

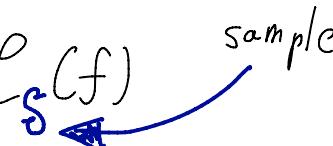
Boosting Decision Trees Neural Networks

Notes are available
online (see Piazza)

Boosting, Decision Trees, Neural Networks

- * Revisit surrogate loss : exp-loss
- * Boosting and exp-loss connected
- * Decision trees, exp-loss, and boosting connected
- * From boosted classifiers to Neural Networks

Notes:

- * old-new view that is not covered in one book or a few papers
- * Intuitive, simple, "proof-free" (almost)
- * Focus on empirical loss $L_S(f)$  sample

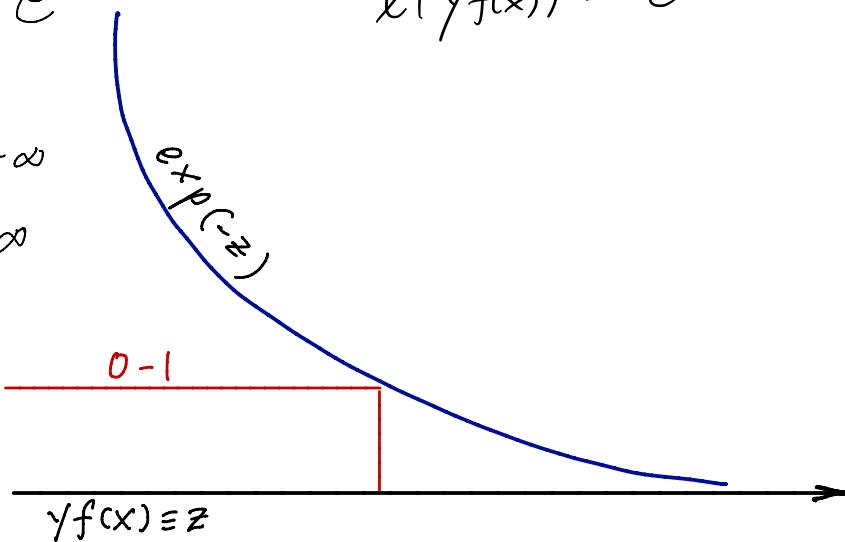
Exponential Loss

$f: \mathcal{X} \rightarrow \mathbb{R}$ $|f(x)|$ - confidence in prediction

$\text{sign}(f(x))$ - predicted outcome

$$\mathcal{L}_S^{\exp}(f) \equiv \frac{1}{|S|} \sum_{i=1}^{|S|} e^{-y_i f(x_i)} \quad l(y f(x)) = e^{-y f(x)}$$

- * grows fast ↗ as $z \rightarrow -\infty$
- * gets small ↓ as $z \rightarrow \infty$
- * "nice" properties



Predictors which can abstain

$$f(x) \in \{-1, 0, +1\}$$

no negative

IDK

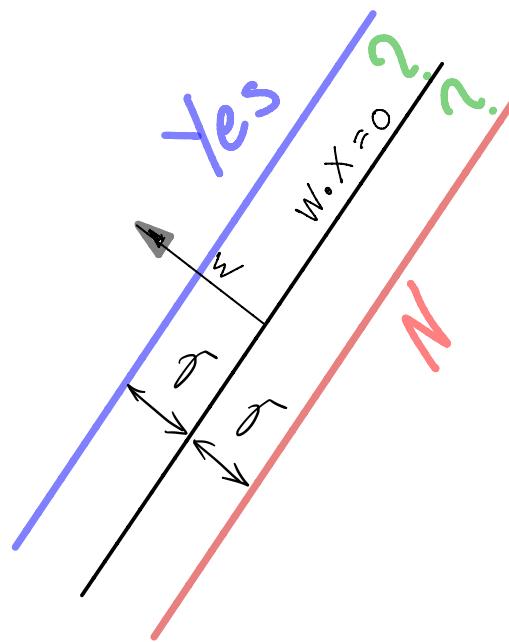
IDC

yes positive

$$f: \mathcal{X} \rightarrow \{-1, 0, +1\}$$

Example $x \in \mathbb{R}^d$ $w \in \mathbb{R}^d$

$$f(x) = \begin{cases} -1 & w \cdot x < -\delta \\ 0 & |w \cdot x| \leq \delta \\ +1 & w \cdot x > \delta \end{cases}$$



Calibrating Predictors

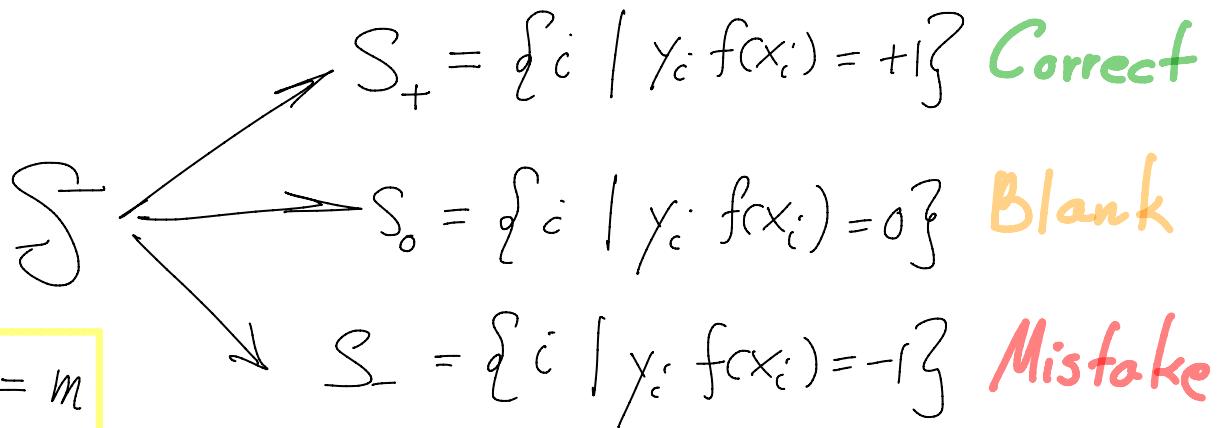
- * Assume that $f: \mathcal{X} \rightarrow \{-1, 0, +1\}$ is given us
- * Need to find α such that $\mathcal{L}_g^{\text{exp}}(\alpha f(x))$ is minimized Can use α_+, α_-
- * Process called calibration / rescaling / reweighting

$$\min_{\alpha \in \mathbb{R}} \frac{1}{|S|} \sum_{i=1}^{|S|} e^{-y_i (\alpha f(x_i))}$$

$\begin{matrix} \parallel \\ x_i \in \mathbb{R} \end{matrix}$

Search for α

* Exploit the fact that $f: \mathcal{X} \rightarrow \{-1, 0, +1\}$



$$\mathcal{L}_S^{\text{exp}}(f) = \frac{1}{m} \left(\sum_{i \in S_+} e^{-\alpha} + \sum_{i \in S_-} e^{+\alpha} + \sum_{i \in S_0} e^0 \right)$$

Are we in a better shape?

Closed form solution

Define $M_+ = \frac{|S_+|}{m}$ $M_- = \frac{|S_-|}{m}$ $M_0 = \frac{|S_0|}{m}$

↓ ↓ ↓

fraction correct fraction mistake what do they care

$$\mathcal{L}_S^{(\alpha)} = M_+ e^{-\alpha} + M_- e^{\alpha} + M_0$$

$\mathcal{L}(\alpha f)$ is convex in α **Yeh! Yey! Ci! Po!**

$$0 = \frac{d\mathcal{L}}{d\alpha} = -M_+ e^{-\alpha} + M_- e^{\alpha}$$



$$\alpha^* = \frac{1}{2} \log \left(\frac{M_+}{M_-} \right)$$

Nobody is perfect assumption: $M_+ > 0$ $M_- > 0$

Further Insights

* If $\mu_+ = \mu_-$ then $\alpha = 0$ \rightarrow $f(x)$ is no better than a random predictor

* If $\mu_- > \mu_+$ then $\alpha < 0$ \rightarrow Negate the prediction of f

Total Loss of $\alpha f(x)$:

$$\begin{aligned} L_S^{\text{exp}}(\alpha f) &= \mu_+ e^{-\frac{1}{2} \log\left(\frac{\mu_+}{\mu_-}\right)} + \mu_- e^{\frac{1}{2} \log\left(\frac{\mu_+}{\mu_-}\right)} + \mu_0 \\ &= \mu_+ \sqrt{\frac{\mu_-}{\mu_+}} + \mu_- \sqrt{\frac{\mu_+}{\mu_-}} + \mu_0 \quad e^{\frac{1}{2} \log \alpha} = e^{\log \sqrt{\alpha}} = \sqrt{\alpha} \\ &= 2\sqrt{\mu_+\mu_-} + (1 - (\mu_+ + \mu_-)) \end{aligned}$$

Total loss of αf

$$\begin{aligned} \mathcal{L}_S^{\text{exp}}(\alpha f) &= \mu_+ e^{-\frac{1}{2} \log\left(\frac{\mu_+}{\mu_-}\right)} + \mu_- e^{\frac{1}{2} \log\left(\frac{\mu_+}{\mu_-}\right)} + \mu_0 \\ &= \mu_+ \sqrt{\frac{\mu_-}{\mu_+}} + \mu_- \sqrt{\frac{\mu_+}{\mu_-}} + \mu_0 \quad \text{green arrows from } e^{\frac{1}{2} \log \alpha} = e^{\log \sqrt{\alpha}} = \sqrt{\alpha} \\ &= 2\sqrt{\mu_+\mu_-} + (1 - (\mu_+ + \mu_-)) \quad \text{blue arrow from } \mu_+ + \mu_- + \mu_0 = 1 \\ &\quad \text{green arrow from } \text{No normalization} \Rightarrow \mu - \mu_+ - \mu_- \end{aligned}$$

Post Calibration Loss

$$\begin{aligned}\mathcal{L}(\alpha f) &= 2\sqrt{\mu_+ \mu_-} + (1 - (\mu_+ + \mu_-)) \\ &= 1 - (\mu_+ - 2\sqrt{\mu^+} \sqrt{\mu^-} + \mu^-) \xrightarrow{\text{(green arrow)}} (\sqrt{\mu^-})^2 \\ &= 1 - (\sqrt{\mu^+} - \sqrt{\mu^-})^2\end{aligned}$$

$\Delta \text{Loss} \equiv \text{loss before using } f \text{ and after}$

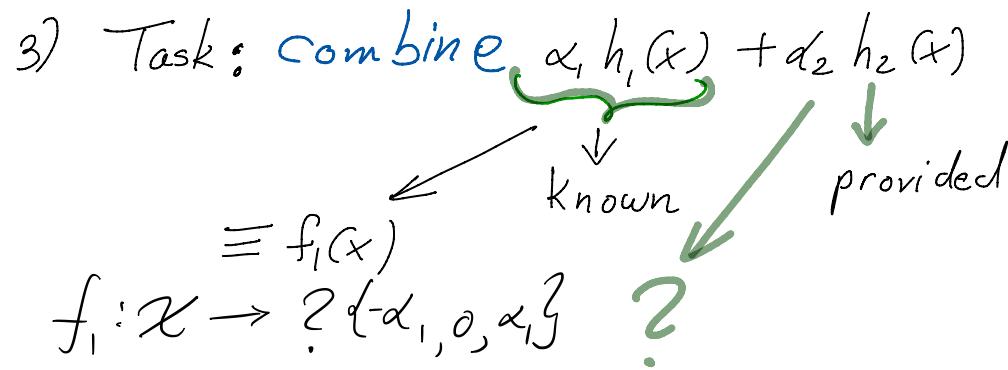
$$\Delta \mathcal{L} = \mathcal{L}(0) - \mathcal{L}(\alpha f) = (\sqrt{\mu^+} - \sqrt{\mu^-})^2$$



Reduction in loss has a closed form

Neat!

Beyond a single predictor

- 1) Assume we calibrated $\alpha_1, h_1(x)$
- 2) Provided with a second predictor $h_2(x)$
- 3) Task: combine $\alpha_1 h_1(x) + \alpha_2 h_2(x) \equiv f_2(x)$

 $f_1: \mathcal{X} \rightarrow ? \{\alpha_1, 0, \alpha_1\}$?
- 4) General case: given $f_t(x) = \sum_{i=1}^t \alpha_i h_i(x)$ & $h_{t+1}(x)$
find $\alpha_{t+1} \Rightarrow f_{t+1}(x) = \sum_{i=1}^{t+1} \alpha_i h_i(x)$
 $= f_t(x) + \alpha_{t+1} h_{t+1}(x)$

Inductive Calibration

As before define:

$$S_+^{t+1} = \{i \mid h_{t+1}(x_i) = y_i\}$$

$$S_-^{t+1} = \{i \mid h_{t+1}(x_i) = -y_i\}$$

$$S_0^{t+1} = \{i \mid h_{t+1}(x_i) = 0\}$$

Generalize: $M_+ = \frac{1}{m} \sum_{i \in S_+} e^{-y_i f_t(x_i)}$

$$M_0 = \frac{1}{m} \sum_{i \in S_0} e^{-y_i f_t(x_i)}$$

$$M_- = \frac{1}{m} \sum_{i \in S_-} e^{-y_i f_t(x_i)}$$

$$\mathcal{L}(f_{t+1}(x)) = \mu_+ e^{-\alpha_{t+1}^+} + \mu_- e^{+\alpha_{t+1}^-} + \mu_0$$

$$f_{t+1}(\cdot) = f_t(\cdot) + \alpha_{t+1} h_{t+1}(\cdot)$$

Solution has the same form !

$$\Delta \mathcal{L}_{t+1} \equiv \mathcal{L}(f_t) - \mathcal{L}(f_{t+1}) = (\sqrt{\mu^+} - \sqrt{\mu^-})^2$$

$$(\mu_+ + \mu_- + \mu_0) - (2 \sqrt{\mu^+ \mu^-} + \mu_0)$$

Importance Weights

* Given $f_t(x)$ define :

$$q_i^t \sim e^{-y_i f_t(x_i)}$$

importance weight:
how "difficult" example (x_i, y_i) is

* Often $\{q_i^t\}$ is normalized $\sum_{i=1}^m q_i^t = 1$

* Does not change analysis and algorithm

* Simply implies $M_+^t + M_-^t + M_0^t = 1$

Which can be obtained by simple scaling

Detour - SGD w/ Weights

$$L(\omega) = \sum_{i=1}^m q_i f_i(\omega) \quad \text{s.t.} \quad \sum q_i = 1; \quad q_i > 0$$

Reduction: define $\tilde{f}_i(\omega) = q_i f_i(\omega)$
use SGD on: $\frac{1}{m} \sum_{i=1}^m \tilde{f}_i(\omega)$

OR

Importance Sampling: batch size b

Sample b times such that example i is chosen w/ probability q_i

Boosting

Initialize: $\forall i: q_i^0 = \frac{1}{m} \quad f_0(x) \equiv 0$

Equivalent
to previous
lecture

For $t=1, \dots, T$:

Find $h_t(x)$ s.t. $\sum_i q_i^t y_i h_t(x_i)$ is large

Partition: $S \mapsto S_+^t, S_-^t, S_0^t$

Calculate: $\alpha_t = \frac{1}{2} \log \left(\frac{M_+^t}{M_-^t} \right)$

Update:

1. $f_{t+1}(x) = f_t(x) + \alpha_t h_t(x)$

2. $q_i^{t+1} = q_i^t e^{-y_i \alpha_t h_t(x_i)}$

$$q_i^{t+1} = \begin{cases} q_i^t & h_t(x_i) = 0 \\ q_i^t e^{-\alpha} & h_t(x_i) = y_i \\ q_i^t e^{\alpha} & h_t(x_i) \neq y_i \end{cases}$$

Generalization

Instead of $h_t: \mathcal{X} \rightarrow \{-1, 0, +1\}$ can use

$$h_t(x) \in [-1, +1]$$



Limit the power
of base predictors

where as before

$$|h_t(x)| \text{ confidence}$$

$$\text{sign}(h_t(x)) \text{ predicted outcome}$$

$$S_+^t \triangleq \{i \mid y_i \cdot h_t(x_i) > 0\}$$

$$S_0^t \triangleq \{i \mid y_i \cdot h_t(x_i) = 0\}$$

$$S_-^t \triangleq \{i \mid y_i \cdot h_t(x_i) < 0\}$$

No further changes
are required

Generalization II

Slide Can Be Skipped

Can replace exp-loss with log-loss (logistic-loss)

$$\mathcal{L}_S^{\text{log}}(f) = \frac{1}{m} \sum_{i=1}^m \log\left(1 + e^{-y_i f(x_i)}\right)$$

$$q_i^{t+1} \sim e^{-y_i f_{t+1}(x_i)} \sim q_i^t e^{-y_i \alpha_t h_t(x_i)}$$

$$q_i^{t+1} = \frac{1}{1 + \exp\left(y_i f_{t+1}(x_i)\right)} = \frac{q_i^t}{q_i^t + (1 - q_i^t) e^{y_i \alpha_t h_t(x_i)}}$$

Alternatively: $z_i^{t+1} \triangleq y_i f_{t+1}(x_i) = z_i^t + y_i \alpha_t h_t(x_i)$

$$q_i^{t+1} = \frac{e^{-z_i^{t+1}}}{Z}$$

Exp
Loss

$$q_i^{t+1} = \left(1 + \exp(z_i^{t+1})\right)^{-1}$$

Log
Loss

Slide Can Be Skipped

Boosting

Initialize: $\forall i \quad q_i^1 = \frac{1}{m} \quad f_0(x) \equiv 0$

For $t=1, \dots, T$:

$$\frac{1}{2}$$

Log-loss
Confidence-rated
W.H.

Find $h_t(x)$ s.t. $\sum_i q_i^t y_i h_t(x_i)$ is large

Partition: $S \mapsto S_+^t, S_-^t, S_0^t$

Calculate: $\alpha_t = \frac{1}{2} \log \left(\frac{M_+^t}{M_-^t} \right)$

Update:

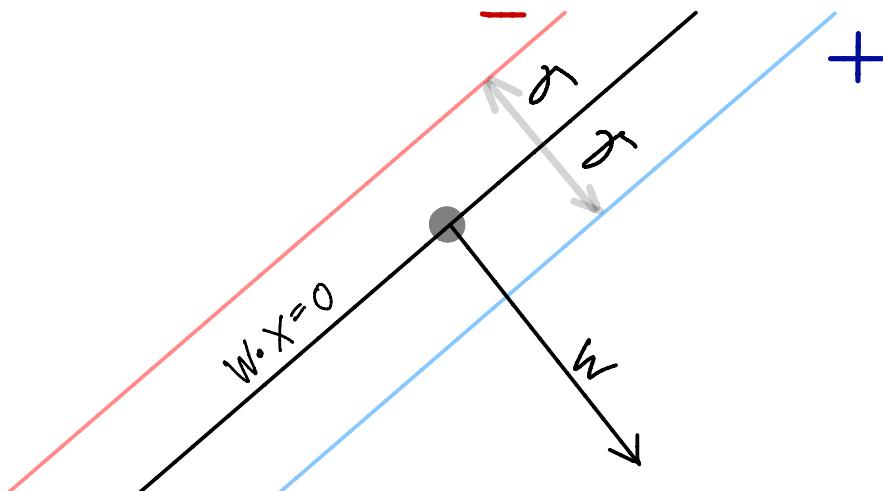
$$f_{t+1}(x) = f_t(x) + \alpha_t h_t(x)$$

$$q_i^{t+1} = q_i^t e^{-y_i \alpha_t h_t(x_i)}$$

$$q_i^{t+1} = q_i^t (q_i^t + (1 - q_i^t) e^{y_i \alpha_t h_t(x_i)})^{-1}$$

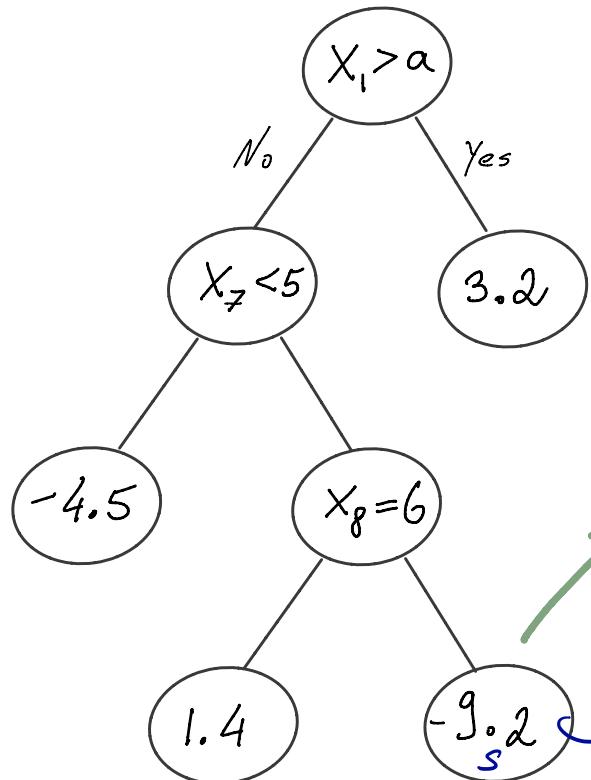
Detour - Linear Predictors w/ Absfation

$$f(x) = w^T x \Rightarrow \tilde{f}(x) \text{ w/ abstfation \& continuous}$$



$$w^T x = z \quad \tilde{f}(z) = \text{sign}(z) [|z| - \tau]_+ = \begin{cases} z - \tau & z > \tau \\ 0 & |z| \leq \tau \\ z + \tau & z < -\tau \end{cases}$$

Decision Trees



At each leaf there exists
a confidence-rated predictor

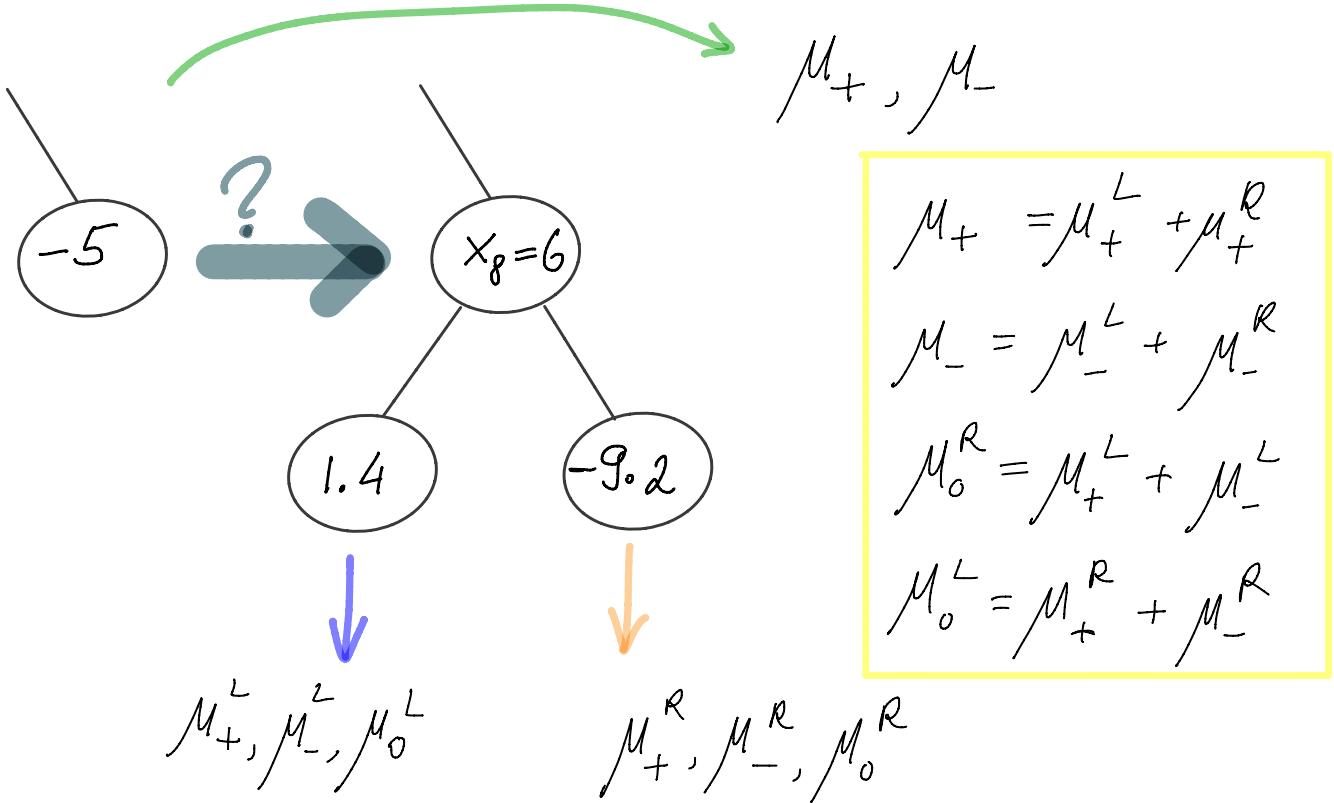
$$h_t(x) = \begin{cases} -9.2 & \text{if } x_1 \leq a, x_7 \geq 5 \wedge x_8 = 6 \\ 0 & \text{o.w.} \end{cases}$$

$\{i : y_i = +1\} = \mu_s^+$

$\{i : y_i = -1\} = \mu_s^-$

$$\frac{1}{2} \log \left(\frac{\mu_s^+}{\mu_s^-} \right)$$

Growing Decision Trees



Improvement in surrogate loss?

Growing ~~Pain~~ Gain

Assume $\mu_+ + \mu_- = 1$ for parent node (normalization)

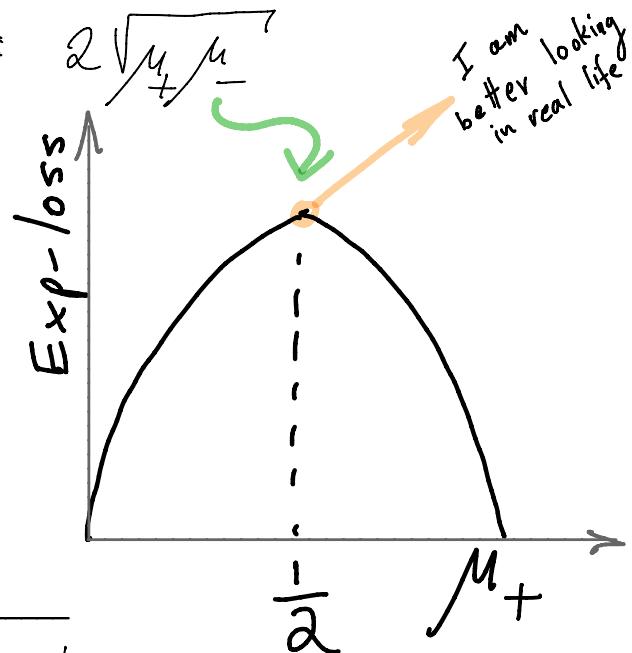
Exp-loss for parent node : $2\sqrt{\mu_+ \mu_-}$

Exp-loss for children :

$$2(\sqrt{\mu_+^L \mu_-^L} + \sqrt{\mu_+^R \mu_-^R})$$

Gain ~

$$\sqrt{(\mu_+^R \mu_+^L)(\mu_-^R \mu_-^L)} - \sqrt{\mu_+^R \mu_-^R} - \sqrt{\mu_+^L \mu_-^L}$$



Towards Neural Networks

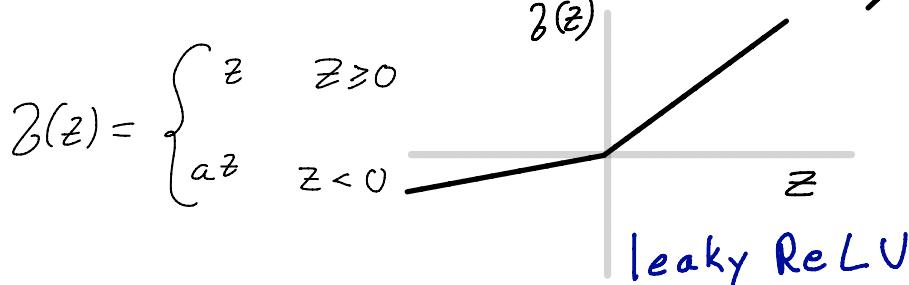
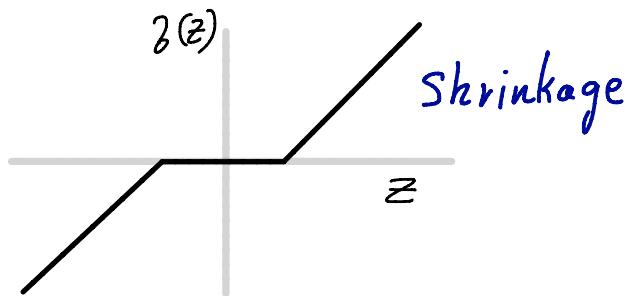
$$f_t(x) = \sum_{i=1}^t \alpha_i h_i(x) \implies \text{"Strong" hypothesis}$$

Suppose each $h_t(x)$ is of the form:

$$\mathcal{Z}(w^t \cdot x) \quad \text{where } \mathcal{Z}: \mathbb{R} \rightarrow \mathbb{R} \text{ is non-linear}$$

Examples:

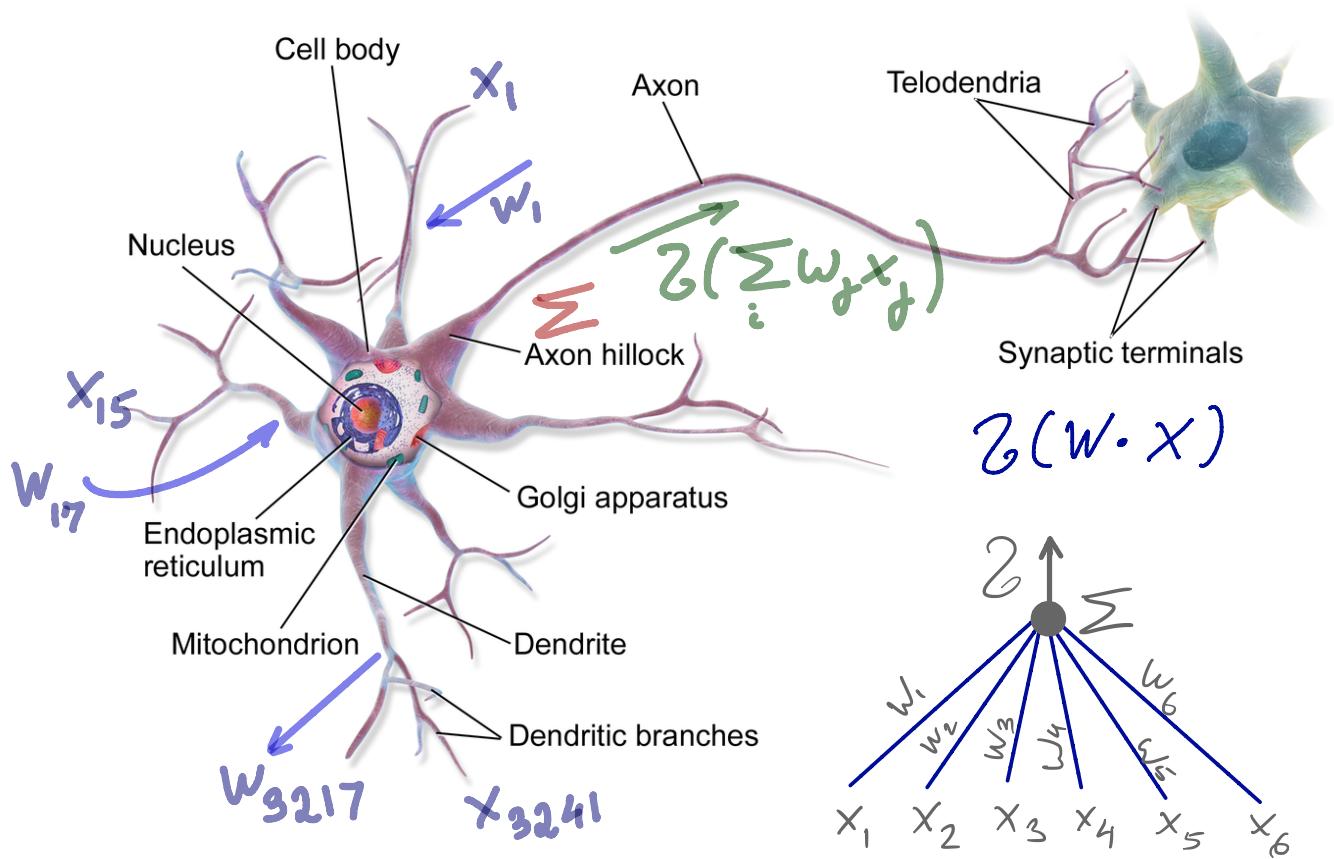
$$\mathcal{Z}(z) = \begin{cases} z - \tau & z > \tau \\ 0 & |z| \leq \tau \\ z + \tau & z < -\tau \end{cases}$$



$$\mathcal{Z}(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

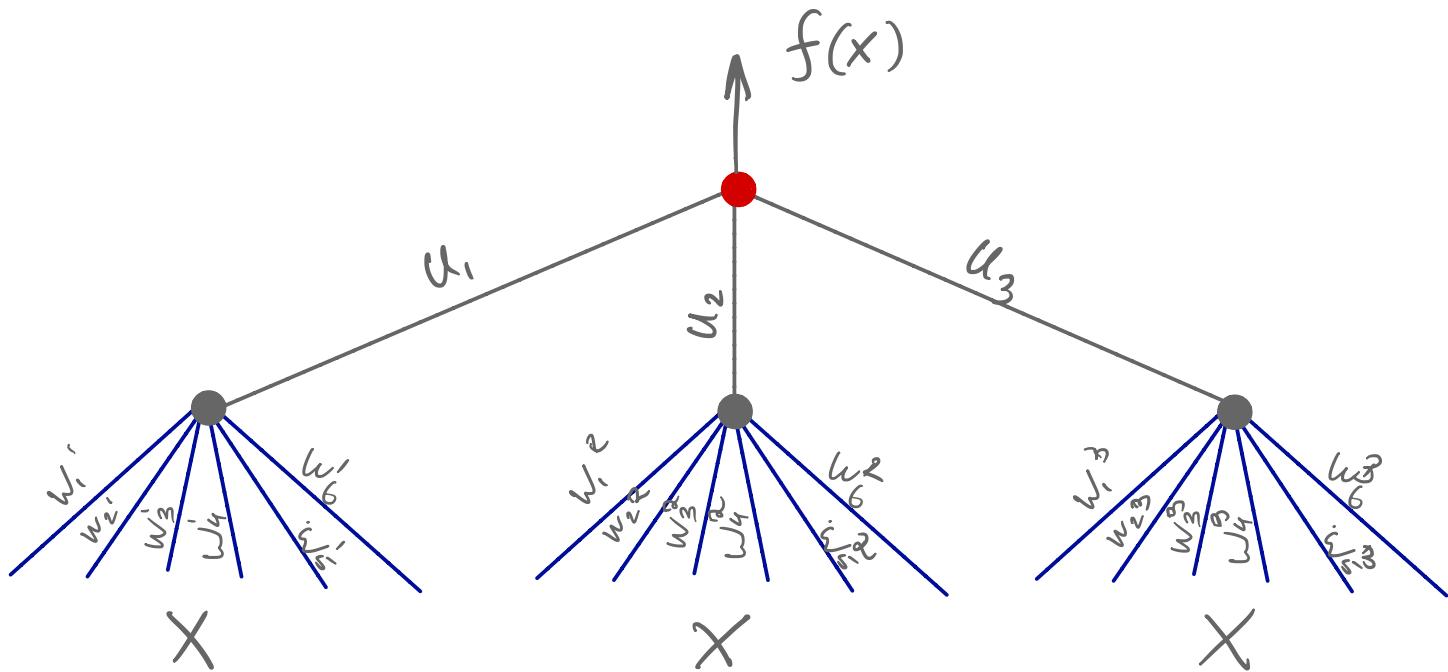
Sigmoid

"Neuron"



Multi layer perceptron (NN)

$$f(x) = \mathcal{Z}\left(u_1 \mathcal{Z}(w^1 \cdot x) + u_2 \mathcal{Z}(w^2 \cdot x) + u_3 \mathcal{Z}(w^3 \cdot x)\right)$$



- You are likely to have many questions at this point...
- A few will be addressed @ IML
- Many will be left unanswered
- Since we don't know ... the answer