Ypred

#### Nearest Neighbor classifier

```
import numpy as np
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#### Nearest Neighbor classifier

#### Memorize training data

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#### Nearest Neighbor classifier

For each test image: Find closest train image Predict label of nearest image import numpy as np

```
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Nearest Neighbor classifier

**Q:** With N examples, how fast are training and prediction?

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Nearest Neighbor classifier

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A: Train O(1), predict O(N)

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Nearest Neighbor classifier

**Q:** With N examples, how fast are training and prediction?

A: Train O(1), predict O(N)

This is bad: we want classifiers that are **fast** at prediction; **slow** for training is ok

## What does this look like?



## **K-Nearest Neighbors**

Instead of copying label from nearest neighbor, take **majority vote** from K closest points



K = 1

K = 3

K = 5

Hyperparameters

What is the best value of **k** to use? What is the best **distance** to use?

These are **hyperparameters**: choices about the algorithm that we set rather than learn

Hyperparameters

What is the best value of **k** to use? What is the best **distance** to use?

These are **hyperparameters**: choices about the algorithm that we set rather than learn

Very problem-dependent. Must try them all out and see what works best.

Idea #1: Choose hyperparameters that work best on the data

Your Dataset

Idea #1: Choose hyperparameters that work best on the data

**BAD**: K = 1 always works perfectly on training data

Your Dataset

Idea #1: Choose hyperparameters that work best on the data

**BAD**: K = 1 always works perfectly on training data

Your Dataset

Idea #2: Split data into train and test, choose hyperparameters that work best on test data

train test

Idea #1: Choose hyperparameters that work best on the data

**BAD**: K = 1 always works perfectly on training data

Your Dataset					
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train	test				

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**BAD**: K = 1 always works perfectly on training data

Your Dataset						
Idea #2: Split data into train and test, chooseBAD: No idea howhyperparameters that work best on test datawill perform on new						
train	test					
Idea #3: Split data into train, val, and test; choose Better! hyperparameters on val and evaluate on test						
train	test					

#### Your Dataset

## Idea #4: Cross-Validation: Split data into folds, try each fold as validation and average the results

fold 1	fold 2	fold 3	fold 4	fold 5	test
fold 1	fold 2	fold 3	fold 4	fold 5	test
fold 1	fold 2	fold 3	fold 4	fold 5	test

Useful for small datasets, but not used too frequently in deep learning

## What does this look like?



## What does this look like?



## K-Nearest Neighbors: Summary

In **Image classification** we start with a **training set** of images and labels, and must predict labels on the **test set** 

The **K-Nearest Neighbors** classifier predicts labels based on nearest training examples

Distance metric and K are **hyperparameters** 

Choose hyperparameters using the **validation set**; only run on the test set once at the very end!

## Linear Classification
## **Recall CIFAR10**



50,000 training images each image is 32x32x3

10,000 test images.

#### **Parametric Approach**



#### Parametric Approach: Linear Classifier







#### Example with an image with 4 pixels, and 3 classes (cat/dog/ship)



Stretch pixels into column

## Interpreting a Linear Classifier



f(x,W) = Wx + b

# What is this thing doing?

## Interpreting a Linear Classifier



$$f(x,W) = Wx + b$$

Example trained weights of a linear classifier trained on CIFAR-10:



# Interpreting a Linear Classifier



# f(x,W) = Wx + b



Array of **32x32x3** numbers (3072 numbers total)

Cat image by Nikita is licensed under CC-BY 2.0

## Hard cases for a linear classifier

Class 1: number of pixels > 0 odd

Class 2: number of pixels > 0 even Class 1: 1 <= L2 norm <= 2

Class 2: Everything else



Class 1: Three modes

#### Class 2: Everything else





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## **So far**: Defined a (linear) <u>score function</u> f(x,W) = Wx + b

Example class scores for 3 images for some W:

How can we tell whether this W is good or bad?

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34

79

airplane	-3.45	-0.51	3.42
automobile	-8.87	6.04	4.64
bird	0.09	5.31	2.65
cat	2.9	-4.22	5.1
deer	4.48	-4.19	2.64
dog	8.02	3.58	5.55
frog	3.78	4.49	-4.34
horse	1.06	-4.37	-1.5
ship	-0.36	-2.09	-4.79
truck	-0.72	-2.93	6.14

Suppose: 3 training examples, 3 classes. With some W the scores f(x, W) = Wx are:



A loss function tells how good our current classifier is

Given a dataset of examples

$$\{(x_i, y_i)\}_{i=1}^N$$

Where  $x_i$  is image and  $y_i$  is (integer) label

Loss over the dataset is a sum of loss over examples:

$$L = \frac{1}{N} \sum_{i} L_i(f(x_i, W), y_i)$$

cat

car

Suppose: 3 training examples, 3 classes. With some W the scores f(x, W) = Wx are:

#### **Previous losses:**

Given an example  $(x_i, y_i)$ where  $x_i$  is the image and where  $y_i$  is the (integer) label,

and using the shorthand for the scores vector:  $s = f(x_i, W)$ 

Least-squares regression has the form

$$L_i = \sum_i ||s_i - y_i||^2$$

The SVM loss has the form:

$$L_{i} = \sum_{j \neq y_{i}} \begin{cases} 0 & \text{if } s_{y_{i}} \geq s_{j} + 1 \\ s_{j} - s_{y_{i}} + 1 & \text{otherwise} \end{cases}$$
$$= \sum_{j \neq y_{i}} \max(0, s_{j} - s_{y_{i}} + 1)$$

Credit: Fei-Fei Li & Justin Johnson & Serena Yeung

cat

car



# cat**3.2**car5.1frog-1.7



scores = unnormalized log probabilities of the classes.

$$s=f(x_i;W)$$





#### scores = unnormalized log probabilities of the classes.

$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$$

where

$$s=f(x_i;W)$$

cat**3.2**car5.1frog-1.7



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where

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cat**3.2**car5.1frog-1.7

#### Softmax function



3.2

5.1

-1.7

cat

car

frog

#### scores = unnormalized log probabilities of the classes.

where

$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$$

$$s=f(x_i;W)$$

Want to maximize the log likelihood, or (for a loss function) to minimize the negative log likelihood of the correct class:

$$L_i = -\log P(Y=y_i|X=x_i)$$



3.2

5.1

cat

car

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frog -1.7 in summary:  $L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$ 



$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$

cat **3.2** car 5.1 frog -1.7

#### unnormalized log probabilities



$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$

unnormalized probabilities



unnormalized log probabilities



unnormalized log probabilities

probabilities





















#### L2 Regularization (Weight Decay)

$$x = [1, 1, 1, 1]$$
  $R(W) = \sum_k \sum_l W_{k,l}^2$ 

$$w_1 = [1, 0, 0, 0] \ w_2 = [0.25, 0.25, 0.25, 0.25]$$

$$w_1^T x = w_2^T x = 1$$

# Recap

- We have some dataset of (x,y)
- We have a **score function**:
- We have a loss function:

$$s = f(x;W) \stackrel{ ext{e.g.}}{=} Wx$$



# Optimization


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Walking man image is CC0 1.0 public domain

#### Strategy: Follow the slope



#### Strategy: Follow the slope

In 1-dimension, the derivative of a function:

$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

In multiple dimensions, the **gradient** is the vector of (partial derivatives) along each dimension

The slope in any direction is the **dot product** of the direction with the gradient The direction of steepest descent is the **negative gradient** 

current W:	
[0.34,	
-1.11,	
0.78,	
0.12,	
0.55,	
2.81,	
-3.1,	
-1.5,	
0.33,]	
loss 1.25347	

#### gradient dW:



current W:	W + h (first dim):	gradient dW:
[0.34, -1 11	[0.34 + <b>0.0001</b> , _1 11	[?,
0.78,	0.78,	?,
0.12, 0.55,	0.12, 0.55,	?, ?.
2.81,	2.81,	?,
-5.1, -1.5,	-3.1, -1.5,	?, ?,
0.33,…] loss 1.25347	0.33,…] loss 1.25322	?,]

current W:	W + h (first dim):	gradient dW:
[0.34, -1.11, 0.78, 0.12, 0.55, 2.81, -3.1, -1.5, 0.33,] <b>Ioss 1.25347</b>	[0.34 + <b>0.0001</b> , -1.11, 0.78, 0.12, 0.55, 2.81, -3.1, -1.5, 0.33,] <b>Ioss 1.25322</b>	$[-2.5, ?, ?, ?, ?, ?, ?, ?, ?,]$ $(1.25322 - 1.25347)/0.0001 = -2.5$ $\frac{df(x)}{dx} = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$ ?, ?,]

current W:	W + h (second dim):
[0.34,	[0.34,
-1.11,	-1.11 + <b>0.0001</b> ,
0.78,	0.78,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25353

gradient dW: [-2.5, ?, ?, ?, ?, ?, ?, ?, ?,...]

current W:	W + h (second dim):
[0.34,	[0.34,
-1.11,	-1.11 + <b>0.0001</b> ,
0.78,	0.78,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25353



current W:	W + h (third dim):
[0.34,	[0.34,
-1.11,	-1.11,
0.78,	0.78 + <b>0.0001</b> ,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25347

gradient dW:

current W:	<b>W + h</b> (third di
[0.34,	[0.34,
-1.11,	-1.11,
0.78,	0.78 + <b>0.0001</b> ,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25347

dim):



## This is silly. The loss is just a function of W:

$$egin{aligned} L &= rac{1}{N} \sum_{i=1}^N L_i + \sum_k W_k^2 \ L_i &= -\log(rac{e^{sy_i}}{\sum_j e^{s_j}}) \ s &= f(x;W) = Wx \end{aligned}$$

want  $\nabla_W L$ 

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want  $\nabla_W L$ 

# Use calculus to compute an analytic gradient



#### Credit: Fei-Fei Li & Justin Johnson & Serena Yeung

[0.34, -1.11, 0.78, 0.12, 0.55, 2.81, -3.1, -1.5, 0.33,...] loss 1.25347

#### current W:



#### gradient dW:

### In summary:

- Numerical gradient: approximate, slow, easy to write
- Analytic gradient: exact, fast, error-prone

#### =>

In practice: Always use analytic gradient, but check implementation with numerical gradient. This is called a gradient check.

# **Gradient Descent**

```
# Vanilla Gradient Descent
while True:
    weights_grad = evaluate_gradient(loss_fun, data, weights)
    weights += - step_size * weights_grad # perform parameter update
```



#### Stochastic Gradient Descent (SGD)

$$L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(x_i, y_i, W) + \lambda R(W)$$
$$\nabla_W L(W) = \frac{1}{N} \sum_{i=1}^{N} \nabla_W L_i(x_i, y_i, W) + \lambda \nabla_W R(W)$$

Full sum expensive when N is large!

Approximate sum using a **minibatch** of examples 32 / 64 / 128 common

```
# Vanilla Minibatch Gradient Descent
while True:
    data_batch = sample_training_data(data, 256) # sample 256 examples
    weights_grad = evaluate_gradient(loss_fun, data_batch, weights)
    weights += - step_size * weights_grad # perform parameter update
```

### **Interactive Web Demo**



http://vision.stanford.edu/teaching/cs231n-demos/linear-classify/

# Image features

#### Image Features



#### **Example: Color Histogram**



## Example: Histogram of Oriented Gradients (HoG)



Divide image into 8x8 pixel regions Within each region quantize edge direction into 9 bins

Lowe, "Object recognition from local scale-invariant features", ICCV 1999 Dalal and Triggs, "Histograms of oriented gradients for human detection," CVPR 2005

## Example: Bag of Words

#### Step 1: Build codebook



### Image Features: Motivation

 $f(x, y) = (r(x, y), \theta(x, y))$ 



Cannot separate red and blue points with linear classifier After applying feature transform, points can be separated by linear classifier

r

θ

### Image features vs ConvNets





#### Neural networks

# (**Before**) Linear score function: f = Wx

(**Before**) Linear score function: (**Now**) 2-layer Neural Network

$$egin{aligned} f &= Wx \ f &= W_2 \max(0, W_1 x) \end{aligned}$$

### Neural networks

(Before) Linear score function: f = Wx(Now) 2-layer Neural Network  $f = W_2 \max(0, W_1x)$ 



## Neural networks



(Before) Linear score function:

(**Now**) 2-layer Neural Network or 3-layer Neural Network

$$f = Wx$$

$$f=W_2\max(0,W_1x)$$

$$f=W_3\max(0,W_2\max(0,W_1x))$$

## Next time:

Backpropagation